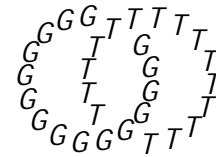


Geometry & Topology
Volume 7 (2003) 225{254
Published: 24 March 2003



Heegaard Floer homology and alternating knots

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Abstract

In an earlier paper, we introduced a knot invariant for a null-homologous knot K in an oriented three-manifold Y , which is closely related to the Heegaard Floer homology of Y . In this paper we investigate some properties of these knot homology groups for knots in the three-sphere. We give a combinatorial description for the generators of the chain complex and their gradings. With the help of this description, we determine the knot homology for alternating knots, showing that in this special case, it depends only on the signature and the Alexander polynomial of the knot (generalizing a result of Rasmussen for two-bridge knots). Applications include new restrictions on the Alexander polynomial of alternating knots.

AMS Classification numbers Primary: 57R58

Secondary: 57M27, 53D40, 57M25

Keywords: Alternating knots, Kauffman states, Floer homology

Proposed: John Morgan
Seconded: Yasha Eliashberg, Robion Kirby

Received: 1 November 2002
Revised: 19 March 2003

1 Introduction

In [25], we introduced a collection of Abelian groups associated to a closed, oriented three-manifold Y , the Heegaard Floer homology of Y .¹ In [27], we introduced a "filtration" on the Heegaard Floer homology of a three-manifold Y which is induced from a null-homologous knot K in Y , see also [30]. Taking the homology groups of the associated graded object, we obtain Floer homology groups $\widehat{HF}K(Y; K) = \bigoplus_{i \in \mathbb{Z}} \widehat{HF}K(Y; K; i)$ (where the integer i appearing here corresponds to the filtration level) which are topological invariants of the knot K .

Our aim here is to study these invariants in the case where the ambient three-manifold is the three-sphere, in which case $\widehat{HF}(S^3) = \mathbb{Z}$. Working with a suitable Heegaard diagram compatible with a planar projection of the knot, we describe the "classical" aspects of the Floer theory: generators of the knot complex, their filtration levels, and absolute gradings (in terms of combinatorics of a (generic) knot projection to the plane (though the differentials in the knot complex still elude such a description)). With this combinatorial description in hand, we are able to completely determine the Heegaard Floer homology for alternating knots (i.e. those which admit a projection for which the crossing types alternate between overcrossings and undercrossings) and give some topological applications. More calculations based on these descriptions will be given in a future paper [29].

1.1 Classical Floer data for classical knots

Let $K \subset S^3$ be a knot. To define the knot Floer homology, we must work with a Heegaard diagram for S^3 which is compatible with the knot K . Specifically, we require that the knot K is supported entirely inside one of the two handlebodies, meeting exactly one of the attaching disks in a single transverse intersection point. As in [27], we then obtain a set of generators X of the chain complex $\mathcal{CF}(S^3)$ (the chain complex whose homology calculates $\widehat{HF}(S^3) = \mathbb{Z}$), which are endowed with a pair of integer-valued functions, the filtration level F and the absolute grading gr .

For the boundary operator on $\mathcal{CF}(S^3)$, if \mathbf{x} corresponds to a generator and \mathbf{y} appears with non-zero multiplicity in the expansion of $\partial \mathbf{x}$, then $gr(\mathbf{y}) =$

¹In most of this paper, we work with the simplest version of Heegaard Floer homology, $\widehat{HF}(Y)$, for three-manifolds with $H_1(Y; \mathbb{Z}) = 0$. In this case $\widehat{HF}(Y)$ is a \mathbb{Z} -graded, finitely generated Abelian group.

$\text{gr}(\mathbf{x}) - 1$, while $F(\mathbf{x}) = F(\mathbf{y})$. Thus, the associated graded complex for the filtration F , which we denote here by $\widehat{CFK}(S^3; K)$, is also freely generated by X , but its boundary operator now preserves F , and hence we have the splitting

$$\widehat{CFK}(S^3; K) = \bigoplus_{i \in 2\mathbb{Z}} \widehat{CFK}(S^3; K; i);$$

where $\widehat{CFK}(S^3; K; i)$ is the subcomplex generated by elements $\mathbf{x} \in X$ with $F(\mathbf{x}) = i$. We reiterate: although this associated chain complex $\widehat{CFK}(S^3; K)$ depends on the choice of Heegaard diagram used for S^3 , its homology

$$\widehat{HFK}(S^3; K) = \bigoplus_{i \in 2\mathbb{Z}} \widehat{HFK}(S^3; K; i)$$

does not.

A *decorated projection* for K is a generic knot projection of K , together with a choice of a distinguished edge. In Section 2, we associate a natural Heegaard diagram for K to any decorated knot projection for K . This allows us to describe the generators X and the functions F and gr in terms of the knot projection. For the description of the generators, we use the notion of *states* introduced by Kau man for the Alexander polynomial, see [16]. We recall this briefly here.

Let $K \subset S^3$ be an oriented knot, and π a decorated projection of K . The projection gives a planar graph G whose vertices correspond to the double-points of the projection of K . Since G is four-valent, there are four distinct quadrants (bounded by edges) emanating from each vertex, each of which is a corner of the closure of some region of $S^2 - G$. Let m denote the number of vertices of G . Clearly, G divides S^2 into $m + 2$ regions. The two regions which share the distinguished edge will be denoted A and B . In fact, we will always choose our projections so that A is the unbounded region.

Definition 1.1 A *Kau man state* (cf. [16]) for a decorated knot projection of K is a map which associates to each vertex of G one of the four in-coming quadrants, so that:

- the quadrants associated to distinct vertices are subsets of distinct regions in $S^2 - G$
- none of the quadrants is a corner of the distinguished regions A or B .

It is easy to see that a Kau man state sets up a one-to-one correspondence between vertices of G and the connected components of $S^2 - G - A - B$.

There is a very simple description of Kauffman states in graph-theoretic terms (see also [16]). The regions in the complement of the planar projection can be colored black and white in a chessboard pattern, by the rule that any two regions which share an edge have opposite color. There is then an associated "black graph", whose vertices correspond to the regions colored black, and whose edges correspond to vertices in G which connect the opposite black regions. In these terms, Kauffman states are in one-to-one correspondence with the maximal subtrees of the black graph (under a correspondence which associates to a Kauffman state x the union of vertices of G , thought of now as edges in the black graph, to which x associates a black quadrant).

Let \mathcal{S} denote the set of Kauffman states for our decorated knot projection. We define two functions $F: \mathcal{S} \rightarrow \mathbb{Z}$ and $M: \mathcal{S} \rightarrow \mathbb{Z}$, called the filtration level and absolute grading respectively.

To describe the filtration level, note that the orientation on the knot K associates to each vertex $v \in G$ a distinguished quadrant whose boundary contains both edges which point towards the vertex v . We call this the quadrant which is "pointed towards" at v . There is also a diagonally opposite region which is "pointed away from" (i.e. its boundary contains the two edges pointing away from v). We define the local filtration contribution of x at v , denoted by $s(x; v)$, by the following rule (illustrated in Figure 2), where $\epsilon(v)$ denotes the sign of the crossing (which we recall in Figure 1):

$$s(x; v) = \begin{cases} \epsilon(v) & x(v) \text{ is the quadrant pointed towards at } v \\ -\epsilon(v) & x(v) \text{ is the quadrant away from at } v \\ 0 & \text{otherwise.} \end{cases}$$

The filtration level associated to a Kauffman state, then, is given by the sum

$$S(x) = \sum_{v \in \text{Vert}(G)} s(x; v)$$

Note that the function $S(x)$ is the T -power appearing for the contribution of x to the symmetrized Alexander polynomial, see [1], [17].

The grading $M(x)$ is defined analogously. First, at each vertex v , we define the local grading contribution $m(x; v)$. This local contribution is non-zero on only one of the four quadrants { the one which is pointed away from at v . At this quadrant, the grading contribution is minus the sign $\epsilon(v)$ of the crossing, as illustrated in Figure 3. Now, the grading $M(x)$ of a Kauffman state x is defined by the formula

$$M(x) = \sum_{v \in \text{Vert}(G)} m(x; v)$$



Figure 1: **Crossing conventions** Crossings of the first kind are assigned $+1$, and those of the second kind are assigned -1 .



Figure 2: **Local filtration level contributions** $s(x; \nu)$ We have illustrated the local contributions of $s(x; \nu)$ for both kinds of crossings. (In both pictures, "upwards" region is the one which the two edges point towards.)



