Geometry \& Topology
Volume 8 (2004) $877\{924$
Published: 5J une 2004


# Global rigidity of solvable group actions on $\mathrm{S}^{1}$ 

Lizzie Bur sl em<br>Amie Wil kinson<br>Department of Mathematics, University of Michigan 2074 East Hall, Ann Arbor, MI 48109-1109 USA and<br>Department of Mathematics, Northwestern University 2033 Sheridan Road, Evanston, IL 60208-2730 USA<br>Email: bursl en@unch. edu, wi l ki nso@math. northwestern. edu


#### Abstract

In this paper we nd all solvable subgroups of $\mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$ and classify their actions. We also investigate the $\mathrm{C}^{r}$ local rigidity of actions of the solvable Baumslag\{Solitar groups on the circle. The investigation leads to two novel phenomena in the study of in nite group actions on compact manifolds. We exhibit a nitely generated group $\Gamma$ and a manifold $M$ such that: $\Gamma$ has exactly countably in nitely many e ective real-analytic actions on M , up to conjugacy in $\mathrm{Di}^{\text {! }}$ (M); every e ective, real analytic action of $\Gamma$ on $M$ is $C^{r}$ locally rigid, for some $r$ 3, and for every such $r$, there are in nitely many nonconjugate, e ective real-analytic actions of $\Gamma$ on $M$ that are $\mathrm{C}^{r}$ locally rigid, but not $\mathrm{C}^{r-1}$ locally rigid.


AMS Classi cation numbers Primary: 58E40, 22F 05
Secondary: 20F16, 57M60
Keywords: Group action, solvable group, rigidity, Di ! $\left(\mathrm{S}^{1}\right)$

| Proposed: Robion Kirby | Received: 26J anuary 2004 |
| :--- | ---: |
| Seconded: Martin Bridson, Steven Ferry | Accepted: 28 May 2004 |

c Geometry \& Topology Publications

## Introduction

This paper describes two novel phenomena in the study of in nitegroup actions on compact manifolds. We exhibit a nitely generated group $\Gamma$ and a manifold $M$ such that:
$\Gamma$ has exactly countably in nitely many e ective real-analytic actions on $M$, up to conjugacy in $\mathrm{Di}!(\mathrm{M})$;
every e ective, real analytic action of $\Gamma$ on $M$ is $C^{r}$ locally rigid, for some $r$ 3, and for every such $r$, there are in nitely many nonconjugate, e ective real-analytic actions of $\Gamma$ on M that are $\mathrm{C}^{r}$ locally rigid, but not $\mathrm{C}^{r-1}$ locally rigid.
In the cases we know of where an in nite group $\Gamma$ has exactly countably many smooth e ective actions on a manifold $M$, that countable number is nite, and indeed usually 0 . While many actions have been shown to to be $\mathrm{C}^{r}$ locally rigid, in the cases where a precise cuto in rigidity has been established, it occurs between $r=1$ and $r=2$. For a survey of some of the recent results on smooth group actions, see the paper of Labourie [9].
Our manifold $M$ is the circle $S^{1}$ and our group $\Gamma$ is the solvable Baumslag\{ Solitar group:

$$
B S(1 ; n)=h a ; b ; j a b a^{-1}=b^{\prime} i ;
$$

where $\mathrm{n} \quad 2$.
As a natural by-product of our techniques, we obtain a classi cation of all solvable subgroups of $\mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$. We show that every such subgroup $G$ is either conjugate in $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ to a subgroup of a rami ed a ne group $\mathrm{A}{ }^{\mathbf{s}}(\mathbb{R})$, or, for some $m 2 \mathbb{Z}$, the group $G^{m}:=f g^{m}: g 2 G g$ is abdian. The rami ed a ne groups are de ned and their properties discussed in Section 2.2. Each rami ed a ne group is abstractly isomorphic to a direct product $A+(\mathbb{R}) \quad H$, where $A+(\mathbb{R})$ is the group of orientation-preserving a netransformations of $\mathbb{R}$, and H is a subgroup of a nite dihedral group.

## 1 Statement of results

### 1.1 Notation and preliminary de nitions

In places, we shall use two di erent analytic coordinatizations of the circle $\mathrm{S}^{1}$. To denote an element of the additive group, $\mathbb{R}=\mathbb{Z}$, we will use $u$, and for an
element of thereal projective line $\mathbb{R}^{1}{ }^{1}$, we will use $x$. These coordinate systems are identi ed by: $u 2 \mathbb{R}=\mathbb{Z} \square \quad x=\tan (u) 2 \mathbb{R} P^{1}$. When we are not specifying a coordinate system, we will use $p$ or $q$ to denote an element of $S^{1}$. We $x$ an orientation on $\mathrm{S}^{1}$ and use $\backslash<$ " to denote the counterclockwise cyclic ordering on $\mathrm{S}^{1}$.
If $G$ is a group, then we denote by $R^{r}(G)$ the set of all representations 0 : $G$ !
$\mathrm{Di}{ }^{r}\left(\mathrm{~S}^{1}\right)$, and we denote by $\mathrm{R}_{+}{ }_{+}(\mathrm{G})$ the set of all orientation-preserving representations in $\mathrm{R}^{\mathrm{r}}(\mathrm{G})$. Two representations 1; $22 \mathrm{R}^{\mathrm{r}}(\mathrm{G})$ are conjugate (in $\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$ ) if there exists $\mathrm{h} 2 \mathrm{Di}^{r}\left(\mathrm{~S}^{1}\right)$ such that, for every y 2 G , $h_{1}(\gamma) h^{-1}={ }_{2}(\gamma)$.
We use the standard $C^{k}$ topology on representations of a nitely-generated group into $\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$, $\mathrm{r} 2 \mathrm{f} 1 ;::: ; 1 ;!\mathrm{g}$ and $\mathrm{k} \quad \mathrm{r}$. If $\Gamma$ is a nitely-generated group, then the $C^{k}$ \{open sets in $R^{r}(\Gamma)$ take generators in a xed generating set for $\Gamma$ into $C^{k}$ \{open sets. A representation o $2 R^{r}(\Gamma)$ is ( $C^{r}$ ) locally rigid if there exists a $C^{1}$ neighborhood $U$ of 0 in $R^{r}(\Gamma)$ such that every $2 U$ is conjugate in $\mathrm{Di}^{r}\left(\mathrm{~S}^{1}\right)$ to 0 . Finally, we say that $\Gamma$ is globally rigid in $\mathrm{Di}^{r}\left(\mathrm{~S}^{1}\right)$ if there exists a countable set of locally rigid representations in $R^{r}(\Gamma)$ such that every faithful representation in $\mathrm{R}^{\mathrm{r}}(\Gamma)$ is conjugate to an element of this set.
To construct the subgroups and representations in this paper, we use a proce dure we call real rami ed lifting.

De nition A real analytic surjection : $S^{1}!S^{1}$ is called a rami ed covering map over p $2 S^{1}$ if the restriction of to ${ }^{-1}\left(\mathrm{~S}^{1} \mathrm{nf} \mathrm{pg}\right)$ is a regular analytic covering map onto $S^{1} n f p g$ of degree d 1 . The degree of of is de ned to be this integer $d$.

Examples and properties of rami ed covering maps and rami ed lifts are described in Section 2.
Let : $S^{1}$ ! $S^{1}$ be a rami ed covering map over p $2 S^{1}$, and let $f: S^{1}!S^{1}$ be a real analytic di eomorphism that xes $p$. We say that $\mathrm{f}^{\wedge} 2 \mathrm{Di}{ }^{!}\left(S^{1}\right)$ is a \{rami ed lift of $f$ if the following diagram commutes:


More generally, let : 「! $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ be a representation with global xed point p . A representation $\uparrow$. $!$ ! $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ is a \{rami ed lift of if $(\gamma)$ is
a \{rami ed lift ( $\gamma$ ), for every y 2 Г. We will show in Proposition 2.3 that a representation can have more than one \{rami ed lift.
For $G$ a subgroup of $\mathrm{Di}{ }^{!}\left(S^{1}\right)$ with a global xed point $p$, we de ne $\hat{G}$, the \{rami ed lift of G to be the collection of all \{rami ed lifts of elements of G. By Proposition 2.3 and Propostion 2.8, $\widehat{G}$ is a subgroup of $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$, abstractly isomorphic to an H \{extension of $\mathrm{G}_{+}$, where $\mathrm{G}_{+}=\mathrm{Di} \stackrel{\vdots}{+}\left(\mathrm{S}^{1}\right) \backslash \mathrm{G}$, and H is a subgroup of a dihedral group determined by .

### 1.2 Rigidity of solvable Baumslag\{Solitar groups

In real projective coordinates on $\mathbb{R P}^{1}$, the standard representation ${ }_{n}$ of $B S(1 ; n)$ into Di ${ }_{+}^{!}\left(S^{1}\right)$ takes the generators $a$ and $b$ to the a ne maps

$$
x \eta n x ; \quad \text { and } \quad x ワ x+1
$$

This representation has a global xed point $12 \mathbb{R} P^{1}$. Our rst result states that $\mathrm{BS}(1 ; n)$ is globally rigid in $\mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$ :

Theorem 1.1 For each n 2, there are exactly countably in nitely many faithful representations of $\mathrm{BS}(1 ; n)$ into $\mathrm{Di}!\left(\mathrm{S}^{1}\right)$, up to conjugacy in Di! $\left(\mathrm{S}^{1}\right)$. Each conjugacy class contains a $\left\{\right.$ rami ed lift of $n$, where $: \mathbb{R P}^{1}!\mathbb{R P}^{1}$ is a rational map that is rami ed over 1 . Furthermore, if : $\mathrm{BS}(1 ; n)$ ! $\mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$ is not faithful, then there exists a $\mathrm{k} \quad 1$ such that $(b)^{k}=\mathrm{id}$.

We give an explicit description of these conjugacy classes in Section 2.1.
The conclusion of Theorem 1.1 does not hold when $C$ ! is replaced by a lower di erentiability class such as $\mathrm{C}^{1}$, even when analytic conjugacy is replaced by topological conjugacy in the statement. Nonetheless, as r increases, there is a sort of \quantum rigidity" phenomenon. Let : BS $(1 ; n)!\mathrm{Di}^{2}\left(\mathrm{~S}^{1}\right)$ be a representation, and let $f=(a)$. We make a preliminary observation:
Lemma 1.2 If the rotation number of $f$ is irrational, then $g^{k}=i d$, for some $\mathrm{k} \quad \mathrm{n}+1$, where $\mathrm{g}=$ (b).
(See the beginning of Section 5 for a proof). Hence, if $2 R^{2}(B S(1 ; n)$ ) is faithful, then $f$ must have periodic points. For $2 R^{2}(B S(1 ; n))$ a faithful representation, we de ne the inner spectral radius ( ) by:

$$
()=\operatorname{supfj}\left(f^{k}\right)^{q}(p) j^{\frac{1}{k}} j \text { p } 2 \text { Fix }\left(f^{k}\right) \text { and } j\left(f^{k}\right)^{q}(p) j \quad \text { lg: }
$$

For the standard representation, $(n)=\frac{1}{n}$, and if $\hat{n}$ is a rami ed lift of $n$, then $\left(\hat{n}_{n}\right)=\frac{1}{n}{ }^{\frac{1}{s}}$, for some s $2 \mathbb{N}_{1}$.

Theorem 1.3 Let : $\mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$ bea faithful representation, where $r 2[2 ; 1]$. If either $r<1$ and ( ) $\frac{1}{\frac{1}{n}} \frac{1}{r-1}$, or $r=1$ and ()$<1$, then is conjugated by an element of $\mathrm{Di}^{r}\left(\mathrm{~S}^{1}\right)$ into a unique conjugacy class in $R^{!}(B S(1 ; n))$.
If takes values in $\mathrm{Di}^{r}{ }_{+}^{r}\left(\mathrm{~S}^{1}\right)$, then is conjugated by an element of $\mathrm{Di}{ }_{+}^{r}\left(\mathrm{~S}^{1}\right)$ into a unique conjugacy dass in $R!(B S(1 ; n))$.

Theorem 1.3 has the following corollary:
Corollary 1.4 Every representation : $\mathrm{BS}(1 ; n)!\mathrm{Di}{ }^{( }\left(\mathrm{S}^{1}\right)$ is $\mathrm{C}^{1}$ locally rigid. Further, if ()$<\frac{1}{n^{\frac{1}{r-1}}}$, then is $C^{r}$ locally rigid.

This corollary implies that the standard representation is $\mathrm{C}^{r}$ locally rigid, for all $r$ 3, and every representation in $R!(B S(1 ; n))$ is locally rigid in some nite di erentiability classes. This local rigidity breaks down, however, if the di erentiability class is lowered.

Proposition 1.5 For every representation : $\mathrm{BS}(1 ; n)!\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$, if ( ) = $\frac{1}{n} \frac{1}{r-1}$, for some $r \quad 2$ then there exists a family of representations $t^{2}$ $R^{r}(B S(1 ; n))$, $2(-1 ; 1)$, with the following properties:
(1) $0=$,
(2) $t \nabla t$ is continuous in the $C^{r-1}$ topology on $R^{r}(B S(1 ; n))$,
(3) for every $t_{1} ; t_{2} 2(-1 ; 1)$, if $t_{1}$ is conjugate to $t_{2}$ in $\mathrm{Di}^{1}\left(S^{1}\right)$ then $\mathrm{t}_{1}=\mathrm{t}_{2}$.

It follows from our characterization of the conjugacy classes in $R!(B S(1 ; n))$ in the next section that, for each value of $r 2[1 ; 1)$, there are in nitely many nonconjugate representations $2 R!(B S(1 ; n))$ satisfying ()$=\frac{1}{n}^{\frac{1}{r}}$ : Hence, for each $r \quad 3$ there are in nitely many distinct (nonconjugate) representations in $R^{!}(B S(1 ; n))$ that are $C^{r}$ locally rigid, but not $C^{r-1}$ locally rigid.
A. Navas has given a complete classi cation of $C^{2}$ solvable group actions, up to nite index subgroups and topological semiconjugacy. One corollary of his result is that every faithful $\mathrm{C}^{2}$ representation of $\mathrm{BS}(1 ; n)$ into $\mathrm{Di}^{2}\left(\mathrm{~S}^{1}\right)$ is is virtually topologically semiconjugate to the standard representation:

Theorem 1.6 [11] Let : $\mathrm{BS}(1 ; n)$ ! $\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$ be a representation, where $r$ 2. Then either is unfaithful, in which case $(b)^{m}=i d$, for some $m$,
or there exists an integer m 1, a nite collection of closed, connected sets $I_{1} ;::: ; I_{k}$, and a surjective continuous map ${ }^{\prime}: S^{1}!\mathbb{R P}^{1}$ with the following properties:
(1) $(b)^{m}$ is the identity on each set $I_{k}$;
(2) ' sends each set $I_{k}$ to 1 ;
(3) the restriction of ' to $S^{1} n S_{i=1} I_{i}$ is a $C^{r}$ covering map of $\mathbb{R}$;
(4) For every $\mathrm{y} 2 \mathrm{BS}(1 ; n)$, the following diagram commutes:

where n : $\mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ is the standard representation.
The map ' in Theorem 1.6 is a sort of \broken $C^{r}$ rami ed cover." The regularity of ' at the preimages of the point 1 can be poor, and the map can bein niteto-one on the sets $I_{1} ;::: ; I_{k}$, but a map with thesefeatures is nothing more than a deformation of a rami ed covering map. Combining Theorem 1.6 with Theorem 1.3 and the proof Proposition 1.5, we obtain:

## Corollary 1.7 Let : $\mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$, be any representation, with r

 2. Then either:(1) is not faithful, and there exists an $m \quad 1$ such that (b) ${ }^{m}=i d$;
(2) admits $\mathrm{C}^{r-1}$ deformations as in Proposition 1.5; or
(3) is $C^{r}$ conjugated into a unique conjugacy dass in $R^{!}(B S(1 ; n))$.

Sincethe statement of Theorem 1.6 does not appear explicitly in Navas's paper, and we don't use this result elsewhere in the paper, we sketch the proof at the end of Section 5.

Finally, note that the trivial representation $0(a)=0(b)=i d$ is not rigid in any topology; it can beapproximated by the representation (b) = id; (a) = f, where $f$ is an any di eomorphism close to the identity. A nother nice conse quence of Navas's theorem is that this is the only way to $\mathrm{C}^{2}$ deform the trivial representation.

Corollary 1.8 There is a $C^{2}$ neighborhood $U \quad R^{2}(B S(1 ; n))$ of the trivial representation such that, for all $2 \mathrm{U},(\mathrm{b})=\mathrm{id}$.

Proof Let bea C ${ }^{2}$ representation. Since (b) is conjugate by (a) to (b) ${ }^{n}$, it will have rotation number of the form $\frac{k}{n-1}$ if (a) is orientation-preserving, and of theform $\frac{k}{n+1}$ if (a) is orientation-reversing. Therefore, if issu ciently $\mathrm{C}^{0}$ \{close to 0 and if $(\mathrm{b})^{\mathrm{m}}=\mathrm{id}$, for some $\mathrm{m} \quad 1$, then $\mathrm{m}=1$. So we may assume that theresexists a map ' as in Theorem 1.6 and that $\mathrm{m}=1$. On a component of $S^{1} n \quad I_{i}$, is a di eomorphism conjugating the action of to the restriction of the standard representation $n$ to $\mathbb{R}$ (in general ' fails to extend to a di eomorphism at either endpoint of $\mathbb{R}$ ). But in the standard action, the element $n(a)$ has a xed point in $\mathbb{R}$ of derivative $n$. If is su ciently $C^{1}$ close to 0 , this can't happen.

We remark that, in contrast to the results in this paper, there are uncountably many topologically distinct faithful representations of $\mathrm{BS}(1 ; n)$ into $\mathrm{Di}!(\mathbb{R})$ (sæ [3], Proposition 5.1). The proof of our results uses the existence of a global xed point on $S^{1}$ for a nite index subgroup of $B S(1 ; n)$; such a point need not exist when $\mathrm{BS}(1 ; n)$ acts on $\mathbb{R}$. Farb and Franks [3] studied actions of Baumslag\{Solitar groups on the line and circle. Among their results, they prove that if $m>1$, the (nonsolvable) Baumslag\{Solitar group:

$$
B S(m ; n)=h a ; b j a b^{m} a^{-1}=b^{n} i ;
$$

has no faithful $C^{2}$ actions on $S^{1}$ if $m$ does not divide $n$. They ask whether the actions of $B(1 ; n)$ on the circle can be classi ed. This question inspired the present paper.

### 1.3 Classi cation of solvable subgroups of $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$

Several works address the properties of solvable subgroups of $\mathrm{Di}^{r}\left(\mathrm{~S}^{1}\right)$; we mention a few here. Building on work of Kopell [8], Plante and Thurston [12] showed that any nilpotent subgroup of $\mathrm{Di}^{2}\left(\mathrm{~S}^{1}\right)$ is in fact abelian. Ghys [6] proved that any solvable subgroup of $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ is metabelian, ie, two-step solvable. In the same work, he remarks that there are solvable subgroups of $\mathrm{Di}{ }^{1}\left(\mathrm{~S}^{1}\right)$ that are not metabelian. The subgroups he constructs contain innitely flat elements | nontrivial di eomorphisms g $2 \mathrm{Di}^{1}\left(\mathrm{~S}^{1}\right)$ with the property that for some p $2 S^{1}, g(p)=p, g^{q}(p)=1$, and $g^{(k)}(p)=0$ for all k 2 .

Navas [11] constructed further examples of solvable subgroups of $\mathrm{Di}^{1}\left(\mathrm{~S}^{1}\right)$ with arbitrary degree of solvability, again using in nitely flat elements. As mentioned above, Navas's work also contains a topological classi cation of solvable
subgroups of $\mathrm{Di}^{2}\left(\mathrm{~S}^{1}\right)$. As part of a study of ergodicity of actions of discrete groups on $S^{1}$, Rebedo and Silva [13] also study the solvable subgroups of Di ! $S^{1}$ ).

Our main result in this part of the paper, Theorem 1.9, implies that any solvable subgroup of $\mathrm{Di}^{1}\left(S^{1}\right)$ that does not contain in nitely flat elements is either virtually abelian or conjugate to a subgroup of a rami ed lift of thea negroup:

$$
A(\mathbb{R})=f \times \nabla \quad c x+d: \mathbb{R} P^{1}!\mathbb{R} P^{1} j c ; d 2 \mathbb{R} ; c \in 0 g:
$$

Theorem 1.9 Let $G<\operatorname{Di~}^{r}\left(S^{1}\right)$ be a solvable group, where r $2 \mathrm{f} 1 ;!\mathrm{g}$. Then either:
(1) for some $m 2 \mathbb{Z}$, the group $G^{m}:=f g^{m}: g 2 G g$ is abelian,
(2) G contains in nitely flat elements (which can't happen if $r=$ !), or
(3) $G$ is conjugate in $\mathrm{Di}{ }^{r}\left(S^{1}\right)$ to a subgroup of a \{rami ed lift of $A(\mathbb{R})$, where $: \mathbb{R} P^{1}!\mathbb{R} P^{1}$ is a rami ed cover over 1 .
Further, if $\mathrm{G}<\operatorname{Di}{ }_{+}^{r}\left(S^{1}\right)$ and (3) holds, then the conjugacy can be taken in Di ${ }_{+}^{r}\left(S^{1}\right)$.

