# COMPLICATED DYNAMICS IN NONAUTONOMOUS ODES 

by Leszek Pieniążek and Klaudiusz Wójcik


#### Abstract

We present a topological method for detecting complicated dynamics in nonautonomous ordinary differential equations (not necesserily periodic with respect to the time variable). Our main result gives a sufficient condition for the existence of a class of solutions, whose presence displays some chaotic features of the dynamics. The method is based on the Ważewski Retract Theorem and the Lefschetz Fixed Point Theorem. Some applications to the nonautonomous systems in the plane are considered.


1. Introduction. In this note we study a topological method for detecting complicated dynamics in the local processes generated by the nonautonomous ordinary differential equations (not necesserily periodic with respect to the time variable). We show the existence of a class of solutions, whose presence displays some chaotic features of the dynamics. The results presented here, in the same spirit as in [13], [15], [17] are inspired by a lot of papers on the existence of the multibump orbits ( 1 , [3], 6], [7], [5], [10]) starting with the novel minimax method in $\mathbf{1 2 ]}$. In the context of the Lagrangian systems, the multibump orbits mean the orbits which are close to chains of homoclinics of the limit system (see [1], [3] , [7]). The results of [3] are based on the variational version of the Birkhoff-Smale-Shilnikov theory. In contrast to the above method, we do not need any global information on particular solutions of the considered equation. Our method for detecting chaotic dynamics is based on the existence of some sets, called admissible proper sets and the knowledge of the values of some topological invariants of these sets. The notion of the proper pair is based on the concept of the Ważewski set ([4]) and is an inessential modification of the

[^0]periodic block in [13]. In the case that the right-hand side of the considered equation is periodic with respect to the time variable, our main result (up to slightly different notation) improves Th. 2 in [15] (cf. [17]). In fact, the method presented in this paper is adapted to the general nonautonomous systems from the periodic case in [15], [17], [19]. In order to apply the topological method introduced in [15], we have to prove the existence of some sets, called periodic isolating segments, in the extended phase space (see [15]). Basic property of the segment is that at any point on its boundary the vector field is directed outward or inward with respect to the segment (compare the notion of the isolating block in the Conley index theory). Notice that an admissible proper pair (in our sense) can be easily obtained by gluing translated copies of a periodic isolating segment. It was observed by Roman Srzednicki in [13] that the fixed point index of the Poincaré map inside the segment is equal to the Lefschetz number of the monodromy homeomorphism given by the segment (see Th.7.1 in [13]). Our Proposition 1 is a non-periodic version of this result. Theorem 2 in 15 gives a sufficient condition for the chaotic dynamics in the periodic systems in the sense that the Poincare map is semiconjugated to the shift on two symbols and the counterimage (by the semiconjugacy) of any periodic point in the shift contains a periodic point of the Poincaré map. It follows by our Theorem 1 , that any small perturbation of the $T$-periodic system for which the results in [15] show chaos has also complicated dynamics. In the non-periodic case we are not able to prove the existence of periodic solutions but the map after time $T$ is still semiconjugated to the Bernoulli shift on some compact set. In particular, the topological entropy is positive.

In the paper, for practical reasons, we use notation for fixed point index different from that used in classical books like [8]. We understand the fixed point index for some subset of the set of fixed points which has an open neighbourhood as the fixed point index in that open set.
2. Proper pairs. Assume that $X$ is a metric space and $\varphi: D \rightarrow X$ is a continuous mapping, $D \subset \mathbb{R} \times X \times \mathbb{R}$ is an open set. We will denote by $\varphi_{(\sigma, t)}$ the function $\varphi(\sigma, \cdot, t)$.
$\varphi$ is called a local process if the following conditions are satisfied
(1) $\forall \sigma \in \mathbb{R}, x \in X:\{t \in \mathbb{R}:(\sigma, x, t) \in D\}$ is an interval,
(2) $\forall \sigma \in \mathbb{R}: \varphi_{(\sigma, 0)}=\operatorname{id}_{X}$
(3) $\forall \sigma \in \mathbb{R}: \varphi_{(\sigma, s+t)}=\varphi_{(\sigma+s, t)} \circ \varphi_{(\sigma, s)}$,

If $D=\mathbb{R} \times X \times \mathbb{R}$, we call $\varphi$ a (global) process. For $(\sigma, x) \in \mathbb{R} \times X$ the set

$$
\left\{\left(\sigma+t, \varphi_{(\sigma, t)}(x)\right) \in \mathbb{R} \times X:(\sigma, x, t) \in D\right\}
$$

is called the trajectory of $(\sigma, x)$ in $\varphi$. If $T$ is a positive number such that

$$
\begin{equation*}
\forall \sigma, t \in \mathbb{R}: \varphi_{(\sigma+T, t)}=\varphi_{(\sigma, t)} \tag{4}
\end{equation*}
$$

we call $\varphi$ a $T$-periodic local process. It follows that the interval in (1) is open and, by (2), it contains 0 . Since the domains of the both maps in (3) are equal, $(\sigma, x, s+t) \in D$ if and only if $(\sigma, x, s) \in D$ and $\left(\sigma+s, \varphi_{(\sigma, s)}(x), t\right) \in D$.