Figure 3: **Local grading contributions** $m(x; \nu)$ We have illustrated the local contribution of $m(x; \nu)$.

With these objects in place, we can now state the following:

Theorem 1.2 *Let K be a knot in the three-sphere, and choose a decorated knot projection of K . Then, there is a Heegaard diagram for K with the property that the knot complex $\widehat{CFK}(S^3; K)$ is freely generated by Kau man states of the decorated projection. Moreover, if \mathbf{x} denotes the generator of $\widehat{CFK}(S^3; K)$ and x is its corresponding Kau man state, then $F(\mathbf{x}) = S(x)$ and $\text{gr}(\mathbf{x}) = M(x)$.*

1.2 Heegaard Floer homology for alternating knots

In the special case where the knot is alternating, Theorem 1.2 easily determines the knot homology completely in terms of the Alexander polynomial Δ_K of the

knot K and its signature $\sigma(K)$.

In the following theorem, we use the sign conventions according to which the signature of the left-handed trefoil is $+2$, cf. [20].

Theorem 1.3 *Let $K \subset S^3$ be an alternating knot in the three-sphere, and write its symmetrized Alexander polynomial as*

$$\kappa(T) = a_0 + \sum_{s>0} a_s(T^s + T^{-s}).$$

Then, $\widehat{HFK}(S^3; K; s)$ is supported entirely in dimension $s + \frac{\sigma(K)}{2}$, and indeed

$$\widehat{HFK}(S^3; K; s) = \mathbb{Z}^{j^{a_s}}.$$

It is very suggestive to compare the above result with the corresponding theorem of Lee on the Khovanov homology for alternating knots (see [19], see also [18], [2], [13]). We can also use the above theorem to calculate the Heegaard Floer homologies of three-manifolds obtained by zero-surgeries along the knot. In particular, we obtain the following result, which is a generalization of a theorem of Rasmussen (see [30]) which calculates the Heegaard Floer homology of three-manifolds obtained as integer surgeries along two-bridge knots. (In effect, our methods show that alternating knots are "perfect" in Rasmussen's sense.)

To state our results in a useful form, we recall more aspects of the Heegaard Floer homology package from [25]. Specifically, there is a variant of the Heegaard Floer homology $HF^+(Y)$ which is a module over the ring $\mathbb{Z}[U]$. This module is related to the variant $\mathcal{H}F(Y)$ considered earlier by a canonical long exact sequence

$$\cdots \rightarrow \mathcal{H}F(Y) \rightarrow HF^+(Y) \xrightarrow{U} HF^+(Y) \rightarrow \cdots$$

The group $HF^+(Y)$ can be given an absolute $\mathbb{Z}=2\mathbb{Z}$ grading. In fact, these groups obtain some additional structure, depending on the homological properties of Y , which we describe now in the case where $H_1(Y; \mathbb{Z}) = \mathbb{Z}$ (as is the case for zero-framed surgery on a knot in S^3). In this case, there is a splitting $HF^+(Y) = \bigoplus_{s \in \mathbb{Z}} HF^+(Y; s)$ with the property that $HF^+(Y; s) = HF^+(Y; -s)$. Indeed, the summand $HF^+(Y; s)$ is endowed with a relative $\mathbb{Z}=2s\mathbb{Z}$ grading² (compatible with the $\mathbb{Z}=2\mathbb{Z}$ mentioned earlier), and in particular when $s = 0$, it gives a relative \mathbb{Z} -grading. Indeed the summand with

²Let S be an Abelian group. An (absolutely) S -graded Abelian group is an Abelian group G generated by a set X , equipped with a map $\text{gr}: X \rightarrow S$. A relatively S -graded Abelian group is an Abelian group G generated by a set X , equipped with a relative grading $\text{gr}^0: X \rightarrow S$ with $\text{gr}^0(x; y) + \text{gr}^0(y; z) = \text{gr}^0(x; z)$.

$s = 0$ can be given an absolute grading with values in the set $\frac{1}{2} + \mathbb{Z}$. Although this choice might seem unnatural at first glance, it fits neatly with the four-dimensional theory, cf. [28]. Action by the ring element U decreases all of these gradings by 2.

Let T_k^+ denote the \mathbb{Q} -graded $\mathbb{Z}[U]$ -module which is abstractly isomorphic to $\mathbb{Z}[U; U^{-1}] = \mathbb{Z}[U]$, graded so that multiplication by U decreasing grading by two, and its bottom-most homogeneous generator has degree $k \in \mathbb{Q}$. Recall that $HF^+(S^3) = T_0^+$.

Given a knot K and an integer s , let $t_s(K)$ denote the torsion coefficients defined by

$$t_s(K) = \sum_{j=1}^{\infty} j a_{js+j}$$

(where here the a_s are the coefficients of the symmetrized Alexander polynomial of K). These integers are closely related to the Milnor torsion of the knot [21], see also [32].

Finally, for $s \in 2\mathbb{Z}$, we let $\tau(s)$ be the integer defined by

$$\tau(s) = \max(0; d^{\lfloor \frac{j-2js}{4} \rfloor} e) \tag{1}$$

Note that $\tau(s)$ is the s^{th} torsion coefficient of the $(2; j, j+1)$ torus knot.

Theorem 1.4 *Let K be an alternating knot, oriented so that $\text{lk}(K) = 0$, and let $S_0^3(K)$ denote the three-manifold obtained by zero-surgery on K . Then,*

for all $s > 0$, we have a $\mathbb{Z}[U]$ -module isomorphism

$$HF^+(S_0^3(K); s) = \mathbb{Z}^{b_s} \oplus \mathbb{Z}[U] = U^{\tau(s)} \oplus \dots$$

where the first summand is supported in degree $s + \frac{\tau(s)}{2} \pmod{2}$, while the second summand has odd parity, and $\tau(s)$ is defined as in Equation (1), for $s = 0$, we have an isomorphism of graded $\mathbb{Z}[U]$ modules

$$HF^+(S_0^3(K)) = \mathbb{Z}^{b_0} \oplus T_{-1=2}^+ \oplus T_{-2}^+ \oplus \dots \oplus T_{(\tau(0)+\frac{1}{2})}^+$$

and the cyclic summand \mathbb{Z}^{b_0} lies in degree $-\frac{\tau(0)}{2}$.

Thus, in both cases, b_s is given by the formula

$$(-1)^{s+\frac{\tau(s)}{2}} b_s = \tau(s) - t_s(K) \tag{2}$$

In fact, Theorem 1.4 is a formal consequence of Theorem 1.3 (for any knot which satisfies the conclusion of Theorem 1.4, the conclusion of Theorem 1.3 holds). In fact, there are some non-alternating knots which satisfy the conclusion of Theorem 1.4. An example is given in Section 4.

1.3 Applications to the topology of alternating knots

We now describe some of the consequences of the above calculations for alternating knots, combined with other results on Heegaard Floer homology.

As a first consequence, we obtain the following calculation of the "correction terms" for three-manifolds obtained as surgery on S^3 along K , for any alternating knot K . This correction term is defined using the absolute grading on the $\mathbb{Z}[U]$ module $HF^+(Y)$ when Y is an integer homology three-sphere, described in [28]. (As explained in that reference, when $H_1(Y; \mathbb{Z}) = 0$, the group $HF^+(Y)$ can be endowed with an absolute \mathbb{Z} -grading.) This number is the analogue of the gauge-theoretic invariant of Frøyshov introduced in [10], [12], constraining the intersection forms of four-manifolds which bound Y . Specifically, according to Theorem 1.12 of [28], if Y is an integer homology three-sphere, then for each negative-definite four-manifold W which bounds Y , we have the inequality

$$d(Y) + \text{rk}(H^2(W; \mathbb{Z})) \leq 4d(Y); \quad (3)$$

for each characteristic vector g for the intersection form $H^2(W; \mathbb{Z})$.³ Recall that Elkies [8] proves that for any negative-definite, unimodular form over \mathbb{Z} ,

$$\max_{\text{characteristic vectors } g} \lambda_1(V) + \text{rk}(V) \leq 0;$$

with equality holding if and only if the bilinear form V is diagonalizable (over \mathbb{Z}). In view of these results, then, $d(Y)$ bounds the "exoticness" of intersection forms of smooth, definite four-manifolds which bound Y , providing a relative version of Donaldson's diagonalization theorem [6], see also [10] and [12].