In Section 2, we characterize the rami ed lifts of $A(\mathbb{R})$. To summarize the results there, we have:

Theorem 1.10 There exists a collection

$$
\text { RAFF }:=\mathrm{fA}^{\mathbf{s}}(\mathbb{R})<\operatorname{Di}{ }^{!}\left(\mathrm{S}^{1}\right) \text { j s } 2 \overline{\mathrm{~S}} \mathrm{~g}
$$

where $\bar{S}$ is a countably in nite index set, with the following properties:
(1) if $\mathbf{s}_{1} ; \mathbf{s}_{2} 2 \bar{S}$ and $\mathbb{A}^{\mathbf{s}_{1}}(\mathbb{R})$ is conjugate to $\mathbb{A}^{\mathbf{s}_{2}}(\mathbb{R})$ in $\mathrm{Di}^{1}\left(S^{1}\right)$, then $\mathbf{s}_{1}=\mathbf{S}_{2} ;$
(2) for each $\mathbf{s} 2 \overline{\mathrm{~S}}$, there exists a subgroup H of a dihedral group such that $\mathbb{A}^{\mathbf{s}}(\mathbb{R})^{\prime} A+(\mathbb{R}) \mathrm{H}$,
(3) for each nite dihedral or cyclic group $H$, there exist in nitely many s $2 \overline{\mathrm{~S}}$ so that $\mathbb{A}^{\mathbf{s}}(\mathbb{R})^{\prime} \mathrm{A}_{+}(\mathbb{R}) \mathrm{H}$,
(4) each element of R AF F is the \{rami ed lift of $A(\mathbb{R})$, for somerational rami ed cover : $\mathbb{R} P^{1}$ ! $\mathbb{R} P^{1}$ over 1 , and every \{rami ed lift of A $(\mathbb{R})$ is conjugate in Di ! $\left(\mathrm{S}^{1}\right)$ to an element of R AF F.

There also exists a collection

$$
R A F F+:=f \mathbb{A}_{+}^{\mathbf{s}}(\mathbb{R})<\operatorname{Di} \stackrel{!}{+}_{+}\left(\mathrm{S}^{1}\right) \mathrm{j} \mathbf{s} 2 \overline{\mathrm{~S}}_{+} g
$$

with the same properties, except that in (1) and (4), the conjugacy is orientationpreserving, and in (2) and (3), H is cyclic.

Hence we have found all solvable groups that act e ectively on the circle as real-analytic di eomorphisms.

## 2 Introduction to rami ed lifts

Le G be a group and let : G! $\mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$ be a representation with a global xed point $p$. Restricting each element of this representation to a suitably small neighborhood of $p$, we obtain a representation $\sim G!G!$, where $G$ is the group of analytic germs of di eomorphisms. It is known $[1,10,2]$ that if if $G$ is solvable, then for some $\mathrm{k} \quad 1$, $\sim$ is conjugate in G to a representation taking values in the rami ed a ne group $A{ }^{k}(\mathbb{R})$ :

$$
A^{k}(\mathbb{R})=f \frac{x}{\left(a x^{k}+b\right)^{\frac{1}{k}}} j a ; b 2 \mathbb{R} ; b>0 g
$$

(se[6] for a proof in the context of circledi eomorphisms). The name\ rami ed a ne group" is explained by the fact that the elements of $A{ }^{k}(\mathbb{R})$ are lifts of the elements of the a ne group under the branched (or rami ed) cover $z 7 z^{\mathrm{k}}$. These lifts are well-de ned as holomophic germs, but do not extend to di eomorphisms of $\mathbb{C P}{ }^{1}$.

The key observation of this paper is that the elements of $A(\mathbb{R})$ do admit global rami ed lifts as di eomorphisms of $\mathbb{R P}^{1}$. The reason is that, in contrast to a rami ed cover : $\mathbb{C P}^{1}!\mathbb{C P}^{1}$, which must be rami ed over 2 points, a rami ed cover : $\mathbb{R} P^{1}!\mathbb{R P}^{1}$ is rami ed over one point, which can be chosen to coincide with the global xed point of $A(\mathbb{R})$.

Examples of real rami ed covers The map ${ }_{1}: \mathbb{R}=\mathbb{Z}!\mathbb{R}=\mathbb{Z}$ given by ${ }_{1}(\mathrm{u})=\sin ^{2}(\mathrm{u})$ is a rami ed covering map over 0 , with critical points of order 2 at $\quad{ }_{1}^{-1}(0)=f 0 ; \frac{1}{2} \mathrm{~g}$.
The rational map $2: \mathbb{R} P^{1}!\mathbb{R} P^{1}$ given by:

$$
2(x)=\frac{(x+1)^{2}(x-1)^{2}}{x\left(x^{2}+1\right)}
$$

is also a rami ed covering map over 0 , with critical points of order 2 at 1 . It is clear that 1 are critical points of 2 , and one veri pos directly that the other critical points of 2 in $\mathbb{C P}{ }^{1}$ occur $o$ of $\mathbb{R} P^{1}$, at $i \quad 3 \overline{\overline{8}}^{1}$.

We will de ne an equivalence relation on rami ed covering maps in which 1 and 2 are equivalent, and show that, under this notion of equivalence, all possible rami ed covering maps occur as rational maps.

If : $S^{1}!S^{1}$ is a rami ed covering map over $p$ then for each q $2{ }^{-1}(p)$, there exists an integer $s(q) 1$ such that the leading (nonconstant) term in the Taylor expansion of at q is of order $\mathrm{s}(\mathrm{q})$. A regular covering map is a rami ed covering map; in this case, $d$ is the topological degree of the map, and $\mathrm{s}(\mathrm{q})=1$, for each $\mathrm{q} 2{ }^{-1}(\mathrm{p})$. As the examples show, a rami ed covering map need not be a regular covering map (even topologically), as it is possible to have $\mathrm{s}(\mathrm{q})>1$.

Let be a rami ed covering map over $p$, and let $q_{1} ;::: ; q_{d}$ be the elements of ${ }^{-1}(\mathrm{p})$, ordered so that $\mathrm{p} \quad \mathrm{q}_{1}<\mathrm{q}_{\mathrm{k}}<\quad<\mathrm{q}_{\mathrm{d}}<\mathrm{p}$. For each i 2 f 1 ;:::; dg we de ne oi $2 \mathrm{f} \quad \mathrm{gl}$ by:

$$
\mathrm{o}_{\mathrm{i}}= \begin{cases}1 & \text { if } \mathrm{j}_{\left(\mathrm{q} ; q_{+1}\right)} \text { is orientation-preserving, } \\ -1 & \text { if } \mathrm{j}_{\left(q ; q_{+1}\right)} \text { is orientation-reversing. }\end{cases}
$$

We call the vector $s()=\left(s\left(q_{1}\right) ; s\left(o_{2}\right) ;::: ; s\left(q_{d}\right) ; o_{1} ;::: o_{d}\right) 2 \mathbb{N}^{d} \quad f \quad 1 g^{d}$ the signature of . Geometrically, we think of a signature as a regular d\{gon in $\mathbb{R}^{2}$ with vertices labelled by $s_{1} ;::: ; \mathrm{s}_{\mathrm{d}}$ and edges labelled by $\mathrm{o}_{1} ;::: ; \mathrm{o}_{\mathrm{d}}$. Every signature vector $\mathbf{s}=\left(\mathrm{s}_{1} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{o}_{1} ;::: ; \mathrm{o}_{\mathrm{d}}\right)$ has the following two properties:
(1) The number of vertices with an even label is even: \#f $1 \quad$ i $\quad$ j $s_{i} 2$ $2 \mathbb{N g} 22 \mathbb{N}$ :
(2) If a vertex has an odd label, then both edges connected to that vertex have the same label, and if a vertex has an even labed, then the edges have opposite labels: $(-1)^{s_{i}+1}=\mathrm{o}_{\mathrm{i}-1} \mathrm{o}_{\mathrm{i}}$; where addition is mod d.

We will call any vector $\mathbf{s} 2 \mathbb{N}^{d} \quad f \quad 1 g^{d}$ with these properties a signature vector. Note that a signature vector of length $2 d$ is determined by its rst $d+1$ entries. Le $S_{d}$ be the set of all signature vectors with length $2 d$, and let $S$ be the set of all signature vectors.

Proposition 2.1 Given any s 2 S and $\mathrm{p} 2 \mathrm{~S}^{1}$, there is a rami ed covering map : $S^{1}!S^{1}$ over $p$ with signature $\mathbf{s}$.

Proof Let $\mathbf{s}=\left(\mathrm{s}_{1} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{o}_{1} ;::: ; \mathrm{o}_{\mathrm{d}}\right)$ be a signature, and let $\mathrm{p} 2 \mathbb{R}=\mathbb{Z}$. Choose points $u_{1}<\quad<u_{d}$ evenly spaced in $\mathbb{R}=\mathbb{Z}$, and let $F: \mathbb{R}=\mathbb{Z}!\mathbb{R} \mathcal{Z}$ be the piecewise a ne map that sends the $u_{i}$ to $p$, and which sends each component of $\mathbb{R}=\mathbb{Z} n f u_{1} ;::: ; u_{d} g$ onto $\mathbb{R}=Z n f p g$, with orientation determined by $o_{i}$.

Put a new analytic structure on $\mathbb{R}=\mathbb{Z}$ as follows. In the intervals $I_{j}=\left(u_{j} ; u_{j+1}\right)$ use the standard analytic charts, but in each interval $\mathrm{J}_{\mathrm{j}}=\left(\mathrm{u}_{\mathrm{j}}-; \mathrm{u}_{\mathrm{j}}+\right)$ compose the standard chart (that identi es $u_{j}$ with 0 ) with the homeomorphism
$\mathrm{j}: \mathbb{R}!\mathbb{R}$ de ned by:

Since the overlaps are analytic, this de nes a real anaytic atlas on $\mathbb{R}=\mathbb{Z}$.
Note that the map F: ( $\mathbb{R}=\mathbb{Z}$; new structure) ! $(\mathbb{R}=\mathbb{Z}$; standard structure) is analytic: in charts around $u_{j}$ and $p=F\left(u_{j}\right)$, the map $F$ takes the form $x \nabla x^{5_{j}}$. Since there is a unique real analytic structure on the circle, there is an analytic homeomorphism of the circle $\mathrm{h}:(\mathbb{R}=\mathbb{Z}$;standard structure) ! ( $\mathbb{R}=\mathbb{Z}$; new structure). Let $=F$ h. Then is a a rami ed covering map over 0 with signature $\mathbf{s}$.

In fact, rami ed covers exist in the purely algebraic category; every signature can be realized by a rational map. We have:

Proposition 2.2 Given any s 2 S and $\mathrm{p} 2 \mathbb{R} P^{1}$, there is a rational map $: \mathbb{R} P^{1}!\mathbb{R P}^{1}$ that is a rami ed cover over $p$ with signature $\mathbf{s}$.

Proof Since the proof of Proposition 2.2 is somewhat lengthy, we omit the details. The construction proceeds as follows. Let $\mathbf{s}=\left(\mathrm{s}_{1} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{o}_{1} ;::: ; \mathrm{o}_{\mathrm{d}}\right)$ be a signature, and assume that $p=02 \mathbb{R} P^{1}$ and $o_{1}=1$. Choose a sequence of real numbers $a_{0}<a_{1}<:::<a_{2 d-2}$, let $P(x)=\left(x-a_{0}\right)^{s_{1}}\left(x-a_{2}\right)^{s_{2}}:::(x-$ $\left.a_{2 d-2}\right)^{s_{d}}$ and let $Q(x)=\left(x-a_{1}\right)\left(x-a_{3}\right):::\left(x-a_{2 d-3}\right)$. The desired rational function will be a modi cation of $\mathrm{P}=\mathrm{Q}$.
Le $h(x)$ be a polynomial of even degree with no zeros, with critical points of even degree at $a_{i}, 0$ i $2 d-2$, and with no other critical points. One rst shows that, for N su ciently large, the rational function:

$$
0=\frac{\mathrm{Ph}^{\mathrm{N}}}{\mathrm{Q}}
$$

has zeroes of order $s_{1} ;::: ; s_{d}$ at $a_{0} ; a_{2} ;::: ; a_{2 d-2}$, simple poles at $a_{1} ; a_{3} ;:::$; $a_{2 d-3}$, a pole of odd order at 1 , and no other zeroes, poles or critical points. Hence o is a rami ed covering map over 0 with signature s, except at 1 , where it may fail to be a di eomorphism.
Choose such an $N$, and let $2 m+1$ be the order of the pole 1 for 0 . One then shows that for " su ciently small, the rational function:

$$
(x)=\frac{0(x)}{1+{ }^{\prime 2} x^{2 m}}
$$

has the same properties as 0 , except that 1 is now a simple pole; it is the desired rami ed cover.

If is a rami ed covering map, then the cyclic and dihedral groups:

$$
C_{d}=\mathrm{bb}: \mathrm{b}^{\mathrm{d}}=\mathrm{idi} ; \text { and } \mathrm{D}_{\mathrm{d}}=\mathrm{h} ; \mathrm{b}: \mathrm{b}^{\mathrm{d}}=\mathrm{id} ; \mathrm{a}^{2}=\mathrm{id} ; \mathrm{aba}^{-1}=\mathrm{b}^{-1} \mathrm{i} ;
$$

respectively, act on ${ }^{-1}(p)$ and on the set $E()$ of oriented components of $S^{1} n^{-1}(p)$ in a natural way. By an orientation-preserving homeomorphism, we identify the circle with a regular oriented d \{gon, sending the elements of
${ }^{-1}(p)$ to the vertices and the elements of $E()$ to the edges. The groups $C_{d} \quad D_{d}$ act by symmetries of the $d$ \{gon, inducing actions on ${ }^{-1}(p)$ and $E()$ that are clearly independent of choice of homeomorphism. For q $2^{-1}(p)$, e $2 E()$, and $2 D_{d}$, we write (q) and (e) for ther images under this action.

These symmetry groups also act on the signature vectors in $\mathrm{S}_{\mathrm{d}}$ in the natural way, permuting both vertex labels and edge labels. For $2 \mathrm{D}_{\mathrm{d}}$, we will write
$(\mathbf{s})$ for the image of $\mathbf{s} 2 \mathrm{~S}_{\mathrm{d}}$ under this action. In this notation, the action is generated by:

$$
\mathrm{b}\left(\mathrm{~s}_{1} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{o}_{1} ;::: ; \mathrm{o}_{\mathrm{d}}\right)=\left(\mathrm{s}_{2} ; \mathrm{s}_{3} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{s}_{1} ; \mathrm{o}_{2} ; \mathrm{o}_{3} ;::: ; \mathrm{o}_{\mathrm{d}} ; \mathrm{o}_{1}\right) ;
$$

and

$$
a\left(s_{1} ;::: ; s_{d} ; o_{1} ;::: ; o_{d}\right)=\left(s_{1} ; s_{d} ; s_{d-1}::: ; s_{3} ; s_{2} ;-o_{d} ;-o_{d-1} ;::: ;-o_{2} ;-o_{1}\right):
$$

Denote by $\operatorname{Stab}_{C_{d}}(\mathbf{s})$ and $\operatorname{Stab}_{D_{d}}(\mathbf{s})$ the stabilizer of $\mathbf{s}$ in $\mathrm{C}_{\mathrm{d}}$ and $\mathrm{D}_{\mathrm{d}}$, respectively, under this action:

$$
\operatorname{Stab}_{\mathrm{H}}(\mathbf{s})=\mathrm{f} \quad 2 \mathrm{H} \mathrm{j} \quad(\mathbf{s})=\mathbf{s g} ;
$$

for $H=C_{d}$ or $D_{d}$.
Examples The signature vector of ${ }_{1}(u)=\sin ^{2}(u)$ is $s_{1}=(2 ; 2 ; 1 ;-1)$. The stabilizer of $\mathbf{s}_{1}$ in $D_{d}$ is $\operatorname{Stab}_{D_{d}}\left(\mathbf{s}_{1}\right)=$ hai , and the stabilizer of $\mathbf{s}_{1}$ in $C_{d}$ is trivial. The signature vector of $2(x)=\left((x-1)^{2}(x+1)^{2}\right)=\left(x\left(x^{2}+1\right)\right)$ is $\mathbf{s}_{2}=(2 ; 2 ;-1 ; 1)$. Note that $\mathbf{s}_{2}$ lies in the $\mathrm{C}_{\mathrm{d}}$ \{orbit of $\mathbf{s}_{1}$, and so $\operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}\left(\mathbf{s}_{2}\right)$ and $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}\left(\mathbf{s}_{2}\right)$ must be conjugate to $\operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}\left(\mathbf{s}_{1}\right)$ and $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}\left(\mathbf{s}_{1}\right)$, respectively, by an element of $\mathrm{C}_{\mathrm{d}}$. In this simple case, the stabilizers are equal.

For another example, consider the signature vector

$$
(2 ; 3 ; 1 ; 2 ; 3 ; 1 ;-1 ;-1 ;-1 ; 1 ; 1 ; 1) ;
$$

which geometrically is represented by the following labelled graph:


This labelling has no symmetries, despite thefact that the edge labels have a flip symmetry and the vertex labels have a rotational symmetry. By contrast, the signature ( $2 ; 1 ; 4 ; 2 ; 1 ; 4 ;-1 ;-1 ; 1 ;-1 ;-1 ; 1$ ) has a 180 degree rotational symmetry corresponding to the element $\mathrm{b}^{3} 2 \mathrm{C}_{6}$, and so both stabilizer subgroups are $\mathrm{hb}^{3} \mathrm{i}$.

### 2.1 Characterization of rami ed lifts of the standard representation ${ }_{n}$ of $B S(1 ; n)$

Thenext proposition gives thekey tool for lifting representations under rami ed covering maps.

Proposition 2.3 Let G be a group, and let : G! Di ! ${ }_{+}\left(\mathrm{S}^{1}\right)$ be a representation with global xed point p . Let : $\mathrm{S}^{1}!\mathrm{S}^{11}$ be a rami ed covering map over $p$ with signature $\mathbf{s} 2 S_{d}$, for some $d \quad 1$.
Then for every homomorphism $\mathrm{h}: \mathrm{G}!\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}(\mathbf{s})$, there is a unique representation

$$
\wedge=\uparrow ; h): G!D i!\left(S^{1}\right)
$$

such that, for all $\gamma 2 \mathrm{G}$,
(1) ^is a \{rami ed lift of ;
(2) $\uparrow(\gamma)(q)=h(\gamma)(q)$, for each $q 2^{-1}(p)$;
(3) $\gamma(\gamma)(e)=h(\gamma)(e)$, for each oriented component e2 $E(\quad)$;

Furthermore, if $h$ takes values in $\mathrm{Stab}_{\mathrm{C}_{\mathrm{d}}}(\mathbf{s})$, then ${ }^{\wedge}$ takes values in $\mathrm{Di}{ }_{+}^{!}\left(\mathrm{S}^{1}\right)$.
Proposition 2.3 is a special case of Proposition 4.4, which is proved in Section 4. Note that the representation in Proposition 2.3 must be orientation preserving, although the lift ^might not be, depending on where the image of h lies. There is also a criterion for lifting representations into $\mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$ that are not necessarily orientation-preserving. We discuss this issue in the next subsection.

Lemma 2.4 Suppose that 1 and 2 are two rami ed covering maps over $p$ such that $\mathbf{s}(2)$ lies in the $D_{d}$ \{orbit of $\mathbf{s}(1)$; that is, suppose there exists
$2 \mathrm{D}_{\mathrm{d}}$ such that $\mathbf{s}(2)=(\mathbf{s}(1))$ : Then given any representation : G! Di ${ }_{+}^{!}\left(S^{1}\right)$ with global xed point $p$ and homomorphism h: G! $\operatorname{Stab}_{D_{d}}\left(\mathbf{s}_{1}\right)$, therepresentations $\uparrow{ }_{1} ; \mathrm{h}$ ) and $\uparrow 2 ; \mathrm{h}^{-1}$ ) areconjugatein $\mathrm{Di}!\left(\mathrm{S}^{1}\right)$, where

$$
\left(h^{-1}\right)(\gamma):=h(\gamma)^{-1}:
$$

Furthermore, if $2 \mathrm{C}_{\mathrm{d}}$ and h takes values in $\operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}(\mathbf{s})$, then $\left.\Upsilon_{1} ; \mathrm{h}\right)$ and个 $2 ; \mathrm{h}^{-1}$ ) are conjugate in $\mathrm{Di}{ }_{+}^{!}\left(\mathrm{S}^{1}\right)$.