A local process $\varphi$ on $X$ determines a local flow $\Phi$ on $\mathbb{R} \times X$ by the formula

$$
\Phi_{t}(\sigma, x)=\left(\sigma+t, \varphi_{(\sigma, t)}(x)\right) .
$$

Remark 1. The differential equation

$$
\text { (*) } \dot{x}=f(t, x)
$$

such that $f$ is regular enough to guarantee the uniqueness of solutions of Cauchy problems associated to $(*)$ generates a local process as follows. For $x\left(t_{0}, x_{0} ; \cdot\right)$, the solution of $(*)$ such that $x\left(t_{0}, x_{0} ; t_{0}\right)=x_{0}$, we put

$$
\varphi_{\left(t_{0}, \tau\right)}\left(x_{0}\right)=x\left(t_{0}, x_{0} ; t_{0}+\tau\right) .
$$

If $f$ is $T$-periodic with respect to $t$ then $\varphi$ is a $T$-periodic local process and in order to determine all $T$-periodic solutions of the equation (*) it suffices to look for fixed points of $\varphi_{(0, T)}$ (called the Poincaré map).

We will use the following notation: by $\pi_{1}: \mathbb{R} \times X \rightarrow \mathbb{R}$ and $\pi_{2}: \mathbb{R} \times X \rightarrow X$ we denote the projections and for every $Z \subset \mathbb{R} \times X$ and $t \in \mathbb{R}$ we put

$$
Z_{t}=\{x \in X:(t, x) \in Z\} .
$$

Let $\left(U, U^{-}\right)$be a pair of subsets of $\mathbb{R} \times X$ (i.e. $\left.U^{-} \subset U \subset \mathbb{R} \times X\right)$. We call $\left(U, U^{-}\right)$a proper pair (for the process $\varphi$ ) and $U^{-}$the exit set of $U$ if:
(i) $U$ and $U^{-}$are closed ENR's, $U_{0}, U_{0}^{-}$are compact,
(ii) there exists a homeomorphism

$$
h: \mathbb{R} \times\left(U_{0}, U_{0}^{-}\right) \longrightarrow\left(U, U^{-}\right)
$$

such that $\pi_{1}=\pi_{1} \circ h$,
(iii) for every $\sigma \in \mathbb{R}$ and $x \in \partial U_{\sigma}$ there exists a $t \in \mathbb{R}$ such that $\varphi_{(\sigma, t)}(x) \notin$ $U_{\sigma+t}$,
(iv) $U^{-}=\left\{(\sigma, x) \in U: \exists s_{n}>0 s_{n} \rightarrow 0: \varphi_{\left(\sigma, s_{n}\right)}(x) \notin U_{\sigma+s_{n}}\right\}$.

Define a map

$$
\tau_{U}: U \ni(\sigma, x) \longrightarrow \sup \left\{t \geq 0: \forall s \in[0, t]: \Phi_{s}(\sigma, x) \in U\right\} \in[0, \infty] .
$$

$\tau_{U}$ is continuous (by the argument in a proof of the Ważewski Theorem, [4], [13).

Let $\left(U, U^{-}\right)$be a proper pair, $U_{a}=U_{b}, U_{a}^{-}=U_{b}^{-}$for some $a, b \in \mathbb{R}, a<b$. Define a homeomorphism

$$
h_{a, b}:\left(U_{a}, U_{a}^{-}\right) \longrightarrow\left(U_{b}, U_{b}^{-}\right)=\left(U_{a}, U_{a}^{-}\right)
$$

by $h_{a, b}(x)=\pi_{2}\left(h\left(b, \pi_{2} h^{-1}(a, x)\right)\right)$ for $x \in U_{a}$.