In general, calculating $d(Y)$ is challenging. But for surgeries on alternating knots, we have the following explicit result (compare [30], [11]):

Corollary 1.5 *Let $K \subset S^3$ be an alternating knot, then*

$$d(S_1^3(K)) = 2 \min(0; -d - \frac{e(K)}{4}):$$

In another direction, Theorem 1.4 can be used to give restrictions on the Alexander polynomials of alternating knots. A classical result of Crowell and Murasugi (see [4] and [22]) states that the coefficients of the symmetrized Alexander polynomial for such a knot alternate in sign (indeed, the sign of a_s is $(-1)^{s+\bar{x}}$). Theorem 1.4 in turn immediately gives the following inequality for the torsion coefficients, which is easily seen to generalize this alternating phenomenon:

³Recall that for a bilinear form Q over a lattice $V = \mathbb{Z}^n$, a *characteristic vector* is a vector $c \in V$ with the property that $Q(v; v) \equiv Q(c; v) \pmod{2}$ for all $v \in V$.

Corollary 1.6 *Let K be an alternating knot in the three-sphere. Then for all $s \in \mathbb{Z}$, we have that*

$$(-1)^{s+g} (t_s(K) - c(s)) = 0;$$

where $c(s)$ are the constants defined in Equation (1).

For example, consider the nine-crossing knot K appearing in the standard knot tables as 9_{42} , see for example [3]. This knot has

$$c(K) = 2 \quad \text{and} \quad \kappa(K)(T) = -1 + 2(T + T^{-1}) - (T^2 + T^{-2});$$

i.e. its Alexander polynomial is alternating, but it fails to satisfy the conditions of Corollary 1.6, so it is not alternating. (Note this particular result is classical, see [5].)

Other restrictions on the Alexander polynomials of alternating knots have been conjectured by Fox, see [9] (see also [23], where these properties are verified for a large class of alternating knots). Specifically, Fox conjectures that for an alternating knot, the absolute values of the coefficients of the Alexander polynomial $|j a_s j|$ are non-increasing in s , for $s \geq 0$. It is easy to see that the above corollary verifies Fox's conjecture for alternating knots of genus 2. For a general alternating knot, the inequalities stated above for coefficients $s < g - 1$ are independent of Fox's prediction. However, for the first coefficient change, i.e. when $s = g - 1$, the above inequalities translate into the following stronger bound:

$$|j a_{g-1} j| \leq 2 |j a_g j| + \begin{cases} \infty & \\ < -1 & \text{if } j = 2g \\ 1 & \text{if } j = 2g - 2 \\ 0 & \text{otherwise.} \end{cases}$$

Finally, we describe a relationship between Theorem 1.4 and contact geometry. Recall that a braid knot $K \subset S^3$ endows S^3 with an open book decomposition, and hence a contact structure, using a construction of Thurston and Winkelnkemper, see [31]. One can ask which contact structure this is.

For this purpose, recall that a contact structure in S^3 has a classical invariant, the "Hopf invariant" of the induced two-plane field $h(\cdot) \in \mathbb{Z}$, which is an integer which uniquely specifies the homotopy class of \cdot . This number is defined by

$$4h(\cdot) = c_1(k)^2 + 2 - 2 \chi(W) - 3 \sigma(W);$$

where W is any almost-complex four-manifold which bounds S^3 so that the induced complex tangencies on its boundary coincide with \cdot , k is the canonical class of the almost-complex structure, $\chi(W)$ is the Euler characteristic of W , and $\sigma(W)$ is the signature of its intersection form.

Using results on the knot homology of braid knots described in [26] (which, in turn, are based on the important work of Giroux [14]), we obtain the following:

Corollary 1.7 *Let $K \subset S^3$ be an alternating, braid knot of genus g , and let κ denote its induced contact structure over S^3 . Then,*

$$h(\kappa) = -\frac{\chi(K)}{2} - g(K): \quad (4)$$

Moreover, the induced contact structure on S^3 is tight if and only if $h(\kappa) = 0$.

In [7], Eliashberg classifies contact structures over S^3 , showing that for each non-zero integer i , there is a unique contact structure κ_i whose Hopf invariant is i , while there are two contact structures with vanishing Hopf invariant: the "standard" (tight) contact structure, and another (overtwisted) one. Combining Corollary 1.7 with Eliashberg's classification, we obtain the following:

Corollary 1.8 *The standard contact structure and all other contact structures in S^3 with negative Hopf invariant are precisely those contact structures which are represented by alternating, braid knots.*

1.4 Alternating links

Theorem 1.3, together with many of its consequences, admits a straightforward generalization to the case of non-split, alternating links. We state and prove the generalization in Section 4. As an illustration, we use this as a stepping-stone for a calculation of the knot homology for a non-alternating knot, 9_{48} .

Acknowledgements The authors wish to warmly thank Jacob Rasmussen and Andras Stipsicz for interesting conversations.

PSO was supported by NSF grant number DMS 9971950 and a Sloan Research Fellowship; ZSz was supported by NSF grant number DMS 0107792 and a Packard Fellowship.

2 Proof of Theorem 1.2.

We prove here the state-theoretic interpretation of the classical Floer data, stated in Theorem 1.2. The main ingredient is a Heegaard diagram which is naturally associated to a decorated knot projection. (Note that this is not

the usual diagram induced from placing the knot into "bridge position".) We describe this Heegaard diagram, after briefly recalling some of the ingredients of the knot Floer complex for knots (specializing for simplicity to the case where the ambient manifold is S^3).

2.1 Classical Floer data.

We give here a rapid description of the data for the knot Floer complex captured in Theorem 1.2. We refer the reader to [27] for a more detailed discussion.

Fix an oriented knot $K \subset S^3$. A *marked Heegaard diagram* is triple of data

$$(\Sigma; f_1, \dots, f_g; f_{g+1}, \dots, f_{g+g}; m)$$

where here

Σ is an oriented surface of genus g ,

f_1, \dots, f_g are pairwise disjoint, embedded circles in Σ representing the attaching circles for a handlebody U_1 ; similarly, f_{g+1}, \dots, f_{g+g} are pairwise disjoint, embedded circles in Σ representing the attaching circles for a handlebody U_2

m is a marked point on the attaching circle f_1 , which is disjoint from the f_i

the Heegaard diagram describes S^3 , i.e. we have a diffeomorphism $U_1 \cup U_2 \cong S^3$

under this identification, the knot K is supported entirely inside U_1 , and it is disjoint from the attaching disks for f_j with $j > 1$, meeting the attaching disk for f_1 in a single positive, transverse intersection point.

We consider the g -fold symmetric product $\text{Sym}^g(\Sigma)$, with two distinguished tori

$$\mathbb{T} = \{f_1\} \times \dots \times \{f_g\} \quad \text{and} \quad \mathbb{T} = \{f_1\} \times \dots \times \{f_{g+g}\}$$

The generators X for the chain complex $\widehat{CFK}(S^3; K)$ are intersection points between \mathbb{T} and \mathbb{T} in $\text{Sym}^g(\Sigma)$. Let w and z be two points in \mathbb{T} which are near m , but which lie on either side of f_1 . A choice of orientation on K gives an ordering on these two points. More precisely, we can find arc γ connecting z to w so that γ is disjoint from all f_i and f_j with $j > 1$, meeting f_1 in a single, transverse intersection point. Orienting γ in the same direction as K , we order the two base points so that γ goes from z to w .

By simple topological considerations (cf. Section 2 of [25]), given two intersection points $\mathbf{x}, \mathbf{y} \in \mathbb{T} \setminus \mathbb{T}$, we can find a Whitney disk w for \mathbb{T} and \mathbb{T} which connects \mathbf{x} to \mathbf{y} ; i.e. a map u from the standard complex disk D into $\text{Sym}^g(\Sigma)$ with the properties that

$$u|_{\text{Re}(z) = 0} \text{ and } j \circ j = 1g \text{ on } \mathbb{T}; \quad u|_{\text{Re}(z) = 0} \text{ and } j \circ j = 1g \text{ on } \mathbb{T};$$

$$u(-i) = \mathbf{x}; \quad u(i) = \mathbf{y}.$$

Let ρ be a point in $\Sigma - \Sigma - \dots - \Sigma - \Sigma - \dots - \Sigma$, we let $n_\rho(\Sigma)$ denote the algebraic intersection number of Σ with the submanifold $\rho \in \text{Sym}^{g-1}(\Sigma)$. In fact, by choosing reference points in each connected component of $\Sigma - \Sigma - \dots - \Sigma - \Sigma - \dots - \Sigma$, we obtain a function from this set of regions to \mathbb{Z} , denoted $D(\Sigma)$, and called the *domain* associated to Σ . As explained in Section 2 of [25], when $g > 2$, the homotopy class of Σ is uniquely determined by $D(\Sigma)$. We denote the set of homotopy classes of Whitney disks by $\mathcal{W}_2(\mathbf{x}, \mathbf{y})$.