Lemma 2.4 follows from Lemma 4.5, which is proved in Section 4. We now characterize the countably many conjugacy dasses in $R$ ! $(B S(1 ; n))$. Note that the elements of $S_{d}$ are totally ordered by the lexicographical order on $\mathbb{R}^{n}$. Hence we can write $S_{d}$ as a disjoint union of $C_{d}$ \{orbits:

$$
\mathrm{S}_{\mathrm{d}}=\mathrm{C}_{2 \mathrm{~A}_{+}} \mathrm{C}_{\mathrm{d}}(\mathbf{s})
$$

where for each $2 A_{+}$, $\mathbf{s}$ is the smallest element in its $C_{d}$ \{orbit. Similarly, there is an index set A $A_{+}$such that:

$$
S_{d}=D_{2 A}(\mathbf{s}):
$$

Le $\bar{S}_{d}=\mathrm{fs} \quad \mathrm{j} \quad 2 \mathrm{Ag}$, and let $\bar{S}_{d}^{+}=\mathrm{fs} \quad \mathrm{j} \quad 2 \mathrm{~A}+\mathrm{g}$. Finally, let $\overline{\mathrm{S}}={ }^{\mathrm{S}}{ }_{d} \bar{S}_{d}$ and let $\overline{\mathrm{S}}^{+}={ }_{\mathrm{d}} \overline{\mathrm{S}}_{\mathrm{d}}^{+}$.
De nition Let n : $\mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}{ }_{+}^{!}\left(\mathrm{S}^{1}\right)$ denote the standard projective action, with global xed point at $12 \mathbb{R P}^{1}$. Then we de ne:
$V=f \hat{n}(\mathbf{s} ; \mathrm{h}) \mathrm{j} \mathbf{s} 2 \bar{S}_{\mathrm{d}} ; \mathrm{h} 2 \operatorname{Hom}\left(\mathrm{BS}(1 ; \mathrm{n}) ; \operatorname{Stab}_{D_{\mathrm{d}}}(\mathbf{s})\right)=; \mathrm{d} 2 \mathbb{N} ; \mathrm{d} \quad 1 \mathrm{~g} ;$ and let

$$
V_{+}=f \hat{n}(\mathbf{s} ; h) j \text { s } 2 \bar{S}_{d}^{+} ; h 2 \operatorname{Hom}\left(B S(1 ; n) ; \operatorname{Stab}_{C_{d}}(\mathbf{s})\right) ; d 2 \mathbb{N} ; d \quad 1 \mathrm{~g} ;
$$

where, for $\mathbf{s} 2 S_{d}, \mathbf{s}: S^{1}!S^{1}$ is the rational rami ed cover over 1 with signature $\mathbf{s}$ given by Proposition 2.2, and denotes conjugacy in $\operatorname{Stab}_{D_{d}}(\mathbf{s})$.

Proposition 2.5 Each element of V and $\mathrm{V}_{+}$represents a distinct conjugacy class of faithful representations.
That is, if $\hat{n}\left(s_{1} ; h_{1}\right) ; \hat{n}\left(s_{2} ; h_{2}\right) 2 V\left(r e s p .2 V_{+}\right)$are conjugate in $\mathrm{Di}^{1}\left(S^{1}\right)$ (resp. in Di ${ }_{+}^{1}\left(S^{1}\right)$ ), then $\mathbf{s}_{1}=\mathbf{s}_{2}$ and $h_{1}=h_{2}$.
Proposition 2.5 is proved at theend of Section 4. Our main result, Theorem 1.1, states that the elements of V and $\mathrm{V}_{+}$are the only faithful representations of $\mathrm{BS}(1 ; n)$, up to conjugacy in $\mathrm{Di}!\left(\mathrm{S}^{1}\right)$ and $\mathrm{Di} \stackrel{!}{+}\left(\mathrm{S}^{1}\right)$, respectively.

### 2.2 Proof of Theorem 1.10

To characterize the rami ed lifts of $A(\mathbb{R})$, we need to de ne rami ed lifts of orientation-reversing di eomorphisms. In the end, our description is complicated by the following fact: in contrast to lifts by regular covering maps, ramied lifts of orientation-preserving di eomorphisms can be orientation-reversing, and vice versa.

To deal with this issue, we introduce another action of the dihedral group $D_{d}=h a ; b ; j a^{2}=1 ; b^{d}=1 ; a a^{-1}=b^{-1} i$ on $S_{d}$ that ignores the edge labels completely. To distinguish from the action of $D_{d}$ on $S_{d}$ already de ned, we will write \# : $S_{d}!S_{d}$ for the action of an element $2 D_{d}$. In this notation, the action is generated by:

$$
\mathrm{b}^{\#}\left(\mathrm{~s}_{1} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{o}_{1} ;::: ; \mathrm{o}_{\mathrm{d}}\right)=\left(\mathrm{s}_{2} ; \mathrm{s}_{3} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{s}_{1} ; \mathrm{o}_{1} ; \mathrm{o}_{2} ;::: ; \mathrm{o}_{\mathrm{d}}\right) ;
$$

and

$$
a^{\#}\left(\mathrm{~s}_{1} ;:: ; ; \mathrm{s}_{\mathrm{d}} ; \mathrm{O}_{1} ;::: ; \mathrm{o}_{\mathrm{d}}\right)=\left(\mathrm{s}_{1} ; \mathrm{s}_{\mathrm{d}} ; \mathrm{s}_{\mathrm{d}-1}::: ; \mathrm{s}_{3} ; \mathrm{s}_{2} ; \mathrm{o}_{1} ; \mathrm{O}_{2} ;:: ; ; \mathrm{o}_{\mathrm{d}}\right):
$$

For $\mathbf{s} 2 \mathrm{~S}_{\mathrm{d}}$, we denote by $\mathrm{Stab}_{\mathrm{D}_{\mathrm{d}}}^{\#}(\mathbf{s})$ and $\mathrm{Stab}_{\mathrm{C}_{\mathrm{d}}}^{\#}(\mathbf{s})$ the stabilizers of $\mathbf{s}$ in $D_{d}$ and $C_{d}$, respectively under this action.

Lemma 2.6 For each s2 $\mathrm{S}_{\mathrm{d}}$, there exists a homomorphism

$$
\mathbf{s}: \operatorname{Stab}_{D_{\mathrm{d}}}^{\#}(\mathbf{s})!\mathbb{Z}=\mathbb{Z} ;
$$

such that $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}(\mathbf{s})=\operatorname{ker}(\mathbf{s})$.
Proof Let $\mathbf{s} 2 \mathrm{~S}_{\mathrm{d}}$ be given. Clearly $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}(\mathbf{s})$ is a subgroup of $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}^{\#}(\mathbf{s})$. Le I : $\mathrm{S}_{\mathrm{d}}$ ! $\mathrm{S}_{\mathrm{d}}$ be the involution:

$$
I\left(s_{1} ;::: ; s_{d} ; o_{1} ;::: ; o_{d}\right)=\left(s_{1} ;::: ; s_{d} ;-o_{1} ;::: ;-o_{d}\right):
$$

We show that for every $2 \operatorname{Stab}_{D_{d}}^{\#}(\mathbf{s})$, ether $\quad(\mathbf{s})=\mathbf{s}$ (so that $2 \operatorname{Stab}_{D_{d}}(\mathbf{s})$ ) or $(\mathbf{s})=I(\mathbf{s})$. This follows from the property (2) in the de nition of signature vector, which implies that every element of $S_{d}$ is determined by its rst $d+1$ entries. Hence we may de ne $\mathbf{s}()$ to be 0 if $\quad(\mathbf{s})=\mathbf{s}$ and 1 otherwise Since $I$ is an involution, $s$ is a homomorphism.

Example Consider the signature

$$
\mathbf{s}=(2 ; 1 ; 2 ; 1 ; 2 ; 1 ; 2 ; 1 ; 1 ; 1 ;-1 ;-1 ; 1 ; 1 ;-1 ;-1):
$$

For this example we have $\operatorname{Stab}_{\mathrm{C}_{8}}(\mathbf{s})=\mathrm{hb}^{4} \mathrm{i}, \operatorname{Stab}_{\mathrm{D}_{8}}(\mathbf{s})=\mathrm{ha} ; \mathrm{b}^{4} \mathrm{i}, \operatorname{Stab}_{\mathrm{C}_{8}}^{\#}(\mathbf{s})=$ $\mathrm{hb}^{2} \mathrm{i}$, and $\mathrm{Stab}_{\mathrm{D}_{8}}^{\#}(\mathbf{s})=\mathrm{ha} ; \mathrm{b}^{2} \mathrm{i}$. In this example the homomorphism s is surjective, with nontrivial kerne. For $\mathbf{s}=(2 ; 1 ; 4 ; 1 ; 2 ; 1 ; 4 ; 1 ; 1 ; 1 ;-1 ;-1 ; 1 ; 1 ;-1 ;-1)$, on the other hand, the image of $\quad \mathbf{s}$ is trivial, and $\operatorname{Stab}_{\mathrm{D}_{8}}(\mathbf{s})=\operatorname{Stab}_{\mathrm{D}_{8}}^{\#}(\mathbf{s})=$ $\mathrm{ha} ; \mathrm{b}^{\mathrm{t}} \mathrm{i}, \operatorname{Stab}_{\mathrm{C}_{8}}(\mathbf{s})=\operatorname{Stab}_{\mathrm{C}_{8}}^{\#}(\mathbf{s})=\mathrm{hb}^{4} \mathrm{i}$.
For a third example, recall that the stabilizer $\operatorname{Stab}_{D_{6}}(\mathbf{s})$ of the signature vector $\mathbf{s}=(2 ; 3 ; 1 ; 2 ; 3 ; 1 ;-1 ;-1 ;-1 ; 1 ; 1 ; 1)$ is trivial. Because of the rotational symmetry of the vertex labels, however, $\operatorname{Stab}_{\mathrm{C}_{6}}^{\#}(\mathbf{s})=\operatorname{Stab}_{\mathrm{D}_{6}}^{\#}(\mathbf{s})=\mathrm{hb}^{3}, \quad \mathbb{Z}=\mathbb{Z}$. In this example, $s$ is an isomorphism.

Let $\mathrm{G}<\mathrm{Di}!\left(\mathrm{S}^{1}\right)$ be a subgroup with global xed point p $2 \mathrm{~S}^{1}: \mathrm{f}(\mathrm{p})=\mathrm{p}$, for all f 2 G : We now show how to assign, to each $\mathbf{s} 2 \mathrm{~S}$, a subgroup $\mathrm{G}^{5}$ consisting of rami ed lifts of elements of $G$. We rst write $G=G_{+} t G_{-}$, where $\mathrm{G}_{+}=\mathrm{G} \backslash \mathrm{Di}{ }_{+}^{!}\left(\mathrm{S}^{1}\right)$ is the kernel of the homomorphism $\mathrm{O}: \mathrm{G}!\mathbb{Z}=\mathbb{Z}$ given by:

$$
O(f)=\begin{aligned}
& ( \\
& 0 \\
& \text { if } f \text { is orientation-preserving, } \\
& 1
\end{aligned}
$$

Suppose that : $S^{1}!S^{1}$ is a rami ed covering map over $p$. Then, for every $f 2 \mathrm{G}_{+}$, Proposition 2.3 implies that for every $2 \operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}(\mathbf{s}())$, there is a unique lift $f\left(\right.$; ) $2 \mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ satisfying:
(1) $f \uparrow$; ) is a \{rami ed lift of $f$,
(2) $f \uparrow$; $)(q)=(q)$, for all $q 2^{-1}(p)$, and
(3) $f \uparrow$; $)(e)=(e)$, for all e2 $E(p)$
(Further, this lift is orientation-preserving if $2 \operatorname{Stab}_{\mathrm{c}_{\mathrm{d}}}(\mathbf{s})$.) Suppose, on the other hand, that f 2 G_. In Section 4, we prove Lemma 4.2, which implies that if 2 Stab $_{D_{d}}^{\#}(\mathbf{s})$ satis es:

$$
\begin{equation*}
(\mathbf{s})=I(\mathbf{s}) ; \tag{1}
\end{equation*}
$$

then there exists a unique lift $f\}$; ) $2 \mathrm{Di}!\left(S^{1}\right)$ satisfying (1) \{(3) (and, further, $\mathrm{f}\left(\right.$; ) $2 \mathrm{Di}{ }_{+}^{!}\left(\mathrm{S}^{1}\right)$ if $2 \mathrm{Stab}_{\mathrm{C}_{\mathrm{d}}}^{\#}(\mathbf{s})$. .) We can rephrase condition (1) as:

$$
s()=1:
$$

To summarize this discussion, we have proved the following:
 satisfying (1) $\{(3)$ if and only if:

$$
O(f)=s():
$$

For s 2 S , let $\mathbf{s}$ be the rami ed covering map over $p$ with signature $\mathbf{s}$ given by Proposition 2.1. If $\mathrm{G}<\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ has global xed point p , we de ne $\mathcal{G}^{\mathrm{s}} \mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$ to be the bered product of $G$ and $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}^{\#}(\mathbf{s})$ with respect to $O$ and s :

$$
\left.\left.\hat{G}^{s}:=f f\right\} s ;\right) j(f ;) 2 G \quad \operatorname{Stab}_{D_{d}}^{\#}(\mathbf{s}) ; O(f)=s() g:
$$

Similarly, we de ne:

$$
\left.\left.\hat{G}_{+}^{s}:=\mathrm{ff}\right\} \mathbf{s} ;\right) j(f ;) 2 G \quad \operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}^{\#}(\mathbf{s}) ; O(f)=s() \mathrm{g}:
$$

Lemma 2.7 tells us that $\hat{G}^{5}$ coincides with $\hat{G}$, the set of all s $\{$ rami ed lifts of G , and, similarly, that $\hat{G}_{+}^{5}=\hat{G}^{\mathrm{s}} \backslash \mathrm{Di}+\left(\mathrm{S}^{1}\right)$. It follows from Lemma 4.3 that $\hat{G}^{5}$ and $\hat{G}_{+}^{s}$ are subgroups of $\mathrm{Di}{ }^{!}\left(\mathrm{S}^{1}\right)$ and Di ${ }_{+}^{!}\left(\mathrm{S}^{1}\right)$, respectively, with:

$$
\hat{f_{1}}(s ; 1) \hat{f_{2}}(s ; 2)=\widehat{f_{1} f_{2}}(\mathbf{s} ; 12):
$$

Further, we have:
Proposition 2.8 Assume that $G_{-}$is nonempty. Then $\mathcal{G}^{5}$ and $\hat{G}_{+}^{s}$ are both nite extensions of $G_{+}$; there exist exact sequences:

$$
\begin{equation*}
1!G_{+}!\hat{G}^{s}!\operatorname{Stab}_{D_{d}}^{\#}(\mathbf{s})!1 \tag{2}
\end{equation*}
$$

and

$$
\begin{equation*}
1!G_{+}!\hat{G}_{+}^{s}!\operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}^{\#}(\mathbf{s})!1: \tag{3}
\end{equation*}
$$

Furthermore, if the sequence

$$
1!\mathrm{G}_{+}!\mathrm{G}!\mathrm{O}(\mathrm{G})!1
$$

splits, where $\mathrm{O}: \mathrm{G}!\mathbb{Z}=2 Z$ is the orientation homomorphism, then the se quences (2) and (3) are split, and so is the sequence

$$
\begin{equation*}
1!\hat{G}_{+}^{s}!\hat{G}^{s}!O\left(G^{s}\right)!1: \tag{4}
\end{equation*}
$$

Proof The maps in the rst sequence (2) are given by:

$$
\begin{gathered}
: G_{+}!\hat{G}^{s} \quad f \nabla f(s ; i d) \\
: \hat{G}^{s}!\operatorname{Stab}_{D_{d}}^{\#}(\mathbf{s}) f(\mathrm{f} ;) \nabla:
\end{gathered}
$$

It is easy to see that is injective and is surjective. Moreover, $f(\mathbf{s} ;$ ) is in the kerne of if and only if $=i d$, if and only if $f$ is orientation-preserving, if and only if $f(s ; i d)$ is in the image of . Hence the rst sequence is exact. Similarly, the second sequence (3) is exact.

Now suppose that $1!G_{+}$! $G$ ! $O(G)$ ! 1 is split exact. If $O(G)$ is trivial then $\mathrm{G}_{+}=\mathrm{G}$, and there is nothing to prove. If $\mathrm{O}(\mathrm{G})=\mathbb{Z}=\mathbb{Z}$, then $G$ contains an involution g 2 G - with $\mathrm{g}^{2}=\mathrm{id}$, namely the image of 1 under the homomorphism $O(G)!$ G. We use $g$ to de ne a homomorphism $j: \operatorname{Stab}_{D_{d}}^{\#}(\mathbf{s})!\mathcal{G}^{s}$ as follows:

$$
j()=\begin{array}{lll}
(i d(s ;) & \text { if } & s()=0 \\
g(s ;) & \text { if } & s()=1:
\end{array}
$$

Hence the sequence (2) is split. The restriction of $j$ to $\operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}^{\#}(\mathbf{s})$ splits the sequence (3).
If $\mathrm{O}\left(\hat{G}^{5}\right)$ is trivial, then the last sequence (4) is trivially split. If $\mathrm{O}\left(\hat{G}^{5}\right)=$ $\mathbb{Z}=\mathbb{Z}$, then there exists a $2 \operatorname{Stab}_{D_{d}}^{\#}(s)$ such that $s()=1$. We then de ne $\mathrm{k}: \mathrm{O}\left(\hat{G}^{\mathrm{s}}\right)!\mathrm{G}^{\mathrm{s}}$ by $\mathrm{k}(0)=\mathrm{id}, \mathrm{k}(1)=\mathrm{g}(\mathrm{s}$; ), which implies that (4) is split.

Setting $G=A(\mathbb{R})$, which has the global xed point $12 \mathbb{R} P^{1}$, we thereby de ne $\mathbb{A}{ }^{\mathbf{s}}(\mathbb{R})$ and $\mathbb{A}{ }_{+}^{\mathbf{s}}(\mathbb{R})$, for $\mathbf{s} 2 \mathrm{~S}$. Let $\overline{\mathrm{S}}$ and $\overline{\mathrm{S}}_{+}$bethe sets of signatures de ned at the end of the previous subsection. The elements of $\overline{\mathrm{S}}$ and $\overline{\mathrm{S}}_{+}$are representatives of distinct orbits in S under the dihedral and cyclic actions, respectively. We now de ne:

$$
\operatorname{RAFF}:=f \mathbb{A}(\mathbb{R}) \mathrm{j} \mathbf{s} 2 \overline{\mathrm{~S}} \mathrm{~g} ; \text { and } \mathrm{RAFF}+:=f \mathbb{A}_{+}^{\mathbf{s}}(\mathbb{R}) \mathrm{j} \mathbf{s} 2 \overline{\mathrm{~S}}_{+} g:
$$

Since $A(\mathbb{R})$ contains the involution $x \nabla-x$, the sequence

$$
1!A+(\mathbb{R})!A(\mathbb{R})!\mathbb{Z}=2 \mathbb{Z}!1
$$

splits. Proposition 2.8 implies that

$$
\mathbb{A}^{\mathbf{s}}(\mathbb{R})^{\prime} \mathrm{A}_{+}(\mathbb{R}) \quad \operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}^{\#}(\mathbf{s}) ; \quad \mathbb{A}_{+}^{\mathbf{s}}(\mathbb{R})^{\prime} \mathrm{A}_{+}(\mathbb{R}) \quad \operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}^{\#}(\mathbf{s}) ;
$$

and either $\mathbb{A}^{\mathbf{s}}(\mathbb{R})=\mathbb{A}_{+}^{\mathbf{s}}(\mathbb{R})$ or $\mathbb{A}^{\mathbf{s}}(\mathbb{R}), \mathbb{A}^{\mathbf{s}}(\mathbb{R}) \quad \mathbb{Z}=2 \mathbb{Z}$, depending on whether $s$ is surjective. This proves (2) of Theorem 1.10.
Corollary 4.7 implies that $\mathbb{A}^{\mathbf{s}_{1}}(\mathbb{R})$ and $\mathbb{A}{ }^{\mathbf{s}_{2}}(\mathbb{R})$ are conjugate subgroups in Di ${ }^{1}\left(S^{1}\right)$, only if $\mathbf{s}_{1} 2 D_{d} \mathbf{s}_{2}$. Similarly, $\mathbb{A}_{+}^{\mathbf{s}_{1}}(\mathbb{R})$ and $\mathbb{A}{ }_{+}^{\mathbf{s}_{2}}(\mathbb{R})$ are conjugate subgroupsin Di ${ }_{+}^{1}\left(S^{1}\right)$, if and only if $\mathbf{s}_{1} 2 \mathrm{C}_{\mathrm{d}} \mathbf{s}_{2}$. This proves (1) of the theorem.