Geometrically, $h_{a, b}$ moves a point $x \in U_{a}$ to $U_{b}=U_{a}$ along the $\operatorname{arc} h([a, b] \times$ $\left.\left\{\pi_{2} h^{-1}(a, x)\right\}\right)$. Consider the automorphism

$$
\mu_{U_{a, b}}: H\left(U_{a}, U_{a}^{-}\right) \longrightarrow H\left(U_{a}, U_{a}^{-}\right)
$$

induced by $h_{a, b}$ in the singular homology with rational coefficients. Recall that its Lefschetz number is defined as

$$
\operatorname{Lef}\left(\mu_{U_{a, b}}\right)=\sum_{n=0}^{\infty}(-1)^{n} \operatorname{tr} H_{n}\left(h_{a, b}\right)
$$

In particular, if $\mu_{U_{a, b}}=\operatorname{id}_{H\left(U_{a}, U_{a}^{-}\right)}$then $\operatorname{Lef}\left(\mu_{U_{a, b}}\right)$ is equal to the Euler characteristic $\chi\left(U_{a}, U_{a}^{-}\right)$.

In the sequel we will use the following non-periodic version of the Theorem 7.1 in 13

Proposition 1. If $\left(U, U^{-}\right)$is a proper pair, $U_{a}=U_{b}, U_{a}^{-}=U_{b}^{-}$for some $a, b \in \mathbb{R}, a<b$ then the set

$$
F_{U_{a, b}}=\left\{x \in X: \varphi_{(a, b-a)}(x)=x, \forall t \in[0, b-a]: \varphi_{(a, t)}(x) \in U_{a+t}\right\}
$$

is compact and open in the set of fixed points of $\varphi_{(a, b-a)}$ and the fixed point index of $\varphi_{(a, b-a)}$ in $F_{U_{a, b}}$ is given by

$$
\operatorname{ind}\left(\varphi_{(a, b-a)}, F_{U_{a, b}}\right)=\operatorname{Lef}\left(\mu_{U_{a, b}}\right)
$$

Proof. Our proof of Proposition 1 is simpler but similar in the spirit to the proof of Theorem 7.1 in [13]. By Lemma 2.3.1 in 14$] F_{U_{a, b}}$ is compact and open in the set of fixed points of the $\varphi_{(a, b-a)}$. Let $\tau=\tau_{U}: U \rightarrow[0, \infty]$. For $s \in[a, b]$ we define a homeomorphism

$$
h_{s, b}:\left(U_{s}, U_{s}^{-}\right) \rightarrow\left(U_{b}, U_{b}^{-}\right),
$$

by $h_{s, b}(x)=\pi_{2} h\left(b, \pi_{2} h^{-1}(s, x)\right)$. Consider a homotopy $H:\left(U_{a}, U_{a}^{-}\right) \times[0,1] \rightarrow$ $\left(U_{b}, U_{b}^{-}\right)=\left(U_{a}, U_{a}^{-}\right)$given by

$$
H(x, t)= \begin{cases}h_{a+\tau(a, x), b}\left(\varphi_{(a, \tau(a, x))}(x)\right), & \tau(a, x) \leq(1-t)(b-a) \\ \left.h_{a+(1-t)(b-a), b}\left(\varphi_{(a,(1-t)(b-a))}\right)(x)\right), & \tau(a, x) \geq(1-t)(b-a)\end{cases}
$$

Put $H_{t}(x)=H(x, t)$. It is easy to check that $H_{t}(x)=h_{a, b}(x)$ for $x \in U_{a}^{-}$, $t \in[0,1]$ and $H_{1}=h_{a, b}$. By the homotopy property of the Lefschetz number,

$$
\operatorname{Lef}\left(h_{a, b}\right)=\operatorname{Lef}\left(H_{0}\right)
$$

Moreover,

$$
\operatorname{Lef}\left(H_{0}\right)=\operatorname{ind}\left(\varphi_{(a, b-a)}, F_{U_{a, b}}\right)+\operatorname{ind}\left(H_{0}, \operatorname{Fix}\left(\left.h_{a, b}\right|_{U_{a}^{-}}\right)\right),
$$

and by the commutativity property of the fixed point index

$$
\operatorname{ind}\left(H_{0}, \operatorname{Fix}\left(\left.h_{a, b}\right|_{U_{a}^{-}}\right)\right)=\operatorname{Lef}\left(\left.h_{a, b}\right|_{U_{a}^{-}}\right)
$$

thus the proof is complete, because

$$
\operatorname{Lef}\left(\mu_{U_{a, b}}\right)=\operatorname{Lef}\left(h_{a, b}\right)-\operatorname{Lef}\left(\left.h_{a, b}\right|_{U_{a}^{-}}\right) .
$$

3. Main result. Let $\left(U, U^{-}\right)$be a proper pair for the process $\varphi$. We call $U$ admissible iff there is a sequence $\left\{t_{n}\right\}_{n \in \mathbb{Z}} \subset \mathbb{R}$ such that $t_{n}<t_{n+1}, U_{t_{n}}=U_{t_{0}}$, $U_{t_{n}}^{-}=U_{t_{0}}^{-}$for all $n \in \mathbb{Z}$.