We now describe the functions F and gr , referred to in the introduction. The definitions we sketch here are somewhat simpler than the general definitions given in [27]⁴, owing to the fact that our ambient manifold is S^3 .

First, we discuss gr . Given \mathbf{x} and \mathbf{y} , let w be a Whitney disk connecting \mathbf{x} to \mathbf{y} . We claim that if $\mu(w)$ denotes the Maslov index of w , then $\text{gr}(\mathbf{x}) - \text{gr}(\mathbf{y}) - 2n_w(\Sigma)$ is independent of the choice of w . Indeed (cf. Equation (10) of [25]), the function gr is determined up to an additive constant by the relation

$$\text{gr}(\mathbf{x}) - \text{gr}(\mathbf{y}) = \mu(w) - 2n_w(\Sigma).$$

The remaining indeterminacy is removed using the Heegaard Floer homology of S^3 : $\mathcal{CF}(S^3)$ is a chain complex which is generated by the same intersection points X (though its boundary operator allows for more differentials than the knot Floer complex $\widehat{CFK}(S^3; K)$), its boundary operator decreases gr by one, and its homology is \mathbb{Z} , supported in a single dimension. The indeterminacy, then, is removed by the convention that the homology is supported in dimension zero.

Similarly, if \mathbf{x} and \mathbf{y} are a pair of intersection points and w is a Whitney disk connecting them, then we claim that the difference of intersection numbers

⁴In fact, in [27], the filtration is denoted \underline{gr}_m , and in the case we are considering now, it takes values in the set of Spin^c structures on $S^3_0(K)$. This is related to the present function F by the formula

$$F(\mathbf{x}) = hc_1(\underline{gr}_m(\mathbf{x}); [\hat{P}]);$$

where here \hat{P} is the closed surface in $S^3_0(K)$ obtained by capping off a Seifert surface F for K which respects the orientation of K .

$n_z(\cdot) - n_w(\cdot)$ is independent of the choice of \cdot . Indeed (cf. Lemma 2.5 of [27]), the function F is determined up to an additive constant, by the equation

$$F(\mathbf{x}) - F(\mathbf{y}) = n_z(\cdot) - n_w(\cdot):$$

The remaining indeterminacy of F is removed with the help of the observation that

$$\sum_{\mathbf{x} \in 2F(x)} (-1)^{\text{gr}(\mathbf{x})} T^{F(\mathbf{x})} = T^c \kappa(T);$$

where here $\kappa(T)$ denotes the symmetrized Alexander polynomial of K (see Equation (1) of [27]), and c is some integer. The additive indeterminacy of F , then, is removed by requiring that $c = 0$.

We have not defined here the differential on the chain complex. Loosely speaking, the differential on $\mathcal{CF}(S^3)$ counts pseudo-holomorphic Whitney disks u with $n_w(u) = 0$, while the differential on $\widehat{CFK}(S^3; K)$ counts those which satisfy $n_w(u) = 0 = n_z(u)$. Details are given in [27].

2.2 The Heegaard diagram belonging to a decorated knot projection

Let K be an oriented knot in S^3 , and fix a decorated knot projection of K (i.e. a generic planar projection G of K with n crossings, and a choice of distinguished edge e which appears in the closure of the unbounded region A). With these choices, we construct a Heegaard diagram for $(S^3; K)$ as follows.

Let B denote the other region which contains the edge e , and let ∂_r be the boundary of a regular neighborhood in S^3 of G (i.e. it is a surface of genus $n + 1$); we orient ∂_r as $@(S^3 - \text{nd}(G))$. We associate to each region $r \in R(G) - A$, an attaching circle ∂_r (which follows along the boundary of r). To each crossing v in G we associate an attaching circle ∂_v as indicated in Figure 4. In addition, we let ∂_m denote the meridian of the knot, chosen to be supported in a neighborhood of the distinguished edge e .

Each vertex v is contained in four (not necessarily distinct) regions. Indeed, it is clear from Figure 4, that in a neighborhood of each vertex v , there are at most four intersection points of ∂_v with circles corresponding to these four quadrants. (There are fewer than four intersection points with ∂_v if v is a corner of the unbounded region A .) Moreover, the circle corresponding to v meets the circle ∂_B in a single point (and is disjoint from the other circles). It is easy to see that for any choice of marked point $m \in \partial_m$, the construction we have just described gives a marked Heegaard diagram for K .

The correspondence between states and generators for the knot complex $\widehat{CFK}(S^3; K)$, $\mathbb{T} \setminus \mathbb{T}$, should now be clear: an intersection point gives at each vertex (i.e. σ -curve) one of four quadrants (corresponding to the up to four σ -curves). Moreover, since the meridian μ meets exactly one σ -curve, the curve corresponding to the region B , that corresponding σ -curve is not assigned to any of the vertices.

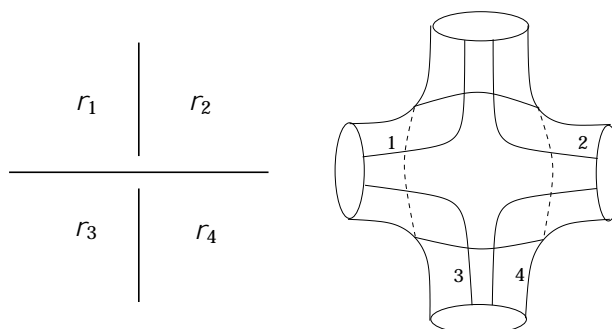


Figure 4: **Special Heegaard diagram for knot crossings** At each crossing as pictured on the left, we construct a piece of the Heegaard surface on the right (which is topologically a four-punctured sphere). The curve σ is the one corresponding to the crossing on the left; the four arcs $\sigma_1, \dots, \sigma_4$ will close up. (Note that if one of the four regions r_1, \dots, r_4 contains the distinguished edge e , its corresponding σ -curve should *not* be included). Note that the Heegaard surface is oriented from the outside.

Before turning to the other aspects of Theorem 1.2, we recall a very useful technical device: the "Clock Theorem" of Kauffman.

Definition 2.1 Two distinct states x and y are said to differ by a *transposition* if there is a pair of vertices v_1 to v_2 with the property that:

$$x|_{G-v_1-v_2} = y|_{G-v_1-v_2},$$

there is a straight path P from v_1 to v_2 (i.e. a path which follows along the knot K) which does not contain the distinguished edge, so that $x(v_1)$ and $y(v_1)$ are the two quadrants which contain the first edge in P , and $x(v_2)$ and $y(v_2)$ are the two quadrants which contain the last edge in P .

Theorem 2.2 (Kauffman) *Any two distinct states x and y can be connected by a sequence of transpositions.*

The proof of the above result can be found in Chapter 2 of [16].

We now establish some lemmas used in the proof of Theorem 1.2.

Lemma 2.3 *Suppose that the two states x and y differ by a transposition, and let \mathbf{x} and \mathbf{y} denote the corresponding generators of the knot complex. Then, $F(\mathbf{x}) - F(\mathbf{y}) = S(x) - S(y)$.*

Proof Orient the edge between v_1 and v_2 as it appears in the knot. There are now four cases, according to whether v_1 or v_2 are under- or over-crossings.

Suppose that the edge takes us from under-crossing at v_1 to an over-crossing at v_2 (i.e. our edge is on the bottom at v_1 and on the top at v_2). In this case, we claim that after possibly switching the roles of \mathbf{x} and \mathbf{y} , we can find a homotopy class $\sum \alpha_i \mathbf{x}_i \mathbf{y}_i$, with $n_w(\) = 0$ and $n_z(\) = 1$. Indeed, the domain associated to $\mathbf{x}, D(\)$, has all local multiplicities zero or one; topologically, it is a connected surface with a collection of circle boundary components. Assume for a moment that there are no intermediate crossings between v_1 and v_2 . In this case, the topology of $D(\)$ is given as follows: the genus of $D(\)$ is given by the number of vertices encountered twice between v_2 and the final point, it has one boundary component corresponding to the meridian μ , it has one boundary circle for each vertex encountered only once between v_2 and the final point (the corresponding μ -circle), and there is one final boundary component (with four distinguished corner points) which is formed from arcs in v_1, v_2 , and the two μ -curves corresponding to the two regions which contain the edge from v_1 to v_2 . This is pictured in Figure 5. In the case where there are intermediate crossings between v_1 and v_2 , the surface looks much the same, except that now there are additional circle components, one corresponding to each compact region in the complement in \mathbb{R}^2 of the part of the projection between v_1 and v_2 (or equivalently, one for each vertex between v_1 and v_2). Specifically, these circle components are the μ -curves of these intermediate regions.