Finally, every nite dihedral or cydic group H is the stabilizer of in nitely many s $2 \overline{\mathrm{~S}}$, and hence there are in nitely many $\mathbf{s} 2 \overline{\mathrm{~S}}$ so that $\mathbb{A}^{\mathbf{s}}(\mathbb{R})$ ' A $+(\mathbb{R}) \mathrm{H}$. This proves part (3). Property (4) follows from the de nition of RAF F. This completes the proof of Theorem 1.10.

## 3 The relation $\mathrm{f}_{\mathrm{gf}}{ }^{-1}=\mathrm{g}$ : the central technical result

In this section we analyzetherelation $\mathrm{f} \mathrm{gf}^{-1}=\mathrm{g}$ near a common xed point of f and g . If f and g are real-analytic, then they can be locally conjugated into one of the rami ed a ne groups described at the beginning of Section $2[1,10$, 2]. This gives a local characterization of di eomorphisms of $S^{1}$ satisfying this relation about each common xed point, and to obtain a global characterization, it is a matter of gluing together these local ones. This was the way Ghys [6] proved that every solvable subgroup of $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ is metabelian. To prove Theorems 1.1 and 1.3, we adapt the arguments in [10] to the $\mathrm{C}^{r}$ setting, where additional hypotheses on $f$ and $g$ are required.

Theinitial draft of this paper contained a completely di erent proof of the local characterization of $[1,10,2]$ that does not rely on vector elds and works for $\mathrm{C}^{r}$ di eomorphisms as well, under the right assumptions. In the $\mathrm{C}^{!}$and $\mathrm{C}^{1}$ case, this original proof gives identical results as the vector elds proof, but in the general $\mathrm{C}^{r}$ setting, the proof using vector elds gives sharper results. At the end of this section, we outline the alternate proof method. The main idea behind this method is to study the implications of the relation $\mathrm{f} \mathrm{gf}^{-1}=\mathrm{g}$ for the Schwarzian derivative of $g$ near a common xed point at 0 .
We now state the main technical result of this section. Le [ $q$; $q_{\mathbb{I}}$ ) be a half open interval, let r 2 [ $2 ; 1]\left[\mathrm{f}!\mathrm{g}\right.$, and let $\mathrm{f} ; \mathrm{g} 2 \mathrm{Di}^{\mathrm{r}}\left(\left[\mathrm{q}_{\mathrm{i}} \mathrm{q}_{\mathrm{i}}\right)\right.$ ) be di eomorphisms. Assume that $g$ has no xed points in ( $q$; $q_{1}$ ).

Standing Assumptions We assume that either (A), (B), (C) or (D) holds:
(A) $r=$ !, and there exists an integer $>1$ such that $\mathrm{f} \mathrm{gf}^{-1}=\mathrm{g}$ :
(B) $\mathrm{r} 2\left[2 ; 1\right.$ ), and there is an integer $>1$ such that $\mathrm{f}_{\mathrm{gf}}{ }^{-1}=\mathrm{g}$; and $f q$ q) $\quad 1^{\frac{1}{r-1}}$.
(C) $\mathrm{r}=1, \mathrm{f} q \mathrm{q})<1$, and for some integer $>1$, $\mathrm{f} \mathrm{gf}^{-1}=\mathrm{g}$ :
(D) r 2 f 1 ;! g , g is not in nitely flat, and there is a $\mathrm{C}^{1}$ flow $\mathrm{g}^{\mathrm{t}}$ : $\left[\mathrm{q} ; \mathrm{q}_{1}\right)$ ! $\left[q ; q_{1}\right)$ such that:
(1) $\mathrm{g}^{1}=\mathrm{g}$, and
(2) $\mathrm{f} \mathrm{gf}^{-1}=\mathrm{g}$ for some positive real number $\in 1$.

Assumptions (A), (B) and (C) will arise in the proof of Theorems 1.1 and 1.3, and assumption (D) will arise in the proof of Theorem 1.9. The main technical result that we will use in these proofs is the following.

Proposition 3.1 Assume that either (A), (B), (C) or (D) holds. Then there is a $C^{r}$ di eomorphism : $\left(q ; q_{1}\right)!(-1 ; 1) \quad \mathbb{R}^{1}$ such that for all $p 2$ ( $\mathrm{q}^{-1}(0)$ ):
(1) $(p)=h(p)^{\text {s }}$; where $h:\left[q^{-1}(0)\right)$ ! $[-1 ; 0)$ is a $\mathrm{C}^{r}$ di eomorphism, $s$ is an integer satisfying $1 \mathrm{~s}<\mathrm{r}$, and 2 f 1 g ,
(2) $g(p)=(p)+1$ and $f(p)=(p)$ :

We start with a lemma describing which values of $f(q)$ and $g^{q}(q)$ can occur.
Lemma 3.2 Assume that one of assumptions (A) $\left\{(\mathrm{D})\right.$ holds. Then $\mathrm{g}^{\circ}(\mathrm{q})=1$, and either
(1) $\mathrm{g}^{(\mathrm{i})}(\mathrm{q})=0$ for $2 \quad \mathrm{i} \quad \mathrm{r}$ (in particular, neither assumption (A) nor (D) can hold in this case), or
(2) $f^{q}(q)=\left(\frac{1}{1}\right)^{\frac{1}{s}}$ for some integer $1 \quad s<r$, and

$$
g^{(i)}(q)=0 \text { for } 2 \quad i \quad s ; \quad \text { and } g^{(s+1)}(q) \in 0:
$$

Proof Since $\mathrm{fg}=\mathrm{g} \mathrm{f}$,

$$
\left.f^{q} g(p)\right) g^{q}(p)=(g)^{q}(f(p)) f^{q}(p):
$$

When $\mathrm{p}=\mathrm{q}$, we thus have $\mathrm{g}^{q}(\mathrm{q})=(\mathrm{g})^{9}(\mathrm{q})$ : But $(\mathrm{g})^{q}(\mathrm{q})=\left(\mathrm{g}^{q}(\mathrm{q})\right.$ ), and so $g^{\prime}(q)=1$.
Suppose that $f^{q}(q)=G 1$. Then there is an interval $[q ; p)$ on which $f$ is $C^{r}$ conjugate to the linear map $\times 7 \times([14]$, Theorem 2). So in local coordinates, identifying q with 0 ,

$$
\begin{aligned}
& f(x)=x ; \text { and } \\
& g(x)=x+a x^{s+1}+o\left(x^{s+1}\right) \text { for somes } 1 \text { : }
\end{aligned}
$$

Then

$$
\begin{aligned}
\mathrm{fgf}^{-1}(\mathrm{x}) & =\mathrm{x}+\left(\frac{\mathrm{a}}{\mathrm{~s}}\right) \mathrm{x}^{\mathrm{s}+1}+\mathrm{o}\left(\mathrm{x}^{\mathrm{s}+1}\right) ; \text { and } \\
\mathrm{g}(\mathrm{x}) & =\mathrm{x}+\mathrm{a} x^{s+1}+\mathrm{o}\left(\mathrm{x}^{s+1}\right):
\end{aligned}
$$

So either
(1) $a=0$, and therefore $g^{(i)}(q)=0$ for 2 i $r$, or
(2) a $\in 0$, in which case $=\left(\frac{1}{1}\right)^{\frac{1}{5}}$, and

$$
\begin{aligned}
g^{(i)}(q) & =0 \text { for } 2 \quad \mathrm{i} \\
& \in 0 \text { for } i=s+1:
\end{aligned}
$$

Now suppose that $f(q)=1$. Then in a neighborhood of $q$, we can write

$$
f(x)=x+b x^{k+1}+o\left(x^{k+1}\right) \text { and } g(x)=x+a x^{s+1}+o\left(x^{s+1}\right)
$$

for some $k$, $s \quad 1$. If $k=s$, then

$$
\begin{aligned}
{[f ; g](x) } & :=f g^{-1} g^{-1}(x)=x+o\left(x^{s+1}\right) \\
& =g^{-1}(x)=x+(-1) a x^{s+1}+o\left(x^{s+1}\right):
\end{aligned}
$$

So $\mathrm{a}=0$, and hence $\mathrm{g}^{(\mathrm{i})}(0)=0$ for 2 i $\quad \mathrm{r}$.
If $k \in s$, then we use the following well known result (see, eg, [13]):
Lemma 3.3 If $\mathrm{f}(\mathrm{x})=\mathrm{x}+\mathrm{bx} \mathrm{k}^{\mathrm{k} 1}+\mathrm{o}\left(\mathrm{x}^{\mathrm{k}+1}\right)$ and $\mathrm{g}(\mathrm{x})=\mathrm{x}+\mathrm{ax}{ }^{\mathrm{s}+1}+\mathrm{o}\left(\mathrm{x}^{\mathrm{s}+1}\right)$, and if $s>k \quad 1$, then

$$
[f ; g](x)=x+(s-k) a b x^{s+k}+o\left(x^{s+k}\right):
$$

Assume that $s>k$. (If $s<k$, then the proof is similar). It follows from Lemma 3.3 that

$$
\begin{aligned}
x+(s-k) a b x^{s+k}+o\left(x^{s+k}\right) & =[f ; g](x) \\
& =g^{-1}(x)=x+(-1) a x^{s+1}+o\left(x^{s+1}\right):
\end{aligned}
$$

So either
(1) $\mathrm{k} \quad 2$, and therefore $\mathrm{a}=0$ and $\mathrm{g}^{(\mathrm{i})}(\mathrm{q})=0$, for 2 i r , or
(2) $k=1$, and therefore $b=\frac{-1}{s-1}$.

But if $k=1$, then

$$
\begin{aligned}
x+(s-1) 2 a b x^{s+1}+o\left(x^{s+1}\right) & =\left[f^{2} ; g\right](x) \\
& =f^{2} g f^{-2} g^{-1}(x)=g^{2}-1(x) \\
& =x+\left({ }^{2}-1\right) a x^{s+1}+o\left(x^{s+1}\right):
\end{aligned}
$$

So $b=\frac{{ }^{2}-1}{2(s-1)}=\frac{-1}{s-1}$, which is impossible, since $\in 1$. Therefore $g^{(i)}(q)=0$, for $2 \mathrm{i} \quad \mathrm{r}$.

Lemma 3.4 Assumethat (A), (B), (C) or (D) holds. Then there is a neighborhood $\left[q ; p_{1}\right) \quad\left[q ; q_{1}\right)$ and a $C^{r}$ map $A:\left[q ; p_{1}\right)!\mathbb{R}$ such that for all $p 2\left[q ; p_{1}\right)$,
(1) $\mathrm{A}(\mathrm{p})=\mathrm{oH}(\mathrm{p})^{\mathrm{s}}$, where $\mathrm{H}:\left[\mathrm{q} ; \mathrm{p}_{1}\right)$ ! $\left[0 ; 1\right.$ ) is a $\mathrm{C}^{r}$ di eomorphism, $1 \mathrm{~s}<\mathrm{r}$ is an integer, and o 2 f 1 g ;
(2)

$$
A f(p)=\frac{1}{-} A(p)
$$

(3)

$$
A g(p)=\frac{A(p)}{1-A(p)}
$$

Consequently, $\mathrm{f} q \mathrm{q})=(\underline{1})^{\frac{1}{s}}$ for some integer $1 \quad \mathrm{~s}<\mathrm{r}$, and $\mathrm{g}^{(\mathrm{s}+1)}(\mathrm{q}) \in 0$.
Before giving a proof of Lemma 3.4, we will show how this lemma implies Proposition 3.1.

Lemma 3.5 Assume that (A), (B), (C) or (D) holds. Let A; H;s, and o be given by Lemma 3.4. For $p 2\left[q ; p_{1}\right)$, let

$$
h(p)=\frac{-1}{H(p)} ; \quad \quad 0(p)=\frac{-1}{A(p)}:
$$

Then o extends to a $C^{r}$ map : $\left(q ; q_{1}\right)!(-1 ; 1)$ satisfying the conclusions of Proposition 3.1.

Proof Lemma 3.4 implies that for all $p 2\left(q ; p_{1}\right), \quad o g(p)=o(p)+1$ and ${ }_{0} f(p)=0(p)$. Since $\quad 0$ has been de ned in a fundamental domain for $g$, we can now extend this map to a $C^{r}$ di eomorphism from ( $q ; q_{1}$ ) to ( $-1 ; 1$ ) as follows. Since $g$ has no xed points in $\left(q ; q_{1}\right)$, given any $p 2\left(q ; q_{1}\right)$, there is some $\mathrm{j} 2 \mathbb{Z}$ such that $\mathrm{g}^{j}(p) 2\left(q_{1} ; p_{1}\right)$. Let $(p)=0\left(g^{j}(p)\right)-j$ (which is easily seen to be independent of choice of $j$ ). By construction, $g(p)=(p)+1$ for all $p 2\left(q ; q_{1}\right)$. Since $f(p)=\left(g^{-j}\right) f g^{j}(p)$, we also have:

$$
f(p)=\left(\left(g^{-j}\right) \quad o^{-1}\right)\left(\text { of } \quad 0^{-1}\right)\left(g^{j}(p)\right)=((p)+j)-j=(p):
$$

Hence the conclusions of Proposition 3.1 hold.
Proof of Lemma 3.4 We say that a $C^{2}$ function $c:[a ; b)![a ; b)$ is a $C^{2}$ contraction if $c^{0}$ is positive on $[a ; b)$ and $c(x)<x$, for all $x 2(a ; b)$. Since $g$ has no xed points in ( $q$; $\mathrm{q}_{\mathrm{L}}$ ), either g or $\mathrm{g}^{-1}$ is a $\mathrm{C}^{2}$ contraction. We will assume until the end of the proof that g is a $\mathrm{C}^{2}$ contraction. Replacing g by $\mathrm{g}^{-1}$ does not change the relation $\mathrm{fgf}^{-1}=\mathrm{g}$.
Since $g$ has no xed points in ( $q$; $q_{1}$ ), there is a a unique $C^{1}$ vector eld $X_{0}$ on $\left[q ; q_{1}\right)$ that generates a $C^{1}$ flow $g^{t}$ such that $\mathrm{gj}_{\left[q ; q_{1}\right)}=g^{1}$ (Szekeres, see [11] for a discussion).

Lemma 3.6 For all $\mathrm{j} 2 \mathbb{N}$ and $\mathrm{x} 2\left[q^{\prime} ; q_{1}\right), \mathrm{f}^{-\mathrm{j}} \mathrm{gf}^{\mathrm{j}}(\mathrm{x})=\mathrm{g}^{\frac{1}{1}}(\mathrm{x})$.
Proof We will use the following result of Kopell:
Lemma 3.7 ([8] Lemma 1) Let $g 2 \mathrm{Di}^{2}\left[\mathrm{q}_{\mathrm{f}}\right)$ be a $\mathrm{C}^{2}$ contraction that embeds in a $\mathrm{C}^{1}$ flow $\mathrm{g}^{\mathrm{t}}$, so that $\mathrm{g}=\mathrm{g}^{1}$. If $\mathrm{h} 2 \mathrm{Di}^{1}\left[q_{;} q_{1}\right)$ satis es $\mathrm{hg}=\mathrm{gh}$, then $\mathrm{h}=\mathrm{g}^{\mathrm{t}}$ for some $\mathrm{t} 2 \mathbb{R}$.
It follows from the relation $\mathrm{f}^{\mathrm{j}} \mathrm{gf}^{-\mathrm{j}}=\mathrm{g}^{\mathrm{j}}$ that $\mathrm{f}^{-\mathrm{j}} \mathrm{gf}^{\mathrm{j}}$ commutes with g , and therefore Lemma 3.7 implies that $\mathrm{f}^{-\mathrm{j}} \mathrm{gf}^{j}=\mathrm{g}^{\mathrm{t}}$ for some $\mathrm{t} 2 \mathbb{R}$. This relation also implies that $\left(f^{-j} g^{j}\right)^{j}=g$. So $f^{-j} g^{j}=g^{\frac{1}{1}}$.

Let $=f q(q)$. We may assume, by Lemma 3.2, that $G 1$, and therefore there is an interval ( $q ; p_{1}$ ) on which $f$ has no xed points, and a $C^{r}$ di eomorphism $H:\left[q ; p_{1}\right)![0 ; 1)$ such that $\mathrm{H}_{\mathrm{f}} \mathrm{H}^{-1}(\mathrm{x})=\mathrm{x}([14]$, Theorem 2). The di eomorphism H is unique up to multiplication by a constant. Let $\mathrm{F}=$ $\mathrm{HfH} \mathrm{H}^{-1}$ and let $\mathrm{G}=\mathrm{HgH}^{-1}$. Since we have assumed that g is a contraction, we have $g\left(\left[q ; p_{1}\right)\right) \quad\left[q ; p_{1}\right)$.
Let $X$ be the push-forward of the vector eld $X_{0}$ to $[0 ; 1$ ) under $H$, and let $\mathrm{G}^{\mathrm{t}}$ be the semiflow generated by $\mathrm{X}_{0}$, so that $\mathrm{G}=\mathrm{G}^{1}$.
Lemma 3.8 If $\mathrm{F}^{9}(0) \quad(\underline{1})^{\frac{1}{r-1}}$ and G is r \{flat at 0 , then $\mathrm{X}(\mathrm{x})=0$ on $[0 ; 1$ ).
Proof We will show that for all $\times 2[0 ; 1$ ),

$$
\lim _{t!} \frac{G^{t}(x)-x}{t}=0
$$

Since the limit exists, it is enough to show that it converges to 0 for a subse quence $t_{i}!0$. We will use the subsequence $t_{i}=\frac{1}{1}$. Writing $=F(0)$ as before, we have

$$
F(x)=x \text { and } G(x)=x+R(x)
$$

where $R(x)=x^{r}$ ! 0 as $x!0$, and therefore:

$$
G^{t_{i}}(x)=F^{-i} G F^{i}(x)=x+\frac{1}{i} R\left(\left({ }^{i} x\right)\right):
$$

So

$$
0 \begin{aligned}
\lim _{i!1} \frac{j G^{t_{i}}(x)-x j}{t_{i}}= & \lim _{i!1}{ }^{i} \frac{1}{i} j R\left({ }^{i} x\right) j \\
= & \lim _{i!1}\left({ }^{r-1}\right)^{i} x^{r} \frac{j R\left(\left({ }^{i} x\right)\right) j}{\left({ }^{i} x\right)^{r}} \\
& \lim _{i!1} x^{r} \frac{j R\left(\left({ }^{i} x\right)\right) j}{\left({ }^{i} x\right)^{r}}=0 ;
\end{aligned}
$$

Geometry \& Topology, Volume 8 (2004)
since ${ }^{r-1} \quad \underline{1}$.
Corollary 3.9 Under any assumption (A) $\{(\mathrm{D}), \mathrm{g}$ is not r flat at q , and therefore $f(q)=(\underline{1})^{\frac{1}{s}}$, for some integer $1 \quad s<r$.

Proof Clearly g cannot bein nitely flat if (A) or (D) holds. Under assumption (C), $f^{q} q$ ) < ( $\left.{ }^{1}\right)^{\frac{1}{k}}$, for some $k>0$ and $f ; g$ are $C^{k}$, so (C) reduces to (B). By Lemma 3.8, under assumption (B), if $g$ is $r$ fflat at $q$, then the semiflow $G^{t}$ is tangent to the trivial vector eld, $X(x)=0$. But then $G=i d$, and therefore $g=i d$ on $\left[q ; p_{1}\right)$, contradicting the assumption that $g$ has no xed points in $\left(q ; q_{1}\right)$.

Lemma 3.10 If $\mathrm{F}^{( }(0)=(\underline{1})^{\frac{1}{s}}$ for some integer $1 \quad s<r$, then for some $a<0, X(x)=a x^{s+1}$ on $[0 ; 1)$.

Proof As in the proof of Lemma 3.8, it is enough to show that for all $\times 2$ $[0 ; 1)$, and for $t_{i}=\frac{1}{1}$,

$$
\lim _{i!1} \frac{G^{t_{i}}(x)-x}{t_{i}}=a x^{s+1}
$$

for some a $2 \mathbb{R}$. If $F^{( }(0)=(\underline{1})^{\frac{1}{s}}$ for some integer $1 \quad s<r$, then by Lemma 3.2,

$$
F(x)=\left(\frac{1}{-}\right)^{\frac{1}{5}} x \text { and } G(x)=x+a x^{s+1}+R(x)
$$

for some a $2 \mathbb{R}$, where $R(x)=x^{s+1}$ ! 0 as $x$ ! 0 . The value of a depends on the choice of linearizing map $h$ for $\mathrm{f}_{\left(q ; p_{1}\right)}$. For all i $2 \mathbb{N}$,

$$
\begin{aligned}
G^{t_{i}}(x)=F^{-i} G F^{i}(x) & =\frac{i}{5} G \frac{x}{\frac{i}{5}} \\
& =x+a x^{s+1} \frac{1}{i}+\frac{i}{5} R \frac{x}{\frac{i}{5}}:
\end{aligned}
$$

So

$$
\begin{aligned}
\lim _{i!1} \frac{G^{t_{i}}(x)-x}{t_{i}} & =\lim _{i!1} i a x^{s+1} \frac{1}{i}+\frac{i}{s} R \frac{x}{\frac{i}{s}} \\
& =\lim _{i!1} a x^{s+1}+R \frac{x}{\frac{i}{s}} \frac{\frac{i(s+1)}{s}}{x^{s+1}} x^{s+1}=a x^{s+1}
\end{aligned}
$$

Since $G$ is a contraction on $[0 ; 1$ ), it follows that a 0 , and since G $G$ id, we must have $\mathrm{a}<0$.