Suppose that $\left(U, U^{-}\right),\left(Z, Z^{-}\right)$are proper pairs, $U \subset Z$ are admissible with the same sequence $\left\{t_{n}\right\}_{n \in \mathbb{Z}}$ unbounded from both below and above, $U_{t_{0}}=Z_{t_{0}}$, $U_{t_{0}}^{-}=Z_{t_{0}}^{-}$. Assume that for any $n \in \mathbb{Z}$ there is an $s \in\left(t_{n}, t_{n+1}\right)$ such that $U_{s} \neq Z_{s}$.
Consider the following conditions
(a) for all $n \in \mathbb{Z} \mu_{U_{t_{n}, t_{n+1}}}=\operatorname{id}_{H\left(U_{t_{0}}, U_{t_{0}}^{-}\right.}$,
(b) there is an $n_{0} \in \mathbb{N} \backslash\{1\}$ and an authomorphism $G: H\left(U_{t_{0}}, U_{t_{0}}^{-}\right) \rightarrow$ $H\left(U_{t_{0}}, U_{t_{0}}^{-}\right)$such that $G^{n_{0}}=\operatorname{id}_{H\left(U_{t_{0}}, U_{t_{0}}^{-}\right)}$, for all $n \in\left\{1, \ldots, n_{0}-1\right\}$ $\operatorname{Lef}\left(G^{n}\right)=\operatorname{Lef}(G)$ and $\mu_{Z_{t_{n}, t_{n+1}}}=G(n \in \mathbb{N})$,
(c) $\operatorname{Lef}(G) \neq \chi\left(U_{t_{0}}, U_{t_{0}}^{-}\right) \neq 0$.

Remark 2. Let us consider the planar differential equation

$$
\dot{z}=\mathrm{e}^{i t} \bar{z}^{n}
$$

From the phase portrait one can deduce (comp. 13) the existence of the admissible proper pair $Z$ with the sequence $t_{k}=2 \pi k$ such that $Z_{0}$ is a regular $2(n+1)$-gon, $Z_{0}^{-}$consists of $n+1$ disjoint segments and both the sets $Z_{0}$ and $Z_{0}^{-}$are invariant with respect to the rotation by the angle $\frac{2 \pi}{n+1}$. It is easy to see that

$$
\begin{gathered}
\operatorname{Lef}\left(\mu_{Z_{t_{k}, t_{k+1}}}\right)=\ldots=\operatorname{Lef}\left(\mu_{Z_{t_{k}, t_{k+1}}}^{n}\right)=1, \\
\mu_{Z_{t_{k}, t_{k+1}}}^{n+1}=\operatorname{id}_{H\left(Z_{0}, Z_{0}^{-}\right)},
\end{gathered}
$$

so the condition (b) holds with $n_{0}=n+1$.
We will prove the following
Theorem 1. Under assumptions (a), (b), (c) for any subset $S \subset \mathbb{Z}$ there is $x_{0} \in U_{t_{0}}$ such that
(1) for all $t \in \mathbb{R}, \varphi_{\left(t_{0}, t\right)}\left(x_{0}\right) \in Z_{t_{0}+t}$
(2) if $n \in S$ then there exists $t \in\left(t_{n}-t_{0}, t_{n+1}-t_{0}\right)$ such that $\varphi_{\left(t_{0}, t\right)}\left(x_{0}\right) \notin U_{t_{0}+t}$,
(3) if $n \notin S$ then for all $t \in\left[t_{n}-t_{0}, t_{n+1}-t_{0}\right], \varphi_{\left(t_{0}, t\right)}\left(x_{0}\right) \in U_{t_{0}+t}$.