The detailed description of the topology of $D(\)$ is not particularly relevant to the proof of the present lemma (though it is relevant in the proof of the next one); all we need here is the fact that $n_w(\) = 0$ and $n_z(\) = 1$, from which it follows immediately that $F(\mathbf{x}) - F(\mathbf{y}) = 1$. From the definition of $S(x)$, it follows easily that $S(x) - S(y) = 1$ (i.e. independent of the orientation on the two pieces of K transverse to our edge at v_1 and v_2) as well, verifying the lemma in this case.

Suppose that both v_1 and v_2 are under-crossings. When there are no intermediate intersection points between v_1 and v_2 , it is easy to find a square which serves as $D(\)$ for some $\sum \alpha_i \mathbf{x}_i \mathbf{y}_i$ with $n_w(\) = n_z(\) = 0$, supported on the region of the Heegaard surface corresponding to the edge, as pictured in Figure 5. In particular, the filtration difference is zero. When there are intermediate intersection points, the region $D(\)$ now is a square with a finite

number of circles removed, but it is still disjoint from w and z . Now, it is easy to see that the formula $S(x) - S(y)$ gives zero, independent of the crossing signs of the two vertices.

The remaining two cases (where v_2 is an over-crossing) are handled similarly. □

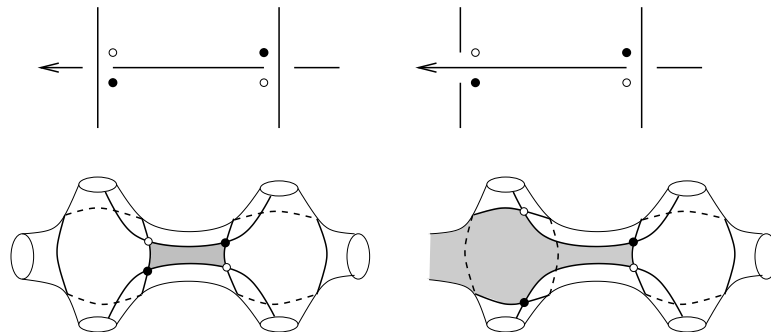


Figure 5: **Illustration of Lemma 2.3** The top row represents the original projection diagram: the light circles represent the state x , while the dark ones represent y . In the second row, we have the corresponding Heegaard picture, with the support of the homotopy class $\mathcal{D}_2(\mathbf{x}; \mathbf{y})$ lightly shaded. (Note that there are two other cases not pictured here, but the corresponding pictures are the same as these, only viewed from underneath.)

Lemma 2.4 *Suppose that the two states x and y differ by a transposition, at vertices v_1 and v_2 . Then, the absolute value of the difference in gradings between the corresponding generators \mathbf{x} in \mathbf{y} is one. More precisely, if \mathbf{x} is represented by light dots in Figure 6, and \mathbf{y} is represented by the dark ones, then $\text{gr}(\mathbf{x}) - \text{gr}(\mathbf{y}) = 1$.*

Proof Domains with $n_w(\cdot) = 0$ connecting intersection points which differ by a transposition have already been demonstrated in the proof of Lemma 2.3 (see Figure 5). Our task here is to calculate their Maslov index (and, indeed, to show that it is one in all the above cases).

In all cases, we have seen that the domains $D(\cdot)$ are topologically a square with a finite number of handles attached, and a finite number of disks removed. Letting $\mathbf{x}; \mathbf{y} \in \mathbb{T} \setminus \mathbb{T}$ denote the intersection points corresponding to the states x and y , and writing $\mathbf{x} = (x_1; \dots; x_g)g$, and $\mathbf{y} = (y_1; \dots; y_g)g$, we have (for some numbering) that for $i = 3; \dots; g$, $x_i = y_i$, while x_1, y_1, x_2 , and y_2 are the four corner points of the square. Now, in the interior of each handle

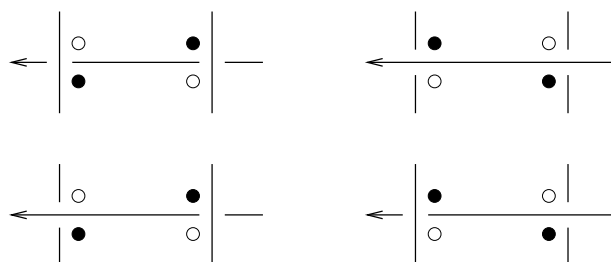


Figure 6: **Grading difference for intersection points which differ by a transposition** Let x be the state represented by the dark dots, and y be the one represented by the light ones. Then, $\text{gr}(x) - \text{gr}(y) = 1$.

attached to the square, we have a point x_i (for $i > 2$), and also on each circle we have a point x_i , and all the remaining intersection points x_i (with $i > 2$) lie in the exterior of $D(\cdot)$. Thus, these extra intersection points do not affect the Maslov index. Moreover, each of the handles can be deleted, while deleting the corresponding intersection point x_i without affecting the Maslov index. (This latter operation corresponds to destabilizing the Heegaard diagram, see [25].)

It remains then to calculate the Maslov index of a homotopy class whose domain consists of square minus a finite collection of disks. We claim that for such a homotopy class, $\mu(\cdot) = 1$. This can be seen, for example, by finding such a homotopy class in a suitably chosen (genus $n + 2$) Heegaard diagram for $\#^{n+1}(S^1 \times S^1)$ (where here n denotes the number of disks removed), and using the fact that $\mathcal{HF}(\#^{n+1}(S^1 \times S^1); \mathfrak{s}_0) = H(T^{n+1}; \mathbb{Z})$ as relatively \mathbb{Z} -graded groups where here \mathfrak{s}_0 denotes the Spin^c structure with first Chern class equal to zero (cf. Section 5 of [25]). Specifically, we can find such a domain which connects two intersection points whose absolute gradings are known to differ by one. We illustrate this in the case where $n = 1$, in Figure 7. □

We find it useful to introduce one more notion before proceeding to the proof of Theorem 1.2. Recall that the decoration on the knot projection (the distinguished edge, and the orientation on the knot projection) induces a natural ordering on all the edges of the knot projection. If v is any vertex in the knot projection, the *edge after* v is the last edge (in this ordering) whose closure contains v . The edge which immediately precedes it will be called the *v -penultimate edge*, and we denote it by e_v . Note also that the orientation of K and the reference point specifies an ordering on the vertices, as follows. We say that $v_1 < v_2$ if the vertex v_1 is crossed the second time before v_2 is (on a path beginning in the interior of the distinguished edge and following K).

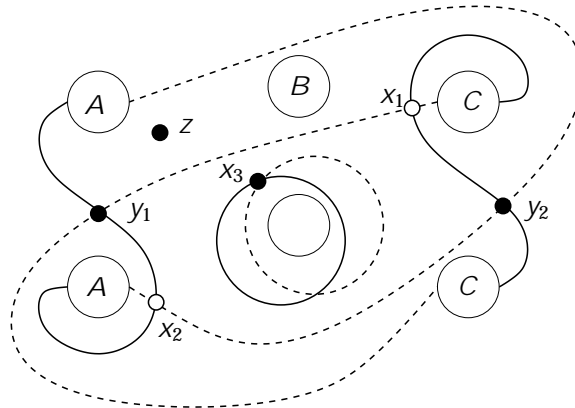


Figure 7: **Maslov index calculation of a square minus a disk** Above, we have pictured a $g = 3$ Heegaard diagram for $\#^2(S^2 - S^1)$. The dark lines represent α -curves, and the dashed ones represent β -curves. Note that the disks labeled with capital letters A , B , or C are to be removed, and their boundaries are pairwise identified, according to their pictured labeling. There are four intersection points in $\mathbb{T}^3 \setminus \mathbb{T}^2$, all of which represent the Spin^c structure with trivial first Chern class, using the pictured reference point z . Let $\mathbf{x} = f_{x_1; x_2; x_3}g$ and $\mathbf{y} = f_{y_1; y_2; y_3}g$ with $y_3 = x_3$. It is easy to find a domain for a Whitney disk $\Sigma_2(\mathbf{x}; \mathbf{y})$ which is a square with a disk removed. Moreover, the grading difference between these two elements is one (they are also connected by a square).