Geometry \& Topology, Volume 8 (2004)

C orollary 3.11 If one of $(A)\left\{(D)\right.$ holds, then $f(q)=(\underline{1})^{\frac{1}{s}}$ for some integer $1 \mathrm{~s}<\mathrm{r}$, and, after a suitable rescaling of the linearizing map $H$,

$$
G(x)=\frac{x}{\left(1+x^{5}\right)^{\frac{1}{s}}}:
$$

Proof Choose $H$ so that $a=-1=5$. Solving the di erential equation ${ }_{\tau} G^{t}(x)$ $=\mathrm{aG}^{\mathrm{t}}(\mathrm{x})^{\mathrm{s}+1}$ with initial condition $\mathrm{G}^{0}(\mathrm{x})=\mathrm{x}$, we obtain $\mathrm{G}^{\mathrm{t}}(\mathrm{x})=\mathrm{x}=\left(1+\mathrm{tx} \mathrm{x}^{\mathrm{s}}\right)^{\frac{1}{s}}$. Since $G(x)=G^{1}(x)$, the conclusion follows.

To complete the proof of Lemma 3.4 assuming that g is a contraction, let $\mathrm{s} ; \mathrm{H}$ be given by Corollary 3.11, and let $0=-1$. Then Corollary 3.11 implies that $\mathrm{A}(\mathrm{p})=\mathrm{o}\left(\mathrm{H}(\mathrm{p})^{\mathrm{s}}\right)$ satis es the desired conditions. If g is not a contraction, we replace g by $\mathrm{g}^{-1}$ in the proof. Setting $\mathrm{o}=1$, we obtain the desired conclusions.

### 3.1 Idea behind an alternate proof of Proposition 3.1

Supposethat $f$ and $g \in$ id are $\mathrm{C}^{r}$ di eomorphisms, de ned in a neighborhood of 0 in $\mathbb{R}$, both xing the origin, and satisfying the relation:

$$
\mathrm{f}_{\mathrm{gf}} \mathrm{f}^{-1}=\mathrm{g} \text {; }
$$

for some $>1$. In this context, the conclusion of Proposition 3.1 can be reformulated as follows: $f$ and $g$ are conjugate, via $-1=$, to the maps

$$
\times 7\left(\frac{1}{-}\right)^{\frac{1}{5}} x \text { and } \times 7 \frac{x}{\left(1-0 x^{5}\right)^{\frac{1}{5}}}
$$

for some integer $1 \quad \mathrm{~s} \quad \mathrm{r}$ and some o $2 \mathrm{f} \quad 1 \mathrm{~g}$. The proof of Proposition 3.1 uses vector elds; herewesketch an alternative proof of this reformulation, using the Schwarzian derivative. This sketch can be made into a complete proof of Proposition 3.1 under assumptions (A), (C) and (D), but gives a weaker result in case (B): for this proof we will need both $r \quad 2 s+1$ and $f(q) \quad(\underline{1})^{1=(s-1)}$, for some $s \quad 1$.
For simplicity, assume that $r=!$ and that $=2$. First note that, since $g$ is not in nitely flat, Lemma 3.2 implies that $f 90) 2 f^{\frac{1}{2}} \frac{1}{5} \mathrm{js}$ 1g. After conjugating $f$ and $g$ by an analytic di eomorphism, we may assume, then, that:

$$
f(x)=\frac{x}{2^{\frac{1}{s}}}
$$

for some s 1.
Le $F(x)=f\left(x^{\frac{1}{s}}\right)^{s}=x=2$ and let $G(x)=g\left(x^{\frac{1}{s}}\right)^{s}$. Rewriting the retation F GF ${ }^{-1}=\mathrm{G}^{2}$, we obtain:

$$
\frac{1}{2} G(2 x)=G^{2}(x)
$$

rearranging and iterating this relation, we obtain:

$$
\begin{equation*}
G(x)=2^{k} G^{2^{k}} \frac{x}{2^{k}} ; \tag{5}
\end{equation*}
$$

for all k 1 .
Recall that the Schwarzian derivative of a $\mathrm{C}^{3}$ function H is de ned by:

$$
S(H)(x)=\frac{H^{q}(x)}{H^{q}(x)}-\frac{3}{2}{\frac{H^{q}(x)}{H^{q}(x)}}^{2} ;
$$

and has the following properties:
(1) $S(H)(x)=0$ for all $x$ i $G$ is Möbius, and
(2) for any $C^{3}$ function $K, S(H \quad K)(x)=K 9(x)^{2} S(H)(K(x))+S(K)(x)$.

Combining these properties with (5), we will show that $S(G)=0$, which implies that $G$ is Möbius. Lemma 3.2 implies that $G^{9}(0)=1$ and $G^{0}(0) \in 0$, so we have $G(x)=\frac{x}{1-o x}$ for o 2 f 1g. Writing $g(x)=G\left(x^{5}\right)^{1=5}$, we obtain the desired result.
The rst thing to check is that $G$ is $C^{3}$. To obtain this, we use a slightly stronger version of Lemma 3.2 (whose proof is left as an exercise), which states that, if $g$ is not in nitely flat, then

$$
g(x)=x+a x^{s+1}+b x^{2 s+1}+
$$

Performing the substitution $G=g\left(x^{1=s}\right)^{s}$ in this series, one nds that $G$ is $C^{3}$. (This requires that $g$ be at least $\mathrm{C}^{2 s+1}$, in contrast to the proof of Proposition 3.1, which requires only $\mathrm{C}^{\mathrm{s}+1}$ ).
Equation (5) implies that

$$
\mathrm{S}(\mathrm{G})(\mathrm{x})=\frac{1}{2^{2 \mathrm{k}}} \mathrm{~S}\left(\mathrm{G}^{2^{\mathrm{k}}}\right)\left(\frac{\mathrm{x}}{2^{\mathrm{k}}}\right) ;
$$

for all $k$ 1. Thus, by the cocycle condition (2) of the Schwarzian, we have:

$$
\begin{align*}
& S(G)(x)={\frac{1}{2^{2 k}}}_{i=1}^{\chi^{k}} S(G)\left(G^{i-1}\left(\frac{x}{2^{k}}\right)\right) \quad\left(G^{i-1}\right) 9\left(\frac{x}{2^{k}}\right)^{2}  \tag{6}\\
& ={\frac{1}{2^{2 k}}}^{\chi^{2}=1} \mathrm{~S}(G)\left(x_{i}\right){ }_{j=1}^{i-1} G^{q}\left(x_{j}\right)^{2} \tag{7}
\end{align*}
$$

Geometry \& Topology, Volume 8 (2004)
where $x_{i}:=G^{i-1}\left(\frac{x}{2^{k}}\right)$.
Fix $x$, and assume without loss of generality that $G^{j}(x)!0$ as $j!1$. Since $G$ is $C^{3}$ and $G^{9}(0)=1$, there is a constant $C>0$ such that $\mathrm{jG}^{9}\left(x_{i}\right) j \quad 1+\frac{c}{2^{k}}$, and $\mathrm{jS}(\mathrm{G})\left(\mathrm{x}_{\mathrm{i}}\right) \mathrm{j} \quad \mathrm{C}$, for all i between 1 and $2^{\mathrm{k}}$ and all $\mathrm{k} \quad$. Combined with (6), this gives us a bound on the Schwarzian of $G$ at $x$ :

$$
\begin{aligned}
& j S(G)(x) j \quad{\frac{C}{2^{2 k}}}_{i=1}^{X^{k}} 1+{\frac{C}{2^{k}}}^{2(i-1)} \\
& \frac{C}{2^{2 k}} \frac{1-\left(1+\frac{c}{2^{k}}\right)^{2^{k+1}}}{1-\left(\frac{C}{1}+\frac{C}{2^{k}}\right)^{2}} \\
& \frac{1}{2^{k}} \frac{\mathrm{e}^{2 \mathrm{C}}-1}{2+\frac{\mathrm{C}}{2^{k}}} ;
\end{aligned}
$$

for all $k$ 1. Hence $S(G)(x)=0$, for all $x$, which implies that $G$ is Möbius.

## 4 Further properties of rami ed covers: proofs of Proposition 2.3, Lemma 2.4 and Proposition 2.5

The next lemma describes a useful normal form for rami ed covering maps.
Lemma 4.1 Let : $\mathbb{R} P^{1}!\mathbb{R P}^{1}$ be a rami ed covering map over 0 , where ${ }^{-1}(0)=f x_{1} ;::: ; x_{d} g$. Let $\mathbf{s}=\left(s\left(x_{1}\right) ;::: ; s\left(x_{d}\right) ; o_{1} ;::: ; o_{d}\right)$ be the signature of . Then given any $x_{i} 2^{-1}(0)$, there is a neighborhood $U$ of $x_{i}$ and an analytic di eomorphism $h: \mathrm{U}!\mathbb{R}$ such that for all $\times 2 \mathrm{U}$,

$$
(x)=h(x)^{s\left(x_{i}\right)}:
$$

Proof In local coordinates at $x_{i}$, identifying $x_{i}$ with 0 , we can write

$$
\begin{aligned}
(x) & =a x^{5}(1+O(x)) \\
& =a x^{5} g(x)
\end{aligned}
$$

where $a>0, s=s\left(x_{i}\right)$ and $g(x)=(1+O(x))$. Let $h(x)=a^{\frac{1}{5}} x g(x)^{\frac{1}{5}}$. Then $h(x)$ is analytic in a neighborhood of 0 , and $(x)=h(x)^{s}$.

This lemma motivates the following de nition.
De nition $A C^{r}$ rami ed cover over $p 2 S^{1}$ is a map : $S^{1}$ ! $S^{1}$ satisfying:
(1) ${ }^{-1}(p)=f q_{1} ; q_{2} ;:: ; q_{d} g$, where $q_{1}<q_{2}<:::<q_{d}$;
(2) the restriction of to ${ }^{-1}\left(\mathrm{~S}^{1} \mathrm{nfpg}\right)$ is a regular $\mathrm{C}^{r}$ covering map onto $S^{1} n f p g$ of degree d 1 ;
(3) for all 1 i d, there are neighborhoods $U_{i}$ of $q$ and $V$ of $p$, and $C^{r}$ charts $h_{i}: U_{i}!\mathbb{R}$ and $k_{i}: V!\mathbb{R}$ with $h_{i}(q)=0$ and $k_{i}(p)=0$, such that

$$
k_{i} \quad h_{i}^{-1}(x)=x^{s_{i}}
$$

for some integer $s_{i}>0$.
Remark By Lemma 4.1, a rami ed cover is a C! rami ed cover.
We de ne the signature of a $\mathrm{C}^{r}$ rami ed cover in the obvious way.
De nition Let $1_{1}$ and 2 be $C^{r}$ rami ed covering maps of degree d over $p_{1}$ and $p_{2}$, respectively. Fix an orientation preserving identi cation between
$1_{1}^{-1}(p)$ and $2_{2}^{-1}(p)$ and between $E(1)$ and $E(2)$. Supposethat $f 2 \mathrm{Di}^{r}\left(S^{1}\right)$ satis es $f\left(p_{1}\right)=p_{2}$, and let $2 D_{d}$. We say that $f\left(2 D i^{r}\left(S^{1}\right)\right.$ is a ( $\left.1 ; 2 ;\right)$ \{ rami ed lift of $f$ if:
(1) $f(q)=(q)$, for all q $2{ }_{1}^{-1}\left(p_{1}\right)$,
(2) $f(e)=(e)$, for all e2 $E\left({ }_{1}\right)$, and
(3) the following diagram commutes:


Lemma 4.2 Let 1,2 and $f$ be as above. Suppose that $2 D_{d}$ satis es

$$
\begin{aligned}
& (\mathbf{s}(1))=\mathbf{s}(2), \text { if f } 2 \mathrm{Di}_{+}^{\mathrm{r}}\left(\mathrm{~S}^{1}\right) \text {, or } \\
& (\mathbf{s}(1))=1(\mathbf{s}(2)) \text {, if } \mathrm{f} 2 \mathrm{Di}_{-}^{r}\left(\mathrm{~S}^{1}\right),
\end{aligned}
$$

where $I: S_{d}!S_{d}$ is the involution that reverses the sign of the last $d$ coordinates.

Then there exists a unique ( $1 ; 2$; ) \{rami ed lift of $f$. We denote this lift by $f(1 ; 2 ;)$, or by $f($; ), if $1=2=$.
Furthermore, we have that if $2 \mathrm{C}_{\mathrm{d}}$, then $f(1 ; 2 ;) 2 \mathrm{Di}^{r}+\left(S^{1}\right)$.

Proof Suppose rst that $f$ preserves orientation. Sincetherestriction of ${ }_{1}$ to ${ }_{1}^{-1}\left(S^{1} n f p_{1} g\right)$ and the restriction of 2 to ${ }_{2}^{-1}\left(S^{1} n f p_{2} g\right)$ are both regular $C^{r}$ covering maps of degree d , for any $2 \mathrm{D}_{\mathrm{d}}$ there is a unique $\mathrm{C}^{r}$ di eomorphism $\hat{f_{0}}$ : $S^{1} n{ }_{1}^{-1} f p_{1} g!S^{1} n{ }_{2}^{-1} f p_{2} g$ such that $\hat{f_{0}}(e)=(e)$ for all e2 $E\left({ }_{1}\right)$, and the diagram (3) commutes on the restricted domains. The condition $\mathbf{s}(2)=$ ( $\mathbf{s}(1))$ implies that $\hat{f_{0}}$ extends to a unique homeomorphism $f$ such that $f(q)=(q)$, for all q $2{ }^{-1}\left(p_{1}\right)$ and such that the diagram in (3) commutes. It remains to show that $\hat{f}^{1}$ is a $C^{r}$ di eomorphism.
It su ces to show that $\hat{f}^{\wedge}$ is a $\mathrm{C}^{r}$ di eomorphism at each q $2{ }_{1}^{-1}\left(p_{1}\right)$. By Lemma 5.6, there are local coordinates near $q$ and $f(q)$, identifying both of these points with 0 , such that

$$
(f(x))^{s(f(q))}=f\left(x^{s(q)}\right)
$$

for some integers $s(f(q))$ and $s(q)$. Since $\mathbf{s}(2)=\left(s\left({ }_{1}\right)\right)$, we have $s((q))=$ $s(q)$. Let $j=s(q)=s(f(q))$. Since $f$ is $C^{r}$ and has a $x e d$ point at 0 ,

$$
f(x)=a_{1} x+a_{2} x^{2}+:::+x^{r}+o\left(x^{r}\right)
$$

and we can assume that the coordinates have been chosen so that $a_{1}>0$. So near $x=0$,

$$
\begin{aligned}
f(x) & =\left(a_{1} x^{j}+a_{2} x^{2 j}+:::+x^{r j}+o\left(x^{r j}\right)\right)^{\frac{1}{j}} \\
& =x\left(a_{1}+a_{2} x^{j}+:::+x^{(r-1) j}+o\left(x^{(r-1) j}\right)\right)^{\frac{1}{j}}
\end{aligned}
$$

where the root is chosen so that $f^{\circ}(0)>0$. Since $a_{1}>0$ and $r \quad 2, f^{\wedge}$ is a $C^{r}$ di eomorphism at 0 . Similarly, we see that if $f$ is analytic, then $f$ is analytic. Finally, we note that since $f$ is orientation preserving, if $2 C_{d}$, then $f \wedge$ must also be orientation preserving.
Now supposethat $\mathrm{f} 2 \mathrm{Di} \underline{\mathrm{r}}_{-}\left(\mathrm{S}^{1}\right)$, and that $(\mathbf{s}(1))=I(\mathrm{~s}(2))$. Let ${ }^{-1}=\mathrm{f} \quad 1$. Setting $f^{\wedge}$ to be the ( ${ }_{1} ; 2$; ) \{lift of the identity map, we obtain the desired conclusions.

Lemma 4.3 Let $f_{1}$ and $f_{2}$ be $C^{r}$ di eomorphisms of $S^{1}$, both with a xed point at $p$, let : $S^{1}!S^{1}$ bea $C^{r}$ rami ed covering map over $p$ with signature $\mathbf{s}$, and let ${ }_{1}, 22 \mathrm{D}_{\mathrm{d}}$. Suppose that 1 and 2 satisfy ${ }_{i}(\mathbf{s})=\mathbf{s}$ if $\mathrm{f}_{\mathrm{i}} 2$ Di ${ }_{+}^{r}\left(S^{1}\right)$, and ${ }_{i}(\mathbf{s})=I(\mathbf{s})$ if $f_{i} 2$ Di $_{-}^{r}\left(S^{1}\right)$. Then

$$
\hat{f_{2}}(; 2) \hat{f_{1}}\left(;{ }_{1}\right)=\widehat{f_{2} f_{1}}(; 2 \quad 1):
$$

Proof The map $\hat{f_{2}}(; 2) \hat{f_{1}}(; 1)(q)$ satis es:
(1) $\hat{f_{2}}(; 2) \hat{f_{1}}\left(;{ }_{1}\right)(q)=2 \quad 1(q)$, for all $q 2^{-1}(p)$,
(2) $\hat{f_{2}}(; 2) \hat{f_{1}}\left(;{ }_{1}\right)(e)=2 \quad 1(e)$, for all e2 $E($ ), and
(3) the following diagram commutes:


By Lemma 4.2, we must have $\hat{\mathrm{f}_{2}}(; 2) \hat{f_{1}}(; 1)=\widehat{f_{2} f_{1}}\left(; 2{ }_{1}\right)$ :

The following proposition is a $\mathrm{C}^{r}$ version of Proposition 2.3.
Proposition 4.4 Suppose that G is a group, and that : G! $\mathrm{Di}^{r}{ }_{+}\left(\mathrm{S}^{1}\right)$ is a representation with global xed point p. Let : $\mathrm{S}^{1}$ ! $\mathrm{S}^{1}$ be a $\mathrm{C}^{r}$ rami ed cover over $p$ with signature vector $\mathbf{s}$. Then for every homomorphism $\mathrm{h}: \mathrm{G}$ ! $\mathrm{Stab}_{\mathrm{D}_{\mathrm{d}}}(\mathbf{s})$, there is a unique representation

$$
\wedge=\uparrow ; h): G!\operatorname{Di}^{r}\left(S^{1}\right)
$$

such that, for all $\gamma 2 \mathrm{G}, \gamma^{\prime} \gamma$ ) is the $(; h(\gamma))\{$ rami ed lift of $(\gamma)$. If $h$ takes values in $\mathrm{Stab}_{\mathrm{C}_{\mathrm{d}}}(\mathbf{s})$, then ${ }^{\wedge}$ takes values in $\mathrm{Di}_{+}^{r}\left(\mathrm{~S}^{1}\right)$.

Proof This follows immediately from the previous two lemmas.

The following lemma is a $\mathrm{C}^{r}$ version of Lemma 2.4.
Lemma 4.5 Let G be a group, and let : $\mathrm{G}!\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ be a representation with global xed point $p$. Let $1 ; 2: S^{1}!S^{1}$ be $C^{r}$ rami ed covers over p $2 S^{1}$, with $\mathbf{s}(1)=(\mathbf{s}(2))$, for some $2 D_{d}$.

Then for every homomorphism $\mathrm{h}: \mathrm{G}$ ! $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}(\mathbf{s})$, the representation $\dagger_{1} ; \mathrm{h}$ ) is conjugate to $+2 ; \mathrm{h}^{-1}$ ) in $\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$, where $\left(\mathrm{h}^{-1}\right)(\mathrm{\gamma}):=\mathrm{h}(\mathrm{\gamma})^{-1}$. If takes values in $\mathrm{Di} \stackrel{+}{+}\left(\mathrm{S}^{1}\right)$, if $\quad 2 \mathrm{C}_{d}$, and if $h$ takes values in $\operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}(\mathbf{s})$, then $\left.{ }^{\prime}{ }_{1} ; \mathrm{h}\right)$ and ${ }^{( } 2 ; \mathrm{h}^{-1}$ ) are conjugate in $\mathrm{Di}_{+}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$.

Proof This lemma follows from the diagram below, which commutes by Proposition 4.4 and Lemma 4.2. (Here ital = ibal $\left.1 ; 2 ;{ }^{-1}\right)$ ).