For $S \subset \mathbb{Z}$, by $U^{S}$ we denote the proper pair such that if $n \in S$ then

$$
U^{S} \cap\left(\left[t_{n}, t_{n+1}\right] \times X\right)=Z \cap\left(\left[t_{n}, t_{n+1}\right] \times X\right),
$$

and if $n \notin S$ then

$$
U^{S} \cap\left(\left[t_{n}, t_{n+1}\right] \times X\right)=U \cap\left(\left[t_{n}, t_{n+1}\right] \times X\right)
$$

Assume that $S$ is a finite set and $\operatorname{card}(S)=k$ for some $k \in \mathbb{N}$. Let $S=$ $\left\{n_{1}, \ldots, n_{k}\right\}, a, b \in\left\{t_{n}: n \in \mathbb{Z}\right\}$ and $a<t_{n_{1}}<\ldots<t_{n_{k}}<b$. Recall that the set

$$
F_{U_{a, b}^{S}}=\left\{x \in X: \varphi_{(a, b-a)}(x)=x, \forall t \in[0, b-a]: \varphi_{(a, t)}(x) \in U_{a+t}^{S}\right\}
$$

is compact and open in the set of fixed points of $\varphi_{(a, b-a)}$. Observe that if $n \in S$, $x \in F_{U_{a, b}^{S}}$ then $\tau_{U}\left(\varphi_{\left(a, t_{n}-a\right)}(x)\right) \neq t_{n+1}-t_{n}$. For any subset $L \subset S$ by $F^{L}$ we denote the set of points $x \in F_{U_{a, b}^{S}}$ such that if $n \in L$ then $\tau_{U}\left(\varphi_{\left(a, t_{n}-a\right)}(x)\right)<$ $t_{n+1}-t_{n}$ and if $n \in S \backslash L$ then $\tau_{U}\left(\varphi_{\left(a, t_{n}-a\right)}(x)\right)>t_{n+1}-t_{n}$. The sets $F^{L}$ over all subsets $L \subset S$ form a compact and disjoint covering of $F_{U_{a, b}^{S}}$. The proof of Theorem 11 is based on the following

Lemma 1. If $\operatorname{card}(S)=k$ then

$$
\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right)=\sum_{l=0}^{k}(-1)^{k-l}\binom{k}{l} \operatorname{Lef}\left(G^{l}\right)
$$

Proof. The case $k=0$ follows immediately from Proposition 1. For $k \geq 1$ we use the induction with respect to $k$. Let $k=1$. Since $F^{S}$ and $F^{\emptyset}$ form a compact and disjoint covering of $F_{U_{a, b}^{S}}$, by the additivity property of the fixed point index,

$$
\operatorname{ind}\left(\varphi_{(a, b-a)}, F_{U_{a, b}^{S}}\right)=\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right)+\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{\emptyset}\right)
$$

hence by Proposition 1

$$
\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right)=\operatorname{Lef}(G)-\chi\left(U_{t_{0}}, U_{t_{0}}^{-}\right)
$$

Assume now that the lemma holds for $p \leq k$. We prove it for $k+1$. Again by the additivity of the fixed point index,

$$
\operatorname{ind}\left(\varphi_{(a, b-a)}, F_{U_{a, b}^{S}}\right)=\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right)+\sum_{L \subset S, L \neq S} \operatorname{ind}\left(\varphi_{(a, b-a)}, F^{L}\right)
$$

By Proposition 1 and the inductive step,

$$
\begin{aligned}
\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right) & =\operatorname{Lef}\left(G^{k+1}\right)-\sum_{s=0}^{k}\binom{k+1}{s} \sum_{l=0}^{s}(-1)^{s-l}\binom{s}{l} \operatorname{Lef}\left(G^{l}\right) \\
& =\operatorname{Lef}\left(G^{k+1}\right)-\sum_{s=0}^{k} \sum_{l=0}^{s}(-1)^{s-l}\binom{k+1}{s}\binom{s}{l} \operatorname{Lef}\left(G^{l}\right) \\
& =\operatorname{Lef}\left(G^{k+1}\right)-\sum_{s=0}^{k} \sum_{l=0}^{s}(-1)^{s-l}\binom{k+1}{l}\binom{k+1-l}{k+1-s} \operatorname{Lef}\left(G^{l}\right) .
\end{aligned}
$$

Let $s_{0} \in\{0, \ldots, k\}$ be fixed. We show that the coefficient of $\operatorname{Lef}\left(G^{s_{0}}\right)$ equals $(-1)^{k+1-s_{0}}\binom{k+1}{s_{0}}$. It is easy to see that this coefficient is equal to

$$
\left[-\sum_{r=s_{0}}^{k}(-1)^{r-s_{0}}\binom{k+1-s_{0}}{k+1-r}\right]\binom{k+1}{s_{0}} .
$$

We put $m=k+1-s_{0}$. Then

$$
\sum_{r=s_{0}}^{k}(-1)^{r-s_{0}}\binom{k+1-s_{0}}{k+1-r}=\sum_{w=0}^{m-1}(-1)^{w}\binom{m}{m-w}=\sum_{w=0}^{m-1}(-1)^{w}\binom{m}{w}
$$

By

$$
\sum_{w=0}^{m}(-1)^{w}\binom{m}{w}=0
$$

we conclude that if $m=k+1-s_{0}$ is even then $\sum_{w=0}^{m-1}(-1)^{w}\binom{m}{w}=-1$ and if $m=k+1-s_{0}$ is odd then $\sum_{w=0}^{m-1}\binom{m}{w}=1$. This finishes the proof.