There is a *canonical state* x_0 which is uniquely characterized by the property that for each crossing v , $x_0(v)$ is one of the two quadrants whose closure contains v -penultimate edge, according to the following lemma:

Lemma 2.5 *The canonical state x_0 is well-defined.*

Proof Let $R(G)$ denote the set of regions in $S^2 - G - A - B$. Let $X_0 = A \sqcup B$. We will inductively define the canonical state x_0 by finding an ordering $f_{v_1; \dots; v_m}g$ of all the vertices in the graph G , with the property that $x_0 \circ f_{v_1; \dots; v_m}g$ is uniquely defined (note that it is *not* the same as the ordering induced by the orientation of K). Correspondingly, we will exhaust S^2 by a sequence of regions

$$X_0 \subset X_1 \subset \dots \subset X_m = S^2$$

with the property that $x_0 \circ f_{v_1; \dots; v_n}g$ maps onto the set of regions in $X_n - G - X_0$ (and hence X_{n+1} is defined by attaching to X_n a region $R_n \in R(G)$). In our induction hypothesis, we will assume that the v_j -penultimate edge is contained in the interior of X_j .

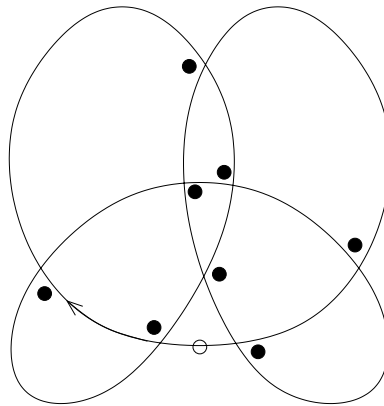


Figure 8: **The canonical state x_0 for 8_{16}** We have illustrated here the canonical state x_0 for the alternating knot 8_{16} . The light circle indicates the distinguished edge, and the arrow indicates the orientation.

For the initial step ($n = 0$), x_0 is vacuously defined.

For the inductive step, either $X_n = S^2$ (in which case we are finished), or X_n is a proper subset of S^2 , in which case it must have corners, since we have assumed that our graph belongs to a knot projection. Consider the last corner point v_{n+1} of X_n (with respect to the ordering induced by the orientation on the knot). It is clear that the v_{n+1} -penultimate edge must appear in two quadrants, one of which is contained in X_n , and the other of which is contained in a region $R_{n+1} = S^2 - X_n$ (for if this hypothesis is not satisfied, we would simply be able to find a later corner vertex). It follows then that $v_{n+1} \notin \{v_1, \dots, v_n\}$ (for the edges before all those vertices are all contained in the interiors of X_n). We then define $x_0(v_{n+1})$ to be the quadrant of R_{n+1} containing the v_{n+1} -penultimate edge. Let $X_{n+1} = X_n \cup R_{n+1}$. It is now clear from the construction of X_{n+1} that the v_{n+1} -penultimate edge is contained in the interior of X_{n+1} .

Observe that the above argument not only constructs the canonical state x_0 but, since there was no ambiguity in the definition, establishes its uniqueness. \square

Proof of Theorem 1.2 The correspondence between states and generators of $\widehat{CFK}(S^3; K)$ in the appropriate Heegaard diagram was already explained in the beginning of this section. We adopt here the notational convention that if x and y are states, then \mathbf{x} and \mathbf{y} are their corresponding intersection points.

To prove the assertion about filtration levels, we appeal to Lemma 2.3, according to which if x and y are any two states which differ by a transposition, then

$$S(x) - S(y) = F(\mathbf{x}) - F(\mathbf{y}).$$

Combining this with Kauffman's theorem, we see that there is a constant c_1 which *a priori* depends on the knot projection, with the property that if x is any state, then

$$S(x) = F(\mathbf{x}) + c_1.$$

In particular, it follows that for some suitable choice of signs (given by the the $\mathbb{Z}=2\mathbb{Z}$ grading of the intersection point \mathbf{x}), the polynomial

$$\kappa(T) = \sum_{x \in \mathcal{S}} (-1)^{\text{gr}(\mathbf{x})} T^{S(x)};$$

has the form $\kappa(T) = T^{c_1} \kappa(T)$ where $\kappa(T)$ denotes the symmetrized Alexander polynomial. Indeed, the fact that $c_1 = 0$ follows from the fact that $\kappa(T)$ is symmetric: indeed, it coincides with the Conway-normalized Alexander polynomial, according to Chapter VI of [17].

When x and y are states which differ by a transposition, and \mathbf{x} and \mathbf{y} their corresponding intersection points, it follows easily from Lemma 2.4 that

$$\text{gr}(\mathbf{x}) - \text{gr}(\mathbf{y}) = M(x) - M(y).$$

From Kauffman's theorem, it then readily follows that there is a constant c_2 with the property that for any state x ,

$$\text{gr}(\mathbf{x}) = M(x) + c_2.$$

To see that $c_2 = 0$, we verify that if x_0 is the canonical state (whose existence was established in Lemma 2.5 above) and \mathbf{x}_0 its corresponding intersection point,

$$M(x_0) = 0 = \text{gr}(\mathbf{x}_0).$$

Indeed, it is straightforward to see that $M(x_0) = 0$: the local contributions $m(x_0; v)$ vanish for each vertex.

To see that \mathbf{x}_0 has vanishing absolute grading, we proceed as follows. One can reduce the Heegaard diagram for the knot described above to another Heegaard diagram for S^3 by handlesliding the α -curves of vertices. We then arrange the α_v -curves in descending order, according to this ordering of the corresponding vertices, and then handleslide them "forwards" across the reference point z (but never across w). In this manner, we obtain a new Heegaard diagram for S^3 , where the α -curve at any vertex v now meets only the up to two β -curves corresponding to the two quadrants which contain the v -penultimate edge. Thus, the canonical state also induces an intersection point \mathbf{x}_0' for this new Heegaard diagram, and indeed its absolute degree agrees with that of \mathbf{x}_0 , since the handleslides never crossed w (compare Section 5 of [25]). Moreover,

the uniqueness of Lemma 2.5 ensures that \mathbf{x}_0^ℓ is, in fact, the only intersection point in $\mathbb{T} \setminus \mathbb{T}$ for this new Heegaard diagram, so it must have absolute degree zero. \square

3 Results on alternating knots

For the purposes of Theorem 1.3, it is useful to have the following explicit description of the signature $\sigma(K)$ of an alternating link, which follows from work of Gordon and Litherland [15] as interpreted by Lee, see [19], which we now recall.

Consider the four quadrants meeting at some vertex v . If we orient the boundary of one of these quadrants Q (in the manner induced from the orientation of the plane), we obtain an ordering on the two consecutive edges contained in the boundary of Q . If the first of these edges is part of an "overcross" at v , we call Q an *over-rst* quadrant; otherwise, we call Q an *under-rst* quadrant. The alternating condition on a knot projection is equivalent to the condition that all the over-rst quadrants have the same color (and hence that all the under-rst ones have the other color). For definiteness, we color all the under-rst quadrants white, as illustrated in Figure 9.

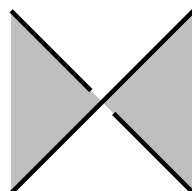


Figure 9: **Coloring conventions for alternating knots** We adopt the pictured convention in the statement of Theorem 3.1.

Theorem 3.1 (Theorem 6 of [15], see also Proposition 3.3 of [19]) *Let K be a knot with alternating projection G . Then, with the coloring conventions illustrated in Figure 9, the signature of K is calculated by the formula*

$$\sigma(K) = \#(\text{black regions in the planar projection}) - \#(\text{positive crossings}) - 1.$$

Proof of Theorem 1.3 Let x be any state. Glancing at the definitions of the local contributions $m(x; v)$ and $s(x; v)$, one sees that

$$m(x; v) - s(x; v) + \frac{(v) + 1}{2} = \begin{cases} 0 & \text{if } x(v) \text{ is an under-rst quadrant} \\ \frac{1}{2} & \text{if } x(v) \text{ is an over-rst quadrant.} \end{cases}$$

Adding this up over all the vertices v , and bearing in mind that the over-
 -rst quadrants are all black, and that there is exactly one black region (the
 distinguished one) which is not represented as $x(v)$ for some vertex v , it follows
 that

$$2(M(x) - S(x)) = \#(\text{black regions in the planar projection}) - \#(\text{positive crossings}) - 1;$$

a quantity which agrees with $\chi(K)$, according to Theorem 3.1. The theorem
 now follows immediately from Theorem 1.2. □

It is straightforward if tedious to verify that in fact the previous theorem deter-
 -mines the filtered chain homotopy type of the knot complex uniquely in terms
 of the Alexander polynomial and the signature of the knot. Rather than in-
 -flicting the necessary linear algebra on our reader, we content ourselves here
 with the proof of Theorem 1.4. For the proof, we will use the relationship be-
 -tween the knot complex and the Floer homology of three-manifolds obtained
 by sufficiently large surgeries on K , which we recall presently.