Geometry \& Topology, Volume 8 (2004)


Consider two lifts $f\left(\begin{array}{l}\text {; }\end{array}\right), f(2 ;$ ) of the same di eomorphism f (or, more generally, of conjugate di eomorphisms). For purely topological reasons, if these lifts are conjugate by a map with rotation number 0 , then $\mathbf{s}\left({ }_{1}\right)$ and $\mathbf{s}(2)$ have the same length 2 d , and the nal d entries in these vectors must agree (More generally, if the conjugacy has nonzero rotation number, then the nal $d$ entries of the rst vector must lie in the $D_{d}$ \{orbit of the nal $d$ entries of the second). We now examine the rst d entries of both vectors. We show that, under appropriate regularity assumptions on $f$ and on the conjugacy, these entries must also agree so that $\mathbf{s}(1)=\mathbf{s}(2)$. The next lemma is the key reason for this.

Lemma 4.6 Let $\mathrm{c}:[0 ; 1)!\left[0 ; 1\right.$ ) be a $\mathrm{C}^{2}$ contraction. Suppose that, for some integers $m ; n>0$, the maps $v_{1}(x)=c\left(x^{m}\right)^{1=m}$ and $v_{2}(x)=c\left(x^{n}\right)^{1=n}$ are conjugate by a $\mathrm{C}^{1}$ di eomorphism $\mathrm{h}:[0 ; 1)![0 ; 1)$. Then $\mathrm{m}=\mathrm{n}$.

Proof Since c is a $\mathrm{C}^{2}$ contraction, the standard distortion estimate (see, eg [8]) implies that for all $x ; y 2[0 ; 1$ ), there exists an $M \quad 1$, such that for all k 0 ,

$$
\begin{equation*}
\frac{1}{M} \quad \frac{\left(c^{k}\right)^{q}(x)}{\left.\left(c^{k}\right)^{9} y\right)} \quad M: \tag{8}
\end{equation*}
$$

Assume without loss of generality that $\mathrm{n}>\mathrm{m}$ and suppose that there exists a $C^{1}$ di eomorphism $h:[0 ; 1)![0 ; 1)$ such that $h v_{1}(x)=v_{2}(h(x))$, for all
$x 2[0 ; 1)$. Let $H(x)=h\left(x^{1=m}\right)^{n}$. Note that the $C^{1}$ function $H:[0 ; 1)$ ! [0;1) has the following properties:
(1) $H^{q}(x) \quad 0$, for all $x 2[0 ; 1)$, and $H^{q}(x)=0 i \quad x=0$;
(2) for all $\mathrm{k} \quad 0, \mathrm{H} \quad c^{k}=c^{k} \mathrm{H}$.

Then (2) implies that for every $\times 2[0 ; 1$ ):

$$
\left.H^{q}(x)=H^{q} c^{k}(x)\right) \frac{\left(c^{k}\right)^{q}(x)}{\left.\left(c^{k}\right)^{q} H(x)\right)}
$$

for all $k \quad 0$. But (8) implies that $\left.\left(c^{k}\right)^{q}(x)=c^{k}\right)^{9}(H(x))$ is bounded independently of $k$, so that $H^{q}(x)=\lim _{k!} 1 H^{9}\left(c^{k}(x)\right)=0$, contradicting property (1).

Corollary 4.7 Let $G$ and $H$ bein nite subgroups of $\mathbb{A}^{\mathbf{s}_{1}}(\mathbb{R})$ and $\mathbb{A}^{\mathbf{s}_{2}}(\mathbb{R})$, respectively, for some $\mathbf{s}_{1} ; \mathbf{s}_{2} 2 \overline{\mathrm{~S}}$. If there exists $2 \mathrm{Di}^{1}\left(\mathrm{~S}^{1}\right)$ such that $\mathrm{G}^{-1}=\mathrm{H}$, then $\mathbf{s}_{1}=\mathbf{s}_{2}$.
If $G<\mathbb{A}{ }_{+}^{\boldsymbol{s}_{1}}(\mathbb{R})$ and $H<\mathbb{A}{ }_{+}^{\mathbf{s}_{2}}(\mathbb{R})$, with $\mathbf{s}_{1} ; \boldsymbol{s}_{2} 2 \bar{S}_{+}$, and there exists 2 Di ${ }_{+}^{1}\left(\mathrm{~S}^{1}\right)$ such that $\mathrm{G}^{-1}=\mathrm{H}$, then $\mathbf{s}_{1}=\mathbf{s}_{2}$.

Proof Let G; H and be given. Note that $\mathbf{s}_{1}$ and $\mathbf{s}_{2}$ must have the same length 2d, since the global nite invariant sets of G and H must beisomorphic. Le $\mathrm{g} ; \mathrm{h}$ beelements of G and H with rotation number 0 such that $\mathrm{h}=\mathrm{g}^{-1}$. Since dilations have twice as many xed points in $\mathbb{R} P^{1}$ as translations, if $g$ is a rami ed lift of a translation, then so is $h$. Assume that $\left.g=\widehat{S( } s_{1} ; i d\right)$ and $h=\hat{f}\left(s_{2} ; i d\right)$, where $S: x \nabla x+s$ and $T: x \nabla x+t$ are translations with $\mathrm{s} ; \mathrm{t}>0$. Let $q_{1} ;::: ; q_{d}$ and $\left(q_{1}\right) ;::: ;\left(q_{d}\right)$ be the preimages of 1 under $s_{1}$ and $s_{2}$, respectively. In a neighborhood of $q$, the map $g$ is conjugate to $x \square\left(S(x)^{m_{i}}\right)^{1=m_{i}}$ and in a neighborhood of ( $q$ ), $h$ is conjugate to $x \bar{y}$ $\left(T(x)^{n_{i}}\right)^{1=n_{i}}$, where $m_{i}=s(q)$ and $n_{i}=s((q))$. Since $S$ is a $C^{2}$ contraction in a neighborhood of 1 and $T$ is conjugate to $S$, it follows from Lemma 4.6 that $m_{i}=n_{i}$ for $1 \quad i \quad d$, which implies that $\mathbf{s}_{\mathbf{1}}=\mathbf{s}_{\mathbf{2}}$.
Suppose instead that $g$ is a rami ed lift of a map in $A(\mathbb{R})$ conjugate to the dilation $D: x 7 a x$, for some $a>1$. Since $g$ must have $d$ xed points with derivative $a$, so must $h$, and so $h$ is also a rami ed lift of a map in $A(\mathbb{R})$ conjugate to D . Around 1 , the map D is a $\mathrm{C}^{2}$ contraction, and the same proof as above shows that $\mathbf{s}_{1}=\mathbf{s}_{2}$.

The proof in the orientation-preserving case is analogous.

Proof of Proposition 2.5 Let $n$ : $\mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ be the standard representation. Suppose that $\hat{n}\left(s_{1} ; h_{1}\right)$ and $\hat{n}\left(s_{2} ; h_{2}\right) 2 \mathrm{~V}$ are conjugate by
$2 \mathrm{Di}{ }^{1}\left(\mathrm{~S}^{1}\right)$, where $\mathbf{s}_{1} ; \mathbf{s}_{2} 2 \mathrm{~S}$. It follows from Corollary 4.7 that $\mathbf{s}_{1}=\mathbf{s}_{\mathbf{s}}$.
We next show $h_{1}=h_{2}$. Let $\gamma 2 B S(1 ; n)$ and let $k=n(\gamma)$. Let $k_{1}=$ $\widehat{k}\left(s_{1} ; h_{1}(\gamma)\right)$ and $k_{2}=\widehat{k}\left(s_{2} ; h_{2}(\gamma)\right)$ Then for all q2 $\mathbf{s}_{1}^{1}(1)$, we have:

$$
h_{1}(\gamma)(q)=k_{1}(q)=k_{2}((q))=h_{2}(\gamma)((q)) ;
$$

and for all e2 $\mathrm{E}\left({ }_{1}\right)$,

$$
h_{1}(\gamma)(e)=k_{1}(e)=k_{2}((e))=h_{2}(\gamma)((e)):
$$

Since $\left(s_{s_{1}}^{1}(1)\right)=\bar{s}_{1}^{1}(1)$ and $\left(E\left({ }_{1}\right)\right)=E\left({ }_{1}\right)$, it follows that $h_{1}(\gamma)=$ $h_{2}(\gamma)$. So $h_{1}=h_{2}$. Recall that each element $c_{n}(s ; h)$ of $V$ is given by a signature vector s $2 \overline{\mathrm{~S}}$ and a representative h of a conjugacy class in $\operatorname{Hom}\left(B S(1 ; n) ; \operatorname{Stab}_{D_{d}}(\mathbf{s})\right.$ ). So $h_{1}=h_{2}$.

## 5 Proof of Theorems 1.1 and 1.3

The construction behind this proof is very simple We are given a $\mathrm{C}^{r}$ representation of $\mathrm{BS}(1 ; \mathrm{n})$. Using elementary arguments, we are reduced to the case where $\mathrm{f}=$ (a) and $\mathrm{g}=$ (b) have a common nite invariant set, the set of periodic orbits of $g$. Assume that the rotation numbers of $f$ and $g$ are both 0 . Using the results from Section 3, we obtain a local characterization of $f$ and $g$ on the intervals between the common xed points. On each of these intervals, f is conjugate to the dilation $\times 7 \mathrm{nx}$ and g is conjugate to the translation $x \nabla x+1$. Gluing together the conjugating maps gives us a $C^{r}$ rami ed covering map over 1 . Hence is a $\mathrm{C}^{r}$ rami ed lift of the standard representation. Proposition 2.2 implies that there is a rational rami ed cover with the same signature as the the given $\mathrm{C}^{r}$ rami ed cover. Lemma 4.5 implies that is $\mathrm{C}^{r}$ conjugate to a rami ed lift of $n$ under the rational rami ed cover. It remains to handle the case where the rotation numbers of $f$ and $g$ are not 0 , but this is fairly simple to do, since the elements of the standard representation embed in analytic vector elds. We now give the complete proof.
Let : $\mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$ be a representation, where $\mathrm{r} 2[2 ; 1]$, or $\mathrm{r}=$ !. If $r<1$, assume that () $\frac{1}{n^{1}} \frac{1}{r-1}:$ If $r=1$, we assume that ()$<1$ :
Le $f=(a)$ and $g=(b)$, where $a b a^{-1}=b^{n}$. Since $g$ is conjugate to $g^{n}$, it follows that $(\mathrm{g})=\left(\mathrm{g}^{\mathrm{n}}\right)=\mathrm{n}(\mathrm{g})$, where $(\mathrm{h})$ denotes the rotation number of h 2 Homeo( $\mathrm{S}^{1}$ ). Hence g has rational rotation number.

Lemma 5.1 f preserves the set of periodic points of g .
Proof Thisfollows from thereation $\mathrm{f} g=\mathrm{g}^{\mathrm{n}} \mathrm{f}$. If $\mathrm{g}^{\mathrm{k}}(\mathrm{q})=\mathrm{q}$, then $\mathrm{g}^{\mathrm{nk}}(\mathrm{f}(\mathrm{q}))=$ $f g^{k}(q)=f(q)$. So $f(q)$ is also periodic for $g$.

Suppose that ( f ) is irrational. Then by Lemma 5.1, the periodic points of g are dense in $S^{1}$, which implies that $g^{k}=i d$, for some $k \quad n+1$. This implies that conclusion (1) of Theorem 1.1 holds.

Suppose, on the other hand, that (f) is rational. Choose I so that $\mathrm{g}^{\prime}$ and $f^{\prime}$ are both orientation-preserving and both have rotation number 0 . Then $f^{\prime}$ leaves Fix $\left(g^{\prime}\right)$ invariant. Choose p 2 Fix $\left(g^{\prime}\right)$. Any accumulation of $\mathrm{ff}^{\ln }(\mathrm{p}) \mathrm{g}$ must be a xed point for $f^{\prime}$ and for $g^{\prime}$. We have shown:

Lemma $5.2 f^{\prime}$ and $g^{\prime}$ have a common xed point.
Note that the xed points for $f^{\prime}$ are isolated; if $f$ is not analytic, then ( ) <1, which implies that the xed points for $\mathrm{f}^{\prime}$ are hyperbolic. Let $\mathrm{w}_{1}<\mathrm{w}_{2}<:::<$ $w_{k}$ be the set of xed points of $f^{\prime}$. We will see that if $g^{\prime}$ is not the identity map, then the set of xed points for $g^{\prime}$ is exactly equal to the set of sinks for $f^{1}$.

Lemma 5.3 If $g^{\prime}\left(w_{i}\right)=w_{i}$ and $\left(f^{\prime}\right)\left(w_{i}\right)>1$, then $g^{\prime}=i d$ on $\left[w_{i-1} ; w_{i+1}\right]$.
Proof Suppose that $\left(f^{\prime}\right) 9\left(w_{i}\right)=>1$, and let : $\left[w_{i} ; w_{i+1}\right)$ ! $[0 ; 1)$ be a
 Let $F=f^{1-1}$, and let $G=g^{1-1}$. If $g^{\prime} G$ id on $\left[w_{i} ; w_{i+1}\right)$, then there is a point $x_{0} 2[0 ; 1)$ such that $G\left(x_{0}\right) \in x_{0}$. Let $x_{0}$ be any such point. We may assume that $\mathrm{G}^{\mathrm{k}}\left(\mathrm{x}_{0}\right)$ ! c as k ! 1 , for some $\mathrm{c}<1$, because this will be true for either $G$ or $\mathrm{G}^{-1}$. Since $\mathrm{GF}{ }^{-\mathrm{k}}=\mathrm{F}^{-\mathrm{k}} \mathrm{G}^{\mathrm{n}^{k}}$ for all $\mathrm{k} 2 \mathbb{N}$, it follows that

$$
G^{q}\left(F^{-k}\left(x_{0}\right)\right)=\frac{\left.\left(F^{-k}\right)^{q} G^{n^{k}}\left(x_{0}\right)\right)}{\left(F^{-k}\right)^{q}\left(x_{0}\right)}\left(G^{n^{k}}\right)^{q}\left(x_{0}\right) ;
$$

for all $k 2 \mathbb{N}$. But since $G^{q}(0)=1$ (by Lemma 3.2), this means that $\left(G^{n^{k}}\right)^{9}\left(x_{0}\right)$ ! 1 , as $k!1$ (or $k$ ! -1 ), for every point $x_{0}$ that is not xed by G. Since $G$ is not the identity, this is not possible. Hence $g=i d$ on $\left[w_{i} ; w_{i+1}\right]$. A similar argument shows that $\mathrm{g}=\mathrm{id}$ on $\left[\mathrm{w}_{\mathrm{i}-1} ; \mathrm{w}_{\mathrm{i}}\right]$,

Corollary 5.4 If $g^{\prime}$ has a xed point in the interval $\left(w_{i} ; w_{i+1}\right)$, then $g^{\prime}=i d$ on [ $w_{i} ; w_{i+1}$ ]. That is, © $i x\left(g^{\prime}\right)$ Fix( $f^{l}$ ).

Proof Suppose that $g^{\prime}(p)=p$ for some $p 2\left(w_{i} ; w_{i+1}\right)$, and suppose that $f^{k l}(p)!w_{i}$ as $k!-1$. By Lemma 5.1, $f^{1 k}(p)$ is periodic for $g^{\prime}$ for all $k 2 \mathbb{Z}$. Since $g^{\prime}$ is an orientation preserving circle di eomorphism with a xed point, $f^{1 k}(p)$ is a xed point of $g^{\prime}$ for all $k$. By continuity, $w_{i}$ is a common xed point for $f^{\prime}$ and $g^{\prime}$. Since $\left(f^{\prime}\right)^{q}\left(w_{i}\right)>1$, Lemma 5.3 implies that $g^{\prime}=i d$ on $\left[w_{i} ; w_{i+1}\right]$. Similarly, if $f^{k l}(p)!w_{i+1}$ as $k!-1$, then $g=i d$ on $\left[w_{i} ; w_{i+1}\right]$.

This has the immediate corollary:
Corollary $5.5 \mathrm{f}^{\mathrm{l}}$ xes every component of $\mathrm{S}^{1} \mathrm{nFix}\left(\mathrm{g}^{\prime}\right)$.
Remark Corollary 5.5 also follows from Theorem 1.6. We have given a different proof here since we will need Lemma 5.3 for the proof of Lemma 5.6.
Let -1 $\quad q_{1}<q_{2} \ll q_{d}<1$ be the elements of © $i x\left(g^{\prime}\right)$.
Lemma 5.6 On each interval $\left(q_{-1} ; q^{\prime}\right.$ ], either $g^{\prime}=i d$, or there is a $C^{r}$ map $i$ : ( $q-1 ; q]$ ! ( $-1 ; 1$ ] such that
(1) i conjugates $\mathrm{f}^{\prime}$ to the map $\times \mathrm{V}^{\mathrm{D}} \mathrm{n}^{\prime} \mathrm{x}$, and conjugates $\mathrm{g}^{\prime}$ to the map $x 7 x+1 ;$
(2) ${ }^{i}{ }_{\left(\mathrm{q}_{-1} ; \mathrm{q}_{)}\right)}$is a $\mathrm{C}^{r}$ di eomorphism onto $(-1 ; 1)$
(3) For all $p$ in a neighborhood of $q$,

$$
i(p)=o_{i} h(p)^{s}
$$

where h is a $\mathrm{C}^{r}$ orientation-preserving di eomorphism onto a neighborhood of $1,1 \mathrm{~s}<\mathrm{r}$, and of 2 f 1 g .

Proof This follows from Proposition 3.1. Note that we can apply Proposition 3.1 in this setting since we know that if $g^{\prime} \in$ id on ( $\left.q-1 ; q\right]$, then ( $\left.f^{\prime}\right)^{9}(q) \quad 1$ (by Lemma 5.3). By our assumptions on (), if $2 r<1$, then $\left(f^{\prime}\right)^{9}(q) \quad\left(\frac{1}{n}\right)^{\frac{1}{r-1}}$, and if $r=1$, then $\left(f^{l}\right)^{\prime}(q)<1$. Therefore one of the assumptions (A) \{(C) of Proposition 3.1 will hold.

Corollary 5.7 Either $g^{\prime}=i d$, or © $\mathrm{ix}\left(\mathrm{g}^{\prime}\right)=\mathrm{Fix}\left(\mathrm{g}^{\prime}\right)=\mathrm{fq}_{\mathrm{q}} ;::: ; \mathrm{q}_{\mathrm{d}} \mathrm{g}$ :
Proof Assume that $\oint^{F i x}\left(g^{\prime}\right)=\mathrm{fq}_{1} ;::: ; q_{\mathrm{d}} g \in \operatorname{Fix}\left(\mathrm{~g}^{\prime}\right)$, but $\mathrm{g}^{\prime} \in$ id. Then there is an interval $\left[q-1 ; q\right.$ ] on which $g^{\prime}=i d$ but where $g^{\prime} G i d$ on $[q ; q+1]$. By Lemma 3.4, either $g^{\prime}$ or $g^{-1}$ is $\mathrm{C}^{r}$ conjugate in a neighborhood $[q ; p)$ to the map $x \square x=\left(1-x^{5}\right)^{\frac{1}{s}}$ for some integer $1 \quad s<r$. But this map is not $r$ flat at $x=0$, so $g^{\prime}$ is not $C^{r}$ at $q$, a contradiction.

Corollary 5.8 If $g^{\prime} \in$ id, then the map : $S^{1}!\mathbb{R P}^{1}$ de ned by:
$(p)=i(p)$; for $p 2(q-1 ; q]$
is a $C^{r}$ rami ed covering map over $1, f^{1}$ is a \{rami ed lift of $x \nabla^{\prime} x$, and $g^{\prime}$ is a $\{r a m i$ ed lift of the map $\times 7 \times+1$.

Proof Let $q 2$ Fix $\left(g^{\prime}\right)$. Applying Lemma 5.6 to the interval $\left[q ; q_{+1}\right)$, we obtain a map $-_{i+1}:\left(q_{;} ; q_{+1}\right)![-1 ; 1)$ which is a $C^{r}$ di eomorphism on $\left(q ; q_{+1}\right)$, and which is a power of a $C^{r}$ di eomorphism in a (right) neighborhood of $q ;{ }_{i+1}(p)=h(p)^{s}$ for $p$ near $q$, for some $C^{r}$ di eomorphism $h$ and some integer $1 \quad s<r$. Similarly, on the interval ( $q-1 ; q$ ] there is a map $i:\left(q_{-1} ; q\right]!(1 ;-1]$ which is a power of a di eomorphism in a (left) neighborhood of $q ; i(p)=h(p)^{s}$ near $q$. We will show that $s=s$, and that the di eomorphisms $h$ and $h$ glue together to give a $\mathrm{C}^{r}$ di eomorphism in a neighborhood of $q$. This will prove that the map

$$
i(p)=\begin{array}{cc}
i(p) ; & \text { for } p 2(q-1 ; q] \\
-i+1(p) ; & \text { for } p 2[q ; q+1)
\end{array}
$$

is the restriction to $\left(q_{-1} ; q_{+1}\right)$ of a $C^{r}$ rami ed covering map over 1 . By construction, the restrictions of $f^{\prime}$ and $g^{\prime}$ to $\left(q_{-1} ; q_{+1}\right)$ are $i\{r a m i$ ed lifts of the maps $\times 7 n^{\prime} \times$ and $\times 7 \times+1$ respectively.