Corollary 1. (1) Under the assumptions of Theorem 1, if $\operatorname{card}(S)=k$ then

$$
\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right)=\left(\sum_{n_{0} \mid s}(-1)^{k-s}\binom{k}{s}\right)\left(\chi\left(U_{t_{0}}, U_{t_{0}}^{-}\right)-\operatorname{Lef}(G)\right)
$$

(2) In particular, if $n_{0}$ is even then $\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right) \neq 0$ and if $n_{0}$ is odd then $\operatorname{ind}\left(\varphi_{(a, b-a)}, F^{S}\right) \neq 0$ iff $k$ is not an odd multiplicity of $n_{0}$.

Proof. (1) This follows from Lemma 1, because $\sum_{s=0}^{k}(-1)^{k-s}\binom{k}{s}=0$ and

$$
\operatorname{Lef}\left(G^{l}\right)= \begin{cases}\chi\left(U_{t_{0}}, U_{t_{0}}^{-}\right), & n_{0} \mid l \\ \operatorname{Lef}(G), & \text { otherwise. }\end{cases}
$$

(2) If $n_{0}$ is even then $(-1)^{k-s}=(-1)^{k}$ for all $s$ such that $n_{0} \mid s$, so the conclusion follows by (1). The case of $n_{0}$ odd will be proved in Corollary 2 in the appendix.

Proof of Theorem 1. Assume first that $S$ is a finite set and $n_{0}$ is even or $\operatorname{card}(S)$ is even multiplicity of $n_{0}$.

Let $a_{n}=t_{-n}, b_{n}=t_{n}$ (one can see that $a_{n} \rightarrow-\infty, b_{n} \rightarrow+\infty$ ). If $a_{n}$ is sufficiently small and $b_{n}$ sufficiently large then by Corollary 1(2) there is $y_{n} \in F^{S} \subset F_{U_{a_{n}, b_{n}}^{S}}$. By the compactness of $U_{t_{0}}$, there is a subsequence of the sequence $\left\{\varphi_{\left(a_{n}, t_{0}-a_{n}\right)}\left(y_{n}\right)\right\} \subset U_{t_{0}}$ which converges to some $x_{0} \in U_{t_{0}}$. The standard arguments show that the trajectory of $x_{0}$ is defined on the whole real line. Conditions (1) and (3) are easy to verify, thus it remains to prove (2). Let $t_{m_{0}} \in S$ be fixed. Because

$$
\varphi_{\left(a, t_{m_{0}}-a\right)}\left(y_{n}\right)=\varphi_{\left(t_{0}, t_{m_{0}}-t_{0}\right)}\left(\varphi_{\left(a, t_{0}-a\right)}\left(y_{n}\right)\right)
$$

by the continuity of $\tau_{U}$,

$$
\tau_{U}\left(\varphi_{\left(a, t_{m_{0}}-a\right)}\left(y_{n}\right)\right) \rightarrow \tau_{U}\left(\varphi_{\left(t_{0}, t_{m_{0}}-t_{0}\right)}\left(x_{0}\right)\right)
$$

On the other hand, by the definition of the sequence $\left\{y_{n}\right\}$ there is

$$
0<\tau_{U}\left(\varphi_{\left(a, t_{m_{0}}-a\right)}\left(y_{n}\right)\right)<t_{m_{0}+1}-t_{m_{0}}
$$

thus

$$
0 \leq \tau_{U}\left(\varphi_{\left(t_{0}, t_{n_{0}}-t_{0}\right)}\left(x_{0}\right)\right) \leq t_{m_{0}+1}-t_{m_{0}}
$$

Because $\tau_{Z}\left(x_{0}\right)=+\infty, Z_{t_{m_{0}}}^{-}=U_{t_{m_{0}}}^{-}$and $Z_{t_{m_{0}+1}}^{-}=U_{t_{m_{0}+1}}^{-}$, we in fact obtain

$$
0<\tau_{U}\left(\varphi_{\left(t_{0}, t_{m_{0}}-t_{0}\right)}\left(x_{0}\right)<t_{m_{0}+1}-t_{m_{0}}\right.
$$

so (2) holds.
If $\operatorname{card}(S)$ is an odd multiplicity of an odd $n_{0}$ then taking $S_{m}=S \cup\{m\}$ for a large $m$ we will find points $x_{m}$ satisfying (1), (2), (3) with $S$ replaced by $S_{m}$. The sequence $\left\{x_{m}\right\}$ has a subsequence convergent to some point $x$ and it satisfies the thesis.