Recall that when $K \subset S^3$ is a knot, we have the $(\mathbb{Z} \times \mathbb{Z})$ -filtered complex

$$CFK^1(S^3; K) = \{[\mathbf{x}; i; j] \mid F(\mathbf{x}) + (i - j) = 0\}g;$$

Of course, the $\mathbb{Z} \times \mathbb{Z}$ -grading of $[\mathbf{x}; i; j]$ is $(i; j)$, and

$$\text{gr}[\mathbf{x}; i; j] = \text{gr}(\mathbf{x}) + 2i;$$

The subcomplex where $i = 0$ (or $j = 0$) represents $CF^-(S^3)$, the whole com-
 -plex represents $CF^1(S^3)$, and the quotient represents $CF^+(S^3)$. More inter-
 -estingly, this complex can be used to calculate $HF^+(S_n^3(K))$ for sufficiently
 large n . Specifically, fix an integer s , and let $HF^+(S_n^3(K); [s])$ denote HF^+
 calculated using a Spin^c structure which extends over the two-handle $B_n^4(K)$
 to a Spin^c structure satisfying

$$hc_1(s); [\mathcal{P}]i = s - n;$$

where here $[\mathcal{P}] \in H_2(B_n^4(K); \mathbb{Z}) = \mathbb{Z}$ is a generator. Consider the quotient
 complex of C , which is generated by tuples $[\mathbf{x}; i; j]$ with $i = 0$ or $j = s$, denoted
 $Cfi = 0$ or $j = sg$. It is shown in Theorem 4.4 of [27] that the homology of
 $Cfi = 0$ or $j = sg$ calculates $HF^+(S_n^3; [s])$, under a map which shifts grading
 by $\frac{1-n}{4}$; and indeed the natural projection map from $Cfi = 0$ or $j = sg$ to
 $Cfi = 0$ g models the map induced from $B_n^4(K)$ induced by the Spin^c structure
 s .

Proof of Theorem 1.4 The proof relies on the fact, which follows from Theorem 1.3, that if we write $\mathfrak{X} = \mathfrak{X}(K)$, then for each intersection point \mathbf{x}

$$\text{gr}(\mathbf{x}) = F(\mathbf{x}) + \frac{1}{2};$$

and hence, for each $[\mathbf{x}; i; j] \in \text{CFK}^1(S^3; K)$,

$$\text{gr}[\mathbf{x}; i; j] = i + j + \frac{1}{2}. \tag{5}$$

To calculate $HF^+(S_0^3(K); s)$, we calculate $\text{rst } HF^+(S_n^3(K); s)$ for all sufficiently large n .

We have the following short exact sequence

$$0 \rightarrow \text{Cfmax}(i; j - s) \rightarrow \text{Cfi} \rightarrow \text{Cfj} \rightarrow \text{Cfmin}(i; j - s) \rightarrow 0;$$

where $H(\text{Cfmin}(i; j - s))$ is supported in degrees $s + \frac{1}{2}$. It follows that

$$\begin{aligned} H_{s + \frac{1}{2} - 2}(\text{Cfmax}(i; j - s)) &= H_{s + \frac{1}{2} - 2}(\text{Cfi} \rightarrow \text{Cfj} \rightarrow \text{Cfmin}(i; j - s)) \\ &= HF^+_{s + \frac{1}{2} - 2}(S^3) \oplus HF^+_{-s + \frac{1}{2} - 2}(S^3) \\ &= HF^+_{s + \frac{1}{2} - 2}(S^3) \end{aligned} \tag{6}$$

(with the last equality following from the fact that $-s + \frac{1}{2} - 2 < 0$).

In the remaining degrees, we obtain information from the short exact sequence

$$0 \rightarrow \text{Cfmax}(i; j - s) \rightarrow C \rightarrow \text{Cfmin}(i; j - s) \rightarrow 0$$

Now, $H(\text{Cfmax}(i; j - s))$ is supported in dimensions $s + \frac{1}{2} - 2$.

Letting R denote the the part in degree $s + \frac{1}{2} - 2$, we have

$$0 \rightarrow HF^1_{s + \frac{1}{2} - 1}(S^3) \rightarrow H_{s + \frac{1}{2} - 1}(\text{Cfmin}(i; j - s)) \rightarrow R \rightarrow 0 \tag{7}$$

Thus, there are two case for $HF^+(S_n^3(K))$ for large n . When $s + \frac{1}{2} = 0$, the above arguments show that

$$H(\text{Cfmax}(i; j - s)) = HF^1_{s + \frac{1}{2} - 1}(S^3) \oplus \mathbb{Z}_{(s + \frac{1}{2} - 1)}^{b_i};$$

for some non-negative integer b_s . In fact, when $s + \frac{1}{2} - 1 = 0$, the map from C to Cfi clearly factors through $\text{Cfi} = 0$ or $j = sg$. Thus, the above arguments show that

$$H(\text{Cfmax}(i; j - s)) = HF^+(S^3) \oplus \mathbb{Z}_{(s + \frac{1}{2} - 1)}^{b_s};$$

The identification of $H(\text{Cfmax}(i; j - s)) = HF^+(S_n^3; [s])$ for sufficiently large n , together with the integer surgery long exact sequence ([24], see also [28])

$$\rightarrow HF^+(S^3) \xrightarrow{F_1} HF^+(S_0^3(K); s) \xrightarrow{F_2} HF^+(S_n^3(K); [s]) \xrightarrow{F_3}$$

now gives the result when $s \neq 0$.

In the case where $s = 0$, we still have a (possibly trivial) cyclic summand \mathbb{Z}^{b_0} in $HF^+(S_n^3(K); 0)$ (for n sufficiently large) supported in dimension $\frac{1-n}{4} + \frac{1}{2} - 1$, with the property that

$$HF^+(S_n^3(K); 0) = T_{-2d_{\frac{1-n}{4}e} + \frac{1-n}{4}}^+ \mathbb{Z}^{b_0}.$$

Now, in the integral surgeries long exact sequence, the map F_3 consists of a sum of terms, each of which decreases the absolute grading by at least $\frac{1-n}{4}$. It follows immediately (again, using our hypothesis that $\chi(K) < 0$) that this map in the present case must vanish.

The map F_2 now shifts degree by $(n - 3)/4$ and the map F_1 shifts degree by $-1/2$ (cf. Lemma 7.10 of [28]), so the calculation of $HF^+(S_0^3(K); 0)$ follows.

The only remaining piece now is the verification of Equation (2). But this follows immediately from Theorem 9.1 of [24], where the Euler characteristic of $HF^+(Y_0)$ is identified with the torsion of S_0^3 , or, more precisely, provided that $i \neq 0$,

$$-t_i(K) = \langle HF^+(S_0^3(K); i) \rangle$$

(see also [24] for the statement when $i = 0$). □

We now turn to the proofs of the corollaries listed in the introduction.

Proof of Corollary 1.6 This is an immediate application of the theorem (after reflecting K if necessary), bearing in mind that, of course, $b_5 = 0$. □

Proof of Corollary 1.5 In general, we have that $d(S_1^3(K)) = d_{\frac{1}{2}}(S_0^3(K)) - \frac{1}{2}$ (see Proposition 4.12 of [28]). In the case where $\chi(K) = 0$, the result then is an immediate application of Theorem 1.4. When $\chi(K) > 0$, let $r(K)$ denote the reflection of K ; then we have (see [28]) that

$$d_{\frac{1}{2}}(S_0^3(K)) = -d_{-\frac{1}{2}}(S_0^3(r(K))) = \frac{1}{2}$$

(with the last equation following once again from Theorem 1.4). □

For the proof of Corollary 1.7, we use the results from [26], which in turn rely on results of Giroux [14]. Specifically, if $K \subset Y$ is a framed knot of genus g , then $\widehat{HFK}(-Y; K; -g) = \mathbb{Z}$. The image of the generator of this group inside $\widehat{HF}(-Y)$ is shown in [26] to depend on the knot only through

its induced contact structure κ , giving rise to an element $c(\kappa) \in \widehat{HF}(-Y)$. Moreover, when $Y = S^3$ (or, more generally, κ is any contact structure over a three-manifold Y whose induced Spin^c structure has torsion first Chern class), $c(\kappa)$ is a homogeneous element whose absolute degree $\deg(c(\kappa))$ coincides with the Hopf invariant of κ . Finally, in Theorem 1.4 of [26], the invariant is shown to vanishing for overtwisted contact structures.