The di eomorphism $1=1$ maps $q$ to 0 , and conjugates $g$ to the map $\times 7$ $\left.x \neq 1+x^{5}\right)^{1=5}$. Similarly, $1=h$ conjugates $g^{\prime}$ to $x \quad x=\left(1+x^{5}\right)^{1=5}$. Since $g$ is $C^{r}$, we must have $s=s$. Both $1=h$ and $l=h$ are linearizing maps for $f^{1}$ at $q_{i}$, and it is not hard to see that they de ne a $C^{r}$ di eomorphism $H$ in a neighborhood of $q$. Therefore $h$ and $h$ glue together to give a $C^{r}$ di eomorphism $1=H$ in a neighborhood of $q$.
It remains to show that $i={ }_{i+1}$ on $\left(q_{i} ; q_{+1}\right)$. Since the restriction of both of these maps to ( $q ; q_{+1}$ ) are di eomorphisms which linearize $f^{\prime}$, they are the same up to a constant multiple. There is a unique point $x_{0} 2\left(q_{-1} ; q\right)$ satisfying $f^{\prime}\left(x_{0}\right)=g^{n^{\prime}-1}\left(x_{0}\right)$; $\left\{\right.$ this is the point $x_{0}=g^{\prime}(y)$, where $y$ is the unique xed point for $f^{1}$ in $\left(q ; q_{+1}\right)$. Both $i$ and $i+1$ send the point $x_{0}$ to the same point $12 \mathbb{R}$. So we have $i=i+1$ on $(q ; q+1)$.

It follows from Lemma 4.5 that the representation of $\mathrm{BS}\left(1 ; \mathrm{n}^{\prime}\right)$ generated by $\mathrm{f}^{\prime}$ and $g^{1}$ is $\mathrm{C}^{r}$ conjugate to an element of V . In the remainder of this section, we will show that the di eomorphisms $f$ and $g$ are $C^{r}$ rami ed lifts of the generators of the standard action of $\mathrm{BS}(1 ; n)$ on $\mathrm{S}^{1}$, hence the representation they generate is also $\mathrm{C}^{r}$ conjugate to an element of V . We begin with some lemmas about rami ed lifts of flows on $\mathrm{S}^{1}$.

Lemma 5.9 Let $^{\prime}: S^{1}$ ! $S^{1}$ bea $C^{r}$ flow with a xed point at $p$, and let : $S^{1}$ ! $S^{1}$ be a $C^{r}$ rami ed covering map over $p$. Let $F={ }^{C 1}($;id) be the $\left\{\right.$ rami ed lift of the time 1 map ' ${ }^{1}$ with rotation number zero. Then $F$ embeds as the time 1 map of a $\mathrm{C}^{r}$ flow $\mathrm{F}^{\mathrm{t}}$ on $\mathrm{S}^{1}$, and for all $\mathrm{t} 2 \mathbb{R}$, $F^{t}=\mathrm{b}_{( }(; \mathrm{id})$.

Proof By Lemma 4.2, given any $\mathrm{t} 2 \mathbb{R}$ there is a unique ( ; id) - rami ed lift of ${ }^{\prime}, F^{t}:={ }^{\prime}(; i d)$. Lemma 4.3 imples that $F^{t} F^{s}=F^{s+t}=F^{s} \quad F^{t}$ for all s; $\mathrm{t} 2 \mathbb{R}$.
Let $X$ be the $C^{r-1}$ vector eld that generates ', and let $\hat{X}$ be the lift of $X$ under. This vector eld is clearly $\mathrm{C}^{r-1}$ on $\mathrm{S}^{1} \mathrm{n}^{-1}(\mathrm{p})$ and dearly generates the flow $\mathrm{F}^{\mathrm{t}}$ on $\mathrm{S}^{1}$. In a neighborhood of $\mathrm{q} 2^{-1}(\mathrm{p}), \hat{X}$ takes the form

$$
\widehat{X}(q)=d_{(q)}{ }^{-1} X(q) ;
$$

and takes the form $(x)=x^{s}$ : A straightforward calculation shows that the vector dd $\widehat{X}$ is $\mathrm{C}^{r-1}$. Similarly, $\widehat{X}$ is analytic if $X$ and are. This completes the proof.

Lemma 5.10 Let $F$ : $S^{1}$ ! $S^{1}$ be the time 1 map of a $C^{r}$ flow $F^{t}$, where $r$ 2. Suppose that $F$ is not $r$ fflat, and $(F)=0$. If $G$ is a $C^{r}$ orientation preserving di eomorphism such that $F G=G F$, and if $(G)=0$, then $G=F^{t}$ for some $\mathrm{t} 2 \mathbb{R}$.

Proof Since $(F)=0$ and $F$ is not $r$ flat, $F$ has a nite set of xed points. Le $q_{1}<:::<q_{d}$ be the elements of $\operatorname{Fix}(F)$. If $F G=G F$, then $G$ permutes the xed points of $F$, and since $G$ is orientation preserving and has rotation number zero, $G\left(\left[q ; q_{+1}\right]\right)=\left[q ; q_{+1}\right]$ for all $q 2$ Fix( $F$ ). By Lemma 3.7, on $\left[q ; q_{+1}\right), G=F^{t_{i}}$ for some $t_{i} 2 \mathbb{R}$, and on $\left(q ; q_{+1}\right], G=F^{s_{i}}$ for some $s_{i}$. Clearly, $t_{i}=s_{i}$. So for 1 i d,

$$
\mathrm{Gj}_{\left[q ; q_{+1}\right]}=\mathrm{F}_{\mathrm{t}} ; \text { for some } \mathrm{t}_{\mathrm{i}} 2 \mathbb{R} \text { : }
$$

If $F^{q}(q) \in 1$ for some $q 2 \operatorname{Fix}^{(F)}$, then since $G$ is $C^{1}$ at $q$, it follows that $t_{i}=t_{i-1}$. If $F^{q}(q)=1$, then in local coordinates, identifying $q$ with 0 ,

$$
F(x)=F^{1}(x)=x+a x^{k}+o\left(x^{k}\right)
$$

for some $a \in 0$ and $k$ ( $r$. Therefore

$$
G(x)=\begin{array}{ll}
x+t_{i-1} a x^{k}+o\left(x^{k}\right) ; & \text { for } \times 2(q-1 ; q] \\
x+t_{i} a x^{k}+o\left(x^{k}\right) ; & \text { for } \times 2\left[q ; q_{+1}\right):
\end{array}
$$

Since $k \quad r$ and $G$ is $C^{r}$, $t_{i}=t_{i-1}$.

Corollary 5.11 Let : $S^{1}!S^{1}$ be a $C^{r}$ rami ed covering map over 1 , and let $F=\widehat{k}(; i d)$ be the ( ;id) \{rami ed lift of $k 2 A(\mathbb{R}), k \in i d$. Let $\mathbf{s}()=\left(s_{1} ;::: ; \mathrm{s}_{\mathrm{d}} ; \mathrm{o}_{\mathrm{i}} ;::: ; \mathrm{o}_{\mathrm{d}}\right)$, where $\mathrm{s}_{\mathrm{i}} \mathrm{r}-1$ for 1 i d. By Lemma 5.9, F embeds as the time 1 map of a $C^{r}$ flow $\mathrm{F}^{\mathrm{t}}$. If $\mathrm{H}: \mathrm{S}^{1}!\mathrm{S}^{1}$ is a $\mathrm{C}^{r}$ orientation preserving di eomorphism such that $\mathrm{FH}=\mathrm{HF}$, and if $(\mathrm{H})=0$, then $\mathrm{H}=\mathrm{F}^{\mathrm{t}}$ for some $t 2 \mathbb{R}$.

Proof By Lemma 5.10, it is enough to show that F is not r \{flat. In coordinates identifying a xed point with 0 ,

$$
F(x)=\frac{x}{\left(b+a x^{s}\right)^{\frac{1}{s}}} ;
$$

where either $a \in 1$ or $b \in 0$, which is clearly not $r$ fflat, if $s<r$.
Proposition 5.12 Let $\mathrm{F} 2 \mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$ be a di eomorphism such that $\mathrm{F}^{\prime}$ is orientation-preserving and $\left(F^{\prime}\right)=0$, for some $I>0$. Suppose that $F^{\prime}=$ $k^{(2)}$; id) is a $C^{r}$ rami ed lift of $k^{\prime} \in i d$, where $k 2 A+(\mathbb{R})$, and suppose that $\mathbf{s}()=\left(s\left(q_{1}\right) ;::: ; s\left(q_{d}\right) ; o_{1} ;::: ; o_{d}\right)$, where $s(q) \quad r-1$ for $1 \quad i \quad d$. Then either $F$ is a \{rami ed lift of $k$ or $F$ is a \{rami ed lift of $-k$.

Proof Let $2 D_{d}$ be such that $(q)=F(q)$ for all $q 2^{-1}(1)$, and (e) $=$ $F(e)$ for all e $2 E()$.

Lemma 5.13 $2 \operatorname{Stab}_{D_{d}}^{\#}(\mathbf{s}())$.
Proof Given any q $2^{-1}(1)$, there is an interval $[q ; p)$ and $C^{r}$ di eomorphisms $h_{1}:[q ; p)![0 ; 1)$ and $h_{2}:[F(q) ; F(p))![0 ; 1)$ such that

$$
h_{1} F^{\prime} h_{1}^{-1}(x)=\left[k^{\prime}\left(x^{s}\right)\right]^{\frac{1}{5}} ; \quad \text { and } \quad h_{2} F^{\prime} h_{2}^{-1}(x)=\left[k^{\prime}\left(x^{t}\right)\right]^{\frac{1}{t}} ;
$$

where $s=s(q)$ and $t=s(F(q))$. We can assume that $k^{\prime}$ is a contraction on $\left[0 ; 1\right.$ ). (If not, then use $k^{-1}$ and $F^{-1}$ ). Since $F^{1} \mathrm{j}_{(\text {qq; })}$ is conjugate by $F$ to $\mathrm{F}^{1} \mathrm{j}_{\mathrm{IF}}(\mathrm{q}) ; \mathrm{F}(\mathrm{p})$ ), Lemma 4.6 implies that $\mathrm{s}(\mathrm{q})=\mathrm{s}(\mathrm{F}(\mathrm{q}))$, and therefore 2 $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}^{\#}(\mathbf{s}())$.

By Lemma 5.13, either $(\mathbf{s}())=\mathbf{s}()$, or $(\mathbf{s}())=\mathrm{I}(\mathbf{s}(\mathrm{)})$. If $(\mathbf{s}())=$ $\mathbf{S}()$, then let : $\mathrm{S}^{1}$ ! $\mathrm{S}^{1}$ be the (; ) \{rami ed lift of the identity map: = ied ; ). By Lemma 4.3, commutes with $\mathrm{F}^{1}$. So $\mathrm{F}^{-1}$ commutes with $F^{1}$, and by construction, $F^{-1}$ xes every interval $(q ; q+1) \quad{ }^{-1}\left(\mathbb{R}^{1} P^{1} n f \mathrm{~g}\right)$. By Lemma 5.10, $\mathrm{F}^{\mathrm{l}}$ embeds as the time 1 map of a $\mathrm{C}^{r}$ flow, $\mathrm{F}^{\mathrm{t}}$, and $\mathrm{F}^{-1}=$
$\mathrm{F}^{\mathrm{t}_{0}}=\mathrm{Ct}_{0}(; i d)$ for some $\mathrm{t}_{0} 2 \mathbb{R}$, where is an analytic flow with ${ }^{1}=\mathrm{k}^{\prime}$. Therefore $\mathrm{F}=\mathrm{Ct}_{0}$ ( ; id) $i \notin\left(\mathrm{~A}(\mathrm{i})=\mathrm{Ct}_{0}(;)\right.$ (using Lemma 4.3). It follows that $t_{0}=1 \neq$, and therefore $F$ is the $(;)$ \{rami ed lift of the map $k$.

If $(\mathbf{s}())=I(s())$, then we let $=d_{i d}(;)$, the $(;)$ rami ed lift of -id: $x!-x$. As above, $F^{-1}$ is the ( ; ) \{rami ed lift of $k$, and therefore $F=t=\varepsilon_{k}(;)$.

C orollary 5.14 f and $g$ are $C^{r}$ rami ed lifts under of the generators of the standard action of $B S(1 ; n)$ on $S^{1}$.

Proof The standard representation ${ }_{n}: B S\left(1 ; n^{\prime}\right)!~ D i \quad\left(\mathbb{R P}^{1}\right)$ is analytically conjugate to the representation $: B S\left(1 ; n^{l}\right)!~ D i!\left(\mathbb{R P}^{1}\right)$ with generators $\left(a^{\prime}\right): x \square n^{\prime} x$ and $(b): x \nabla x+1$. So there is a $C^{r}$ rami ed covering map : $S^{1}!S^{1}$ over $p$ such that $f^{\prime}=\widehat{\left(a^{l}\right)}(; i d)$ and $g^{\prime}=\widehat{(b)}(; i d)$. By Proposition 5.12, either $f$ is a rami ed lift of $n(a): x \square n x$, or $f$ is a rami ed lift of $-{ }_{n}(a): x \nabla-n x$. Similarly, $g$ is either a rami ed lift of $n(b): \times \nabla \times+1$, or a rami ed lift of $-{ }_{n}(b): x \nabla-x-1$. Since $f$ and $g$ satisfy the relation $\mathrm{f} \mathrm{gf}^{-1}=\mathrm{g}^{n}$, the maps that they are lifted from must also satisfy this relation. Given this requirement, the only possibility is that $f$ is a \{rami ed lift of $n(a)$ and $g$ is a $\{r a m i$ ed lift of $n(b)$.

Sincethe generators $(a)=f$ and $(b)=g$ of the representation are rami ed lifts under of the generators $n(a)$ and $n(b)$, respectively, of $n$, it follows that, for every $\gamma 2 B S(1 ; n)$, there exists a unique $h(\gamma) 2 D_{d}$ (or in $C_{d}$ if is orientation-preserving) such that:

$$
(\gamma)=\widehat{n(\gamma)} ; h(\gamma)):
$$

Since $\left(\gamma_{1} \gamma_{2}\right)=\left(\gamma_{1}\right)\left(\gamma_{2}\right)$, it follows that $h: B S(1 ; n)!D_{d}\left(C_{d}\right)$ is a homomorphism. Finally, note that $h$ must take values in $\operatorname{Stab}_{\mathrm{D}_{\mathrm{d}}}(\mathbf{s})$ (or $\operatorname{Stab}_{\mathrm{C}_{\mathrm{d}}}(\mathbf{s})$, if is orientation-preserving).

This concludes the proof of Theorems 1.1 and 1.3.

Finally, we sketch the proof of Theorem 1.6.
Sketch of proof of Theorem 1.6 Let bea $C^{r}$ representation of $B S(1 ; n)$, with $r$ 2, let $f=(a)$ and $g=$ (b). We may assume that $f$ has rational rotation number. By taking powers of the elements of $B S(1 ; n)$, we may assume
that both f and g have rotation number 0 . Assume that g is not the identity map.

Let J be a component of the complement of Fix(g). Using a distortion estimate and the group relation one shows that J must be xed by f, as follows. Otherwise, the $f$ \{orbit of J must accumulate at both ends on a xed point of $f$. The standard $C^{2}$ distortion estimate shows that there is an $M>1$ such that for all $x$; $y$ in same component of the $f$ \{orbit of J, and for all $k 2 \mathbb{Z}$,

$$
\frac{1}{M}<j \frac{\left(f^{k}\right)^{q}(x)}{\left(f^{k}\right)^{q}(y)} j<M:
$$

But, for all k 2 N , we have that $f^{\mathrm{k}} \mathrm{gf}^{-\mathrm{k}}=\mathrm{g}^{\mathrm{n}^{\mathrm{k}}}$. Hence, for all p2 J, we have:

$$
\left(g^{n^{k}}\right)^{q}(p)=g^{q}(y) \frac{\left.\left(f^{k}\right) q g(y)\right)}{\left.\left(f^{k}\right) q^{\prime} y\right)} ;
$$

where $y=f^{-k}(p)$. Note that $y$ and $g(y)$ lie in the same component $f^{-k}(J)$, and $g^{9}(y)$ is uniformly bounded. This implies that for all p2 J and all $k 2 \mathbb{N}$, $\left(g^{n^{k}}\right){ }^{9}(\mathrm{p})$ is bounded, so that $\mathrm{g}=\mathrm{id}$ on J, a contradiction.
So f xes each component of the complement of Fix(g). Let J be such a component. Since $g$ has no xed points on J, $g$ embeds in a $\mathrm{C}^{1}$ flow $\mathrm{g}^{\mathrm{t}}$, de ned on J minus one of its endpoints, that is $\mathrm{C}^{r}$ in theinterior of J (see, eg [16]). Furthermore, for all $\mathrm{t}, \mathrm{fg}^{\mathrm{t}} \mathrm{f}^{-1}=\mathrm{g}^{\text {nt }}$ (this follows from K opell's lemma). Fixing some point $p$ in the interior of J, this flow de nes a $\mathrm{C}^{r}$ di eomorphism between the real line and the interior of J, sending t $2 \mathbb{R}$ to $g^{t}(p) 2 J$. Conjugating by this di eomorphism, $g^{t}$ is sent to a translation by t , and f is sent to a di eomorphism $F$ satisfying $F(x+t)=F(x)+t n$, for all $t ; x 2 \mathbb{R}$. But this means that $\mathrm{F}^{9}(\mathrm{x})=\mathrm{n}$ for all $\mathrm{x} 2 \mathbb{R}$. Up to an a ne change of coordinates, $g$ is conjugate on $J$ to $x \nabla x+1$ and $f$ is conjugate to $\times 7 n x$.

## 6 Proof of Proposition 1.5

Let : $\mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}^{!}\left(\mathrm{S}^{1}\right)$ be a \{rami ed lift of the standard representation $n$ with ()$=\frac{1}{n}^{\frac{1}{r-1}}$, for some $r \quad$ 2. Let $Q$ be the set of all points $q 2^{-1}(1)$ satisfying $s(q)=r-1$; this set is nonempty since ()$=\frac{1}{n^{\frac{1}{r-1}}}$. Lemma 4.1 implies that, in a neighborhood of $q$ : $x \nabla x^{r-1}$, in the appropriate coordinates identifying $q$ with 0 .
For $\mathrm{t} 2(-1 ; 1)$ we deform to obtain a $\mathrm{C}^{r-1+\mathrm{t}^{2}}$ map $\mathrm{t}: \mathrm{S}^{1}!\mathrm{S}^{1}$ with the following properties:
$0=$ and ${ }^{-1}(1)=t^{-1}(1)$, for all $t$;
$\mathrm{t}_{\mathrm{S}^{1} \mathrm{n} \mathrm{t}^{-1}(1)}$ is a $\mathrm{C}^{1}$ covering map onto its image;
about each q2 ${ }^{-1}(1) n Q, t$ is locally equal to ;
about each $q 2 \mathrm{Q}, \mathrm{t}$ is locally $\mathrm{x} 7 \mathrm{x}^{\mathrm{r}-1+\mathrm{t}^{2}}$, in the same charts identifying $q$ with 0 described above.
A slight modi cation of the proof of Proposition 4.4 also shows that ${ }_{n}$ has a lift to a $\mathrm{C}^{r}$ representation $\mathrm{t}: \mathrm{BS}(1 ; \mathrm{n})$ ! $\mathrm{Di}^{r}\left(\mathrm{~S}^{1}\right)$ so that the following diagram commutes, for all ү $2 B S(1 ; n)$ :

(One merely needs to check that the integer j in the proof of Lemma 4.2 can be replaced by the real number $\left.r-1+t^{2}\right)$.
Notice that t has the property that $(\mathrm{t})=\frac{1}{n} \frac{1}{\mathrm{r}-1+\mathrm{t}^{2}}$, so that s is not $\mathrm{C}^{1}$ conjugate to t unles $\mathrm{s}=\mathrm{t}$. One can further modify this construction by replacing the points of $Q$ by intervals of length " $t$, extending ${ }_{t}(b)$ isometrically across these intervals, and extending $\mathrm{t}(\mathrm{a})$ in an arbitrary $\mathrm{C}^{r}$ fashion to these intervals. Since $t(b)$ is $r$ flat (by Lemma 3.2) on $Q$ for $t \in 0$ and $r-1$ flat for $\mathrm{t}=0$, the representation t is $\mathrm{C}^{r}$ and varies $\mathrm{C}^{\mathrm{r}-1}$ continuously in t if we choose " t ! 0 as t ! 0 . In this way, one can create uncountably many deformations of . (Note that, in essence, we have deformed to obtain a \broken $\mathrm{C}^{r}$ rami ed cover" a la Theorem 1.6).