If $S$ is an infinite set then we use the proved finite case and similar arguments based on the compactness of $U_{t_{0}}$.
4. Periodic case. Assume that the vector field $f$ (on a manifold $M$ ) is $T$-periodic $(T>0)$ with respect to the time variable. Let $U$ and $Z$ be two proper sets such that assumptions $(a),(b),(c)$ hold with the sequence $t_{n}=n T$ $(n \in \mathbb{Z})$. As a corollary we obtain

Theorem 2. (1) There are a compact set $I \subset M$ invariant with respect to the Poincaré map $\varphi_{(0, T)}$ and a continuous surjective map $g: I \rightarrow \Sigma_{2}$ such that $\varphi_{(0, T)}$ is semiconjugated to the shift $\sigma: \Sigma_{2} \rightarrow \Sigma_{2}$ by the map $g$ in $I$.
(2) If $n_{0}$ is even then for every $n$-periodic sequence $s \in \Sigma_{2}$ its counterimage by $g$ contains at least one $n$-periodic point of the Poincaré map.
(3) If $n_{0}$ is odd and $s \in \Sigma_{2}$ is an $n$-periodic sequence in which the symbol 1 appears $k$-times in every block of length $n, k$ is not an odd multiplicity of $n_{0}$ then the counterimage of $s$ by $g$ contains an $n$-periodic point of $\varphi_{(0, T)}$.

Proof. The set $I$ and map $g$ are defined in the same way they are in [15]. The surjectivity of $g$ follows from the density of periodic orbits in $\Sigma_{2}$ and Corollary 1.

Remark 3. Let $U$ and $W$ be two periodic isolating segments over $[0, T]$ for the equation $(*)$ (see $[\mathbf{1 5}$ for the definition). Suppose that $U$ and $W$ fulfil the assumptions of Theorem 2 in [15 (see also [17], [18, [19] for examples of concrete differential equations). We define two admissible proper pairs $\tilde{U}, \tilde{W}$ by the conditions

$$
\begin{aligned}
\tilde{U}_{t} & =U_{t \bmod T} \\
\tilde{W}_{t} & =W_{t \bmod T}
\end{aligned}
$$

for $t \in \mathbb{R}$. It follows that all assumptions of our Theorem 1 hold for $\tilde{U}, \tilde{W}$ with $t_{n}=n T$, so for any sufficiently small (not necessarily $T$-periodic) perturbation of system (*) there is a compact set $\Lambda$ which is invariant with respect to $\varphi_{(0, T)}$ and $\varphi_{(0, T)}$ restricted to $\Lambda$ is semiconjugated to the Bernoulli shift with two symbols. In particular, the topological entropy of $\varphi_{(0, T)}$ is positive.
5. Applications. In the present section we consider the following planar nonautonomous equation of the variable $z \in \mathbb{C}$

$$
\begin{equation*}
\dot{z}=\left(1+\left(\cos \left(t^{2}\right)+2\right) e^{i \phi t}|z|^{2}\right) \bar{z} \tag{5.1}
\end{equation*}
$$

for some $\phi \in \mathbb{R}$.
Theorem 3. Equation (5.1) fulfils the assumptions of Theorem 1 for sufficiently small $\phi>0$.
Although a proof is similar to the proof of Th. 2 in [15], we give it in a detailed way for the sake of completeness. Our proof of Theorem 3 consists of the construction of two proper pairs $U$ and $Z$ (admissible with $t_{n}=\frac{2 \pi}{\phi} n$ ) satisfying conditions (a), (b), and (c) in Theorem 1. $Z$ will be a twisted prism with a square base centered at the origin. Its cross-sections $Z_{t}$ will be obtained by rotating the base with the angle velocity $\phi / 2$ over the $t$-interval $[0,2 \pi / \phi]$. The set $U$ will be a regular square-based prism with broadening ends. Its crosssections $U_{t}$ corresponding to $t$ near the centre of the interval will have the
small side and they will broaden when $t$ approaches the ends of the interval (because $U, Z$ should have a common cross-section $U_{t}$ for $t \in\{0,2 \pi / \phi\}$ ).