Proof of Corollary 1.7 According to Theorem 1.3 the degree of an element in filtration degree $-g$ (and hence, as above, the Hopf invariant of the induced homotopy class of two-plane field) is given by Equation (4). Note that the sign appearing in front of the signature occurs because, in the definition of $c(\kappa)$, we reverse the orientation on the ambient three-manifold, which is equivalent to reflecting the knot.

In the case where this Hopf invariant vanishes, the induced element in $\widehat{HF}(S^3)$ must be non-trivial, for it is the only generator in degree zero (again, according to Theorem 1.3). Thus, according to Theorem 1.4 of [26], the induced contact structure is tight. \square

Proof of Corollary 1.8 The fact that the Hopf invariant of κ is non-positive, follows readily from Equation (4), together with the fact that $j(\kappa) = 2g$.

Moreover, we have seen in Corollary 1.7 that the overtwisted contact structure with vanishing Hopf invariant cannot be represented by an alternating knot; while it is clear that unknot represents the tight contact structure.

Finally, using Equation (4), we see that for each $i > 0$, the i -fold connected sum of the figure eight knot realizes the contact structure with Hopf invariant $-i$. \square

4 Alternating links

Recall that in [27], we defined a generalization of the knot invariants \widehat{HFK} to the case of links. These link invariants satisfy a skein exact sequence (cf. Theorem 10.2 of [27]): suppose that ρ is a positive crossing for a projection of a link L_+ , for which both strands belong to the same component of L_+ , then there is a long exact sequence (for each $s \in \mathbb{Z}$) of the form:

$$\dots \rightarrow \widehat{HFK}(L_-; s) \xrightarrow{f} \widehat{HFK}(L_0; s) \xrightarrow{g} \widehat{HFK}(L_+; s) \rightarrow \dots \quad (8)$$

where L_- is the modified version of L_+ (with a crossing-change at ρ), and L_0 is the resolution at ρ of L_+ . Both maps f and g drop absolute grading by 1=2, where the remaining map is non-increasing on the absolute grading.

For the following statement, recall that a link L called a *non-split, alternating link* if it has a projection which is connected, and also, if we traverse any component of L , the crossings in this projection alternate between over-crossings and under-crossings.

Theorem 4.1 *Let $L \subset S^3$ be a non-split, oriented, alternating link in the three-sphere, and let P_L be its Alexander-Conway polynomial. Writing*

$$(T^{-1=2} - T^{1=2})^{n-1} P_L = a_0 + \sum_{s>0} a_s (T^s + T^{-s});$$

we have that $\widehat{HFK}(S^3; L; s)$ is supported entirely in dimension $s + \frac{\sigma(L)}{2}$, and indeed

$$\widehat{HFK}(S^3; L; s) = \mathbb{Z}^{j^{a_s j}}.$$

Here, $\sigma(L)$ is the signature of the link L .

Proof Recall first that the skein exact sequence can be used to show that

$$(\widehat{HFK}(S^3; L; i)) = a_i$$

(cf. [27]).

In view of this calculation, the theorem is obtained by induction on the number of components of L , with Theorem 1.3 as base case.

For the inductive step, let ρ be an intersection point where two different strands of L meet. We can find two links L_- and L_+ with one more intersection point q , both of which admit alternating projections, and which have the property that their resolution L_0 at q is our original L . The two cases, according to the sign of the intersection point ρ , are illustrated in Figure 10.

When ρ is a positive intersection point for L , we see that (after the obvious cancellation), L_- has one fewer positive intersection points than L does, while L_+ has one more positive intersection point. Moreover, the number of black regions (using the coloring conventions of Figure 9) are the same for all three links. If, on the other hand, ρ is a negative intersection point, then the number of black regions for L_- is one greater than number for L , which in turn is one greater than the number for L_+ . Moreover, the number of positive intersection

points is the same for all three. Thus, applying Theorem 3.1, we can conclude that in either case,

$$(L_-) - 1 = (L) = (L_+) + 1: \tag{9}$$

It is now straightforward to conclude the result for $L = L_0$ from the skein exact sequence, and the inductive hypothesis on L_- and L_+ . \square

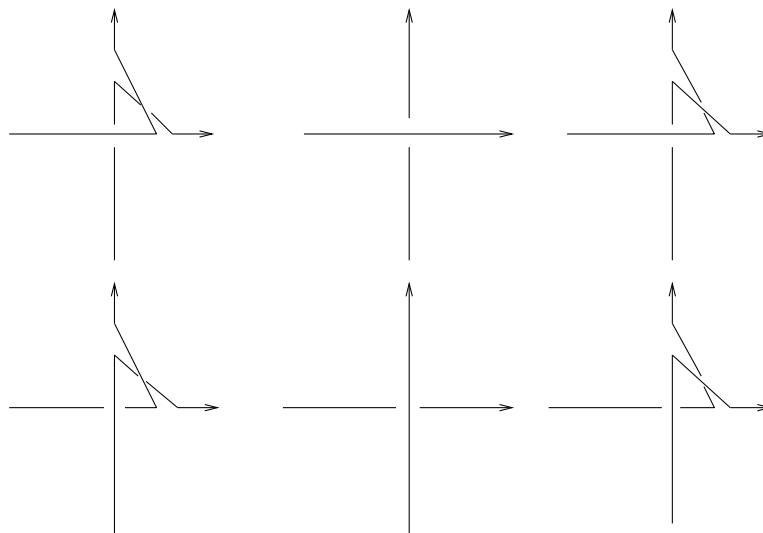


Figure 10: **Skein moves on alternating links** On the left, we have two possible candidates for L_- , in the middle we have the two versions of L , while on the right we have two candidates for L_+ . It is easy to see that if the links L are alternating, then the changes L_- and L_+ can also be arranged to alternate (after cancelling an extra pair of intersection points, if necessary).

Theorem 4.1 can be used to give easy generalizations to (non-split) alternating links of the results stated in the introduction for alternating knots. Rather than enumerating these, we use Theorem 4.1 to give a calculation of \widehat{HFK} for the (non-alternating) knot pictured on the left in Figure 11 (known as “9₄₈” according to the standard knot tables, cf. [3]).

If we change the indicated crossing, we obtain the right-handed trefoil K_- , which has

$$\begin{aligned} (K_-) &= -2 \\ K_- &= T^{-1} - 1 + T: \end{aligned}$$

If the knot crossing is resolved, we obtain the two-component link L pictured on the right in Figure 11 (given the specified orientation). It is straightforward

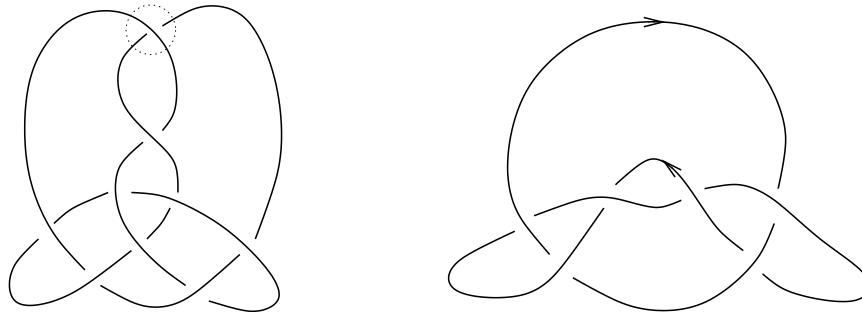


Figure 11: **The knot** 9_{48} We have illustrated this nine-crossing knot. If the crossing circled with a dotted circle is switched, we obtain the right-handed trefoil; while if the crossing is resolved, it is easy to see that we obtain the (oriented) alternating link pictured on the right.

to calculate that

$$\begin{aligned} (L) &= -1 \\ (T^{-1=2} - T^{1=2})_L &= T^{-2} - 6T^{-1} + 10 - 6T + T^2; \end{aligned}$$

It is now an immediate application of the skein exact sequence and Theorem 4.1 that the conclusion of Theorem 4.1 holds for 9_{48} (and hence also the conclusion of Theorem 1.4), even though 9_{48} does not possess an alternating projection.

More calculations of knot homology groups are given [29].

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