## 7 Proof of Theorem 1.9

Let r 2 fl ;! g, and let $\mathrm{G}<\operatorname{Di}^{r}\left(\mathrm{~S}^{1}\right)$ be a solvable group without in nitely flat elements. Suppose that $\mathrm{G}^{\mathrm{m}}:=\mathrm{fg}^{\mathrm{m}}: \mathrm{g} 2 \mathrm{Gg}$ is not abelian, for any $\mathrm{m} 2 \mathbb{Z}$. We begin by showing that the group $\mathrm{G}^{2}<\mathrm{Di}^{\mathrm{r}}\left(\mathrm{S}^{1}\right)$ has a nite set of points that is globally invariant.

Lemma 7.1 $\mathrm{G}^{2}$ contains a non-trivial normal abelian subgroup N , such that N contains an element of in nite order. There is an integer $\mathrm{d}>0$, and a nite set $\mathrm{fq}_{1} ;::: ; q_{\mathrm{d}} \mathrm{g}$, with $q_{1}<q_{2} \ll q_{d}$, such that:
(1) for all f $2 G^{2},\left(f^{d}\right)=0$ and $f f_{1} ;::: ; q_{d} g=f q_{1} ;::: ; q_{d} g ;$
(2) for all $g 2 \mathrm{~N}$, either $g^{d}=i d$ or $\operatorname{Fix}\left(g^{d}\right)=f_{q_{1}} ;::: ; q_{d} g$.

Proof Note that $G^{2}$ is a solvable group, and every di eomorphism in $G^{2}$ is orientation preserving. Let

$$
\mathrm{G}^{2}=\mathrm{G}_{0}>\mathrm{G}_{1}>:::>\mathrm{G}_{\mathrm{n}}>\mathrm{G}_{\mathrm{n}+1}=\mathrm{fidg}
$$

be the derived series for $\mathrm{G}^{2}$, and let $\mathrm{N}=\mathrm{G}_{\mathrm{n}}$ be the terminal subgroup in this series. Recall that N is a normal abelian subgroup of $\mathrm{G}^{2}$. We rst show that N contains an element of in nite order. We will use the following result of Ghys ([7] Proposition 6.17):

Lemma 7.2 If H $\operatorname{Homeo}_{+}\left(\mathrm{S}^{1}\right)$ is solvable, then the rotation number : H $!\mathbb{R}=\mathbb{Z}$ is a homomorphism.

Suppose that every di eomorphism in $N$ has nite order. Since $G^{2} G N$ (because $G^{2}$ is not abelian), $G_{n-1}$ cannot beabelian $\left\{\right.$ if it were, then $G_{n}$ would be trivial. Suppose that $f ; h 2 G_{n-1}$. By Lemma 7.2, ( $\mathrm{f}_{\mathrm{hf}}{ }^{-1} \mathrm{~h}^{-1}$ ) $=0$. But $f \mathrm{hf}^{-1} \mathrm{~h}^{-1}$ is orientation preserving and has nite order, since $\mathrm{f} \mathrm{hf}^{-1} \mathrm{~h}^{-1} 2 \mathrm{G}_{\mathrm{n}}$. Therefore $\mathrm{ff}{ }^{-1} \mathrm{~h}^{-1}=\mathrm{id}$, and $\mathrm{G}_{\mathrm{n}-1}$ is abelian, a contradiction. So N contains a di eomorphism with in nite order.

If ( g ) is irrational, for some orientation-preserving g 2 N , then the elements of N are simultaneously conjugate to rotations. But, since N is normal in $\mathrm{G}^{2}$, this implies that the elements of $\mathrm{G}^{2}$ are simultanously conjugate to rotations, which implies that $\mathrm{G}^{2}$ is abelian, a contradiction.

Hence (g) $2 \mathbb{Q}=\mathbb{Z}$, for every g 2 N . Note that every g 2 N either has nite order, or a nite set of periodic points: if Fix( $g^{\prime}$ ) is in nite, for some integer $I \in 0$, then there is a point q $2 \mathrm{Fix}\left(\mathrm{g}^{\prime}\right)$ that is an accumulation point for a sequence fqg $\operatorname{Fix}\left(g^{\prime}\right)$. But this implies that $g^{l}$ is in nitely flat at $q$, and therefore $\mathrm{g}^{\mathrm{l}}=\mathrm{id}$.

Hence there exists g 2 N with in nite order and a nite xed set, $\mathrm{Fix}(\mathrm{g})=$ $f_{q_{1}} ;::: ; q_{d} g$. If $h 2 N$ is another element of $N$, then, since $h$ commutes with $g$, it follows that $h\left(f q_{1} ;::: ; q_{d} g\right)=f q_{1} ;::: ; q_{d} g$, and so $\left(h^{d}\right)=0$. If the set of $x e d$ points for $h^{d}$ is in nite, then $h^{d}=i d$, and if Fix( $h^{d}$ ) is nite, then $F i x\left(h^{d}\right)=f_{q_{1}} ;::: ; q_{d} g$.

Finally, let $f 2 G^{2} n N$ and pick $g 2 N$ satisfying $F i x(g)=f q_{1} ;::: ; q_{d} g$. Then there exists ag2 2 N such that $\mathrm{fg} \mathrm{f}^{-1}=\mathrm{g}$. This implies that $\mathrm{f}(\mathrm{Fix}(\mathrm{g}))=$ Fix(g) ; that is, $f\left(f q_{1} ;::: ; q_{d} g\right)=f q_{1} ;::: ; q_{d} g$. It follows that $\left(f^{d}\right)=0$. This completes the proof.

Let $\mathrm{fq}_{1} ;::: ; q_{d} g$ be given by the previous lemma, labelled so that $-1 \quad q_{1}<$ $\mathrm{q}_{\mathrm{z}} \ll \mathrm{q}_{\mathrm{d}}<1$, and let $\mathrm{I}=2 \mathrm{~d}$. We will begin by working with the group $\mathrm{G}^{\prime}$. Note that every $\mathrm{g} 2 \mathrm{G}^{\prime}$ is orientation-preserving, has zero rotation number, and xes every point in the set $f q_{1} ;::: ; q_{d} g$. Throughout this section, we will be working on the intervals $\left(q ; q_{+1}\right)$, where we adopt the convention that $q_{d+1}=q_{1}$.

Let $M$ bea normal abelian subgroup of $G^{l}$ which contains an element of in nite order. For the rest of the proof, $x$ a di eomorphism $g 2 M$ which has in nite order.

Lemma 7.3 Let $\mathrm{C}(\mathrm{g})=\mathrm{ff} 2 \mathrm{G}^{\prime} \mathrm{j} \mathrm{gf}=\mathrm{fgg}$. Then $\mathrm{C}(\mathrm{g}) \in \mathrm{G}^{\prime}$.

Proof A proof of this lemma is essentially contained in [5]. This lemma is implied by the following theorem, which is classical.

Theorem 7.4 (Hölder's Theorem) If a group of homomorphisms acts freely on $\mathbb{R}$, then it is abelian.

If $\mathrm{f} 2 \mathrm{C}(\mathrm{g})$, then $\operatorname{Fix}(\mathrm{f})=\mathrm{Fix}(\mathrm{g})$. So on every interval $\left(\mathrm{q} ; \mathrm{q}_{+1}\right)$, 1 i d, no element of $\mathrm{C}(\mathrm{g})$ has a xed point. By Theorem 7.4, the restriction of the action of $C(g)$ to each interval $\left(q ; q_{+1}\right)$ is abelian. Since $f(q)=q$ for all $\mathrm{f} 2 \mathrm{C}(\mathrm{g})$ and for all q $2 \operatorname{Fix}(\mathrm{~g}), \mathrm{C}(\mathrm{g})$ is an abelian subset of $\mathrm{G}^{\prime}$. But $\mathrm{G}^{1}$ is not abelian, so $C(g) \in G^{\prime}$.

Lemma 7.5 Let f $2 \mathrm{G}^{\prime} \mathrm{nC}(\mathrm{g})$. Then for every interval ( $\mathrm{q}_{-1} ; \mathrm{q}$ ] there is a positive real number $;$ and a $C^{r}$ map $i:\left(q_{-1} ; q_{i}\right]!\mathbb{R} P^{1}$ with thefollowing properties:
(1) $i g(p)=i(p)+1$ and $i f(p)=i \quad i(p)$;
(2) $\mathrm{i}_{\left(\mathrm{q}_{-1} ; \mathrm{q}_{1}\right)}$ is a $\mathrm{C}^{r}$ di eomorphism onto ( $-1 ; 1$ );
(3) there is an orientation-preserving $\mathrm{C}^{r}$ di eomorphism $\mathrm{h}_{\mathrm{i}}$ from a neighborhood of $q$ to a neighborhood of 1 and integers $s_{i} 2 f 1 ;:: ; r-1 g$, $\mathrm{o}_{\mathrm{i}} 2 \mathrm{f} 1 \mathrm{~g}$, such that, for all p in this neighborhood:

$$
i(p)=o_{i} h_{i}(p)^{s_{i}}
$$

The same conclusions hold, with the same $i, o_{i}$ and $i_{\left(\mathrm{q}_{-1} ; q_{i}\right)}$, but di erent local (orientation-reversing) di eomorphism $h_{i}$ and integer $s_{i}$, when $q$ is replaced by $q_{-1}$ and the interval ( $\left.q_{-1} ; q_{i}\right]$ is replaced by $\left[q_{-1} ; q^{\prime}\right.$ ).

Remark To ensure that the conditions i>0(as opposed to i $\mathcal{G}$ ) hold in Lemma 7.5, it is necessary that we chose I to be even.

Proof We use the following fact, proved by Takens:
Theorem 7.6 ([15], Theorem 4) Le $h:[0 ; 1)![0 ; 1)$ be a $C^{1}$ di eomorphism with unique xed point $02[0 ; 1)$. If $h$ is not in nitely flat, then there exists a unique $C^{1}$ vector eld $X$ on $[0 ; 1)$ such that $h=h^{1}$, where $h^{t}$ is the flow generated by X .

For each 1 i $d$, Let $g_{i}^{\text {t }}:\left(q_{-1} ; q^{\prime}\right]$ ! $\left(q_{-1} ; q_{1}\right]$ be the flow given by this theorem with $\mathrm{g}_{1}^{1}=\mathrm{gj}_{\left(\mathrm{q}_{-1} ; \mathrm{q}^{\prime}\right]}$. If $\mathrm{f} 2 \mathrm{G}^{\mathrm{n}} \mathrm{nC}(\mathrm{g})$, then since g 2 M , we have $\mathrm{f} \mathrm{gf}^{-1} 2 \mathrm{M}$, and therefore $\mathrm{f} \mathrm{gf}^{-1} 2 \mathrm{C}(\mathrm{g})$. By Lemma 3.7, for $1 \quad \mathrm{i}$ d, we must have

$$
\mathrm{f} \mathrm{gf}^{-1}=\mathrm{g}_{\mathrm{i}}{ }^{i}
$$

on ( $q_{-1} ; q$ ], for some ; $2 \mathbb{R} n f 0 g, \quad \mathfrak{G}$. Note that, because I is even, must be positive, for all i. So assumption (D) of Section 3 holds in the interval ( $q_{-1} ; q_{i}$ ] for each $q^{2} 2 q_{1} ;::: ; q_{d} g$.

The same reasoning can be applied to $\left[q_{-1} ; q\right.$ ), using a possibly di erent flow $g^{\dagger}$ and constant i with

$$
f \mathrm{gf}^{-1}=\mathrm{g}_{1}^{i} \text { : }
$$

Since $g_{i}{ }^{i}$ and $g_{1}{ }^{i}$ coincide on $\left(q ; q_{+1}\right)$, it is not hard to see that we must have $i=i$. Now the result follows from Proposition 3.1, as in the proof of Lemma 5.6 and Corollary 5.8.

Corollary 7.7 For every $\mathrm{f} 2 \mathrm{G}^{\prime} \mathrm{nC}(\mathrm{g})$, there is a positive real number $=$ (f) $\in 1$ such that $i=$, for all $1 \quad i \quad d$, where $i$ is given by Lemma 7.5. For every $i, s_{i}=s_{i+1}$, where addition is mod $d$.

Proof Let 1 i d. As in the proof of Corollary 5.8, we have that g is conjugate in a left neighborhood of $q$ to $\times 7 \quad x=\left(1+x^{5_{i}}\right)^{1=5_{i}}$ and $g$ is conjugate in a right neighborhood of $q$ to $x \eta \quad x=\left(1+x^{S_{i+1}}\right)^{1=s_{i+1}}$. Since $g$ is $C^{1}$, we must have $s_{i}=s_{i+1}$. But then $f$ is conjugate in a left neighborhood of $q$ to $\times \nabla \quad x=i_{i}^{1=s_{i}}$ and $f$ is conjugate in a right neighborhood of $q$ to $x \nabla x \neq i+1)^{1=s_{i+1}}$. It follows that $i=i+1$. Set to be this common value.

The proof of the next corollary is identical to the proof of Corollary 5.8.

C orollary 7.8 For every $f 2 G^{\prime} n C(g)$, the map : $S^{1}!\mathbb{R}^{1}$ de ned by:

$$
(p)=i(p) ; \quad \text { for } p 2(q-1 ; q]
$$

is a $C^{r}$ rami ed cover with signature $\mathbf{s}=\left(s_{1} ;::: s_{d} ; o_{1} ;::: ; o_{d}\right)$. Thedi eomorphism $f$ is a \{rami ed lift of the map $\times 7$ ( $f$ ) $x$, and $g$ is a \{rami ed lift of the map $\times 7 \times+1$.

C orollary 7.9 g embeds in a unique $\mathrm{C}^{r}$ flow $\mathrm{g}^{\mathrm{t}}$, with $\mathrm{g}=\mathrm{g}^{1}$. The elements of $\mathrm{C}(\mathrm{g})$ belong in the flow for g and, for each $\mathrm{f} 2 \mathrm{G}^{\mathrm{l}} \mathrm{nC}(\mathrm{g})$, lie in the rami ed lift under $f$ of the translation group $f \times 7 \times+j 2 \mathbb{R g}$. That is, for any $\mathrm{h} 2 \mathrm{C}(\mathrm{g})$, there exist real numbers , t such that $\mathrm{h}=\mathrm{g}^{\mathrm{t}}$ is a f \{rami ed lift of the map $\times 7 \times+$.

Proof This corollary follows directly from Corollary 7.8, Lemma 5.9 and Lemma 5.10.

Lemma 7.10 For any $f_{1} ; f_{2} 2 G^{\prime} n C(g)$, there exists a real number $\gamma$ such that $f_{2}$ is a $f_{1}$ \{rami ed lift of the map $\times 7 \quad\left(f_{2}\right) x+\gamma$.

Proof The proof is expressed in a series of commutative diagrams.
Lemma 7.11 Thereexists an $2 \mathbb{R}$ such that $g$ is the $\left(f_{1} ; f_{2} ; i d\right)\{r a m i ~ e d$ lift of the identity map.

Proof Thefollowing diagram shows that if itd is the ( $\mathrm{f}_{1} ; \mathrm{f}_{2}$; id) \{rami ed lift of the identity map on $\mathbb{R} P^{1}$, then idd $g=g$ d:


Geometry \& Topology, Volume 8 (2004)

Since g embeds in a flow $\mathrm{g}^{t}$ that is a rami ed lift of an a ne flow, it follows from Corollary 7.9 that there exists an such that $i \notin \mathrm{~g}$.

Lemma 7.12 For every $t_{0} 2 \mathbb{R}$ there exists $\gamma 2 \mathbb{R}$ such that $g^{t_{0}}$ is the ( $f_{1} ; f_{2}$; id) \{rami ed lift of the map $\times 7 \times-\gamma$.

Proof Let be given by the previous lemma. Let $\gamma$ be the real number such that $g^{t_{0}-}$ is a $f_{1}$ - rami ed lift of $x \nabla x-\gamma$. The proof follows from the following diagram:


Thecomposition of themaps on thetop row is $\mathrm{g} \mathrm{g}^{\mathrm{t}_{0}-}=\mathrm{g}^{\mathrm{t}_{0}}$. Thecomposition of the maps on the bottom row is $x 7 x-\gamma$.

Lemma 7.13 For all $\mathrm{t} 2 \mathbb{R}, \mathrm{f}_{2} \mathrm{~g}^{\mathrm{t}} \mathrm{f}_{2}^{-1}=\mathrm{g}^{\left(\mathrm{f}_{2}\right) \mathrm{t}}$.

Proof The proof follows from the following diagram:

$$
\begin{aligned}
& S^{1}-f_{2}^{-1}-S^{1}-g^{t}-S^{1}-f_{2}-S^{1}
\end{aligned}
$$

The composition of the maps on the bottom row gives $\times 7 \times+\left(f_{2}\right) t$. By uniqueness (Lemma 5.9), $\mathrm{f}_{2} \mathrm{~g}^{\mathrm{t}} \mathrm{f}^{-1}=\mathrm{g}^{\left(\mathrm{f}_{2}\right) \mathrm{t}}$ for all $\mathrm{t} 2 \mathbb{R}$.

Le be given by Lemma 7.11, and let $\gamma$ be given by Lemma 7.12, with $t_{0}=\left(f_{2}\right)$. From the following diagram:

it follows that $F(x)=\left(f_{2}\right) x+\gamma$, completing the proof of Lemma 7.10.
Proposition 7.14 Fix f $2 \mathrm{G}^{\prime} \mathrm{nC}(\mathrm{g})$. Then for each h 2 G , there exists $F 2 A(\mathbb{R})$ such that $h$ is a $f$ \{rami ed lift of $F$.

Proof By Corollary 7.9 and Lemma 7.10, we have that for each h 2 G , there exists $k 2 A+(\mathbb{R})$, so that $h^{l}$ is a $f$ \{rami ed lift of $k^{\prime}$. Therefore, by Proposition 5.12, h is a f \{rami ed lift of either k or -k .

By Lemma 4.5, this completes the proof of Theorem 1.9.

## Acknowledgements

Many useful conversations with Gautam Bharali, Christian Bonatti, Keith Burns, Matthew Emerton, Benson Farb, Giovanni Forni, J ohn Franks, Ralf Spatzier, J ared Wunsch and Eric Zaslow aregratefully acknowledged. Wethank Andres Navas and Etienne Ghys for very useful comments on earlier versions of this paper, and for pointing out several references to us. Ghys supplied the simple proof of Proposition 2.1, and Curt McMullen supplied the simple proof of Lemma 4.1. Finally, we thank Benson Farb for reminding us that the BS groups are often interesting. The second author was supported by an NSF grant.

## References

[1] D Cerveau, R M oussu, Groupes d'automorphismes de ( $C ; 0$ ) et equations di erentielles ydy $+\quad=0$, Bull. Soc. Math. France 116 (1989) $459\{488$
[2] P M Elizarov, Yu S Ilyashenko, A A Shcherbakov, S M Voronin, Finitely generated groups of germs of one-dimensional conformal mappings, and invariants for complex singular points of analytic foliations of the complex plane, Adv. Soviet Math. 14, Amer. Math. Soc. Providence, RI (1993)
[3] B Farb, J Franks, Groups of homeomorphisms of one-manifolds, I: Actions of nonlinear groups, preprint
[4] B Farb, L M osher, On the asymptotic geometry of abelian-by-cyclic groups, Acta Math. 184 (2000) 145\{202
[5] B Farb, P Shalen, Groups of real-analytic di eomorphisms of the circle, Ergodic Theory and Dynam. Syst. 22 (2002) 835-844
[6] E Ghys, Sur les groupes engendres par des di eomorphismes proches de l'identite, Bol. Soc. Brasil. Mat. (N.S.) 24 (1993) 137\{178
[7] E Ghys, Groups acting on the circle, L'Ensiegnement Mathematique, 47 (2001) 329-407
[8] N K opell, Commuting Di eomorphisms, Global Analysis (Proc. Sympos. Pure Math., Vol. XIV, Berkeley, Calif. (1968) 165\{184
[9] F Labourie, Large groups actions on manifolds, Proceedings of the International Congress of Mathematicians, Vol. II (Berlin, 1998) Doc. Math. (1998) Extra Vol. II, 371\{380
[10] I Nakai, Separatrices for nonsolvable dynamics on $\mathbb{C} ; 0$, Ann. Inst. Fourier (Grenoble) 44 (1994) 569\{599
[11] A Navas, Groups resolubles de di emorphismes de l'intervalle, du cercle et de la droite, to appear in Bol. Soc. Brasil. Mat.
[12] J F Plante, W P Thurston, Polynomial growth in holonomy groups of foliations, Comment. Math. Helv. 51 (1976) 567\{584
[13] J Rebelo, R Silva, The multiple ergodicity of non-discrete subgroups of Di ! (S ${ }^{1}$ ), Mosc. Math. J. 3 (2003) $123\{171$
[14] S Sternberg, Local Contractions and a theorem of Poincare, Amer. J. Math. 79 (1957) 809-824
[15] F Takens, Normal forms for certain singularities of vector elds, Ann. Inst. Fourier (Grenoble) 23 (1973) 163\{195
[16] M Zhang, W Li, Embedding flows and smooth conjugacy, Chinese Ann. Math. Ser. B, 18 (1997) 125\{138