The remainder of this section will be devoted to a proof of the above theorem. Equation (5.1) coincides with the system of two planar equations:

$$
\left\{\begin{array}{l}
\dot{x}=x+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)(x \cos (\phi t)+y \sin (\phi t))  \tag{5.2}\\
\dot{y}=-y+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)(x \sin (\phi t)-y \cos (\phi t))
\end{array}\right.
$$

By $F$ we denote the vector field in the extended phase space $\mathbb{R}^{3}$ generated by the right-hand side of system (5.2), i.e.

$$
F(t, x, y)=\left(\begin{array}{c}
1 \\
x+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)(x \cos (\phi t)+y \sin (\phi t)) \\
-y+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)(x \sin (\phi t)-y \cos (\phi t))
\end{array}\right)
$$

In the sequel we assume that $\phi>0$. In order to construct $U$ and $Z$ we will introduce several auxiliary functions and sets. Let $R>0$. Put

$$
\begin{aligned}
\Lambda_{R}^{1}(t, x, y) & =\frac{1}{R^{2}}\left(x \cos \left(\frac{\phi}{2} t\right)+y \sin \left(\frac{\phi}{2} t\right)\right)^{2}-1 \\
\Lambda_{R}^{2}(t, x, y) & =\frac{1}{R^{2}}\left(x \sin \left(\frac{\phi}{2} t\right)-y \cos \left(\frac{\phi}{2} t\right)\right)^{2}-1
\end{aligned}
$$

and

$$
\begin{aligned}
& L_{R}=\left\{(t, x, y) \in \mathbb{R}^{3}: \Lambda_{R}^{i}(t, x, y) \leq 0, i=1,2\right\} \\
& L_{R}^{-}=\left\{(t, x, y) \in \mathbb{R}^{3}: \Lambda_{R}^{1}(t, x, y)=0, \Lambda_{R}^{2}(t, x, y) \leq 0\right\} \\
& L_{R}^{+}=\left\{(t, x, y) \in \mathbb{R}^{3}: \Lambda_{R}^{1}(t, x, y) \leq 0, \Lambda_{R}^{2}(t, x, y)=0\right\}
\end{aligned}
$$

Lemma 2. If $\phi \leq 1$ and $R \geq 3$ then

$$
\begin{array}{cc}
F(t, x, y) \cdot \nabla \Lambda_{R}^{1}(t, x, y)>0 & \left((t, x, y) \in L_{R}^{-}\right) \\
F(t, x, y) \cdot \nabla \Lambda_{R}^{2}(t, x, y)<0 & \left((t, x, y) \in L_{R}^{+}\right) \tag{5.4}
\end{array}
$$

Proof. We omit the proof, since the lemma is essentially the same as one in 15.

Now let $r>0$ and put

$$
\begin{aligned}
\Xi_{r}^{1}(t, x, y) & =\frac{1}{r^{2}} x^{2}-1 \\
\Xi_{r}^{2}(t, x, y) & =\frac{1}{r^{2}} y^{2}-1
\end{aligned}
$$

and

$$
\begin{aligned}
& K_{r}=\left\{(t, x, y) \in \mathbb{R}^{3}: \Xi_{r}^{i}(t, x, y) \leq 0, i=1,2\right\} \\
& K_{r}^{-}=\left\{(t, x, y) \in \mathbb{R}^{3}: \Xi_{r}^{1}(t, x, y)=0, \Xi_{r}^{2}(t, x, y) \leq 0\right\} \\
& K_{r}^{+}=\left\{(t, x, y) \in \mathbb{R}^{3}: \Xi_{r}^{1}(t, x, y) \leq 0, \Xi_{r}^{2}(t, x, y)=0\right\}
\end{aligned}
$$

Lemma 3. For an arbitrary $\phi$ and $r \leq \frac{1}{4}$,

$$
\begin{array}{cc}
F(t, x, y) \cdot \nabla \Xi_{r}^{1}(t, x, y)>0 & \left((t, x, y) \in K_{r}^{-}\right), \\
F(t, x, y) \cdot \nabla \Xi_{r}^{2}(t, x, y)<0 & \left((t, x, y) \in K_{r}^{+}\right) . \tag{5.6}
\end{array}
$$

Proof. There is

$$
\begin{align*}
& F(t, x, y) \cdot \nabla \Xi_{r}^{1}(t, x, y)  \tag{5.7}\\
& \quad=\frac{2}{r^{2}}\left(x^{2}+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)\left(x^{2} \cos (\phi t)+x y \sin (\phi t)\right)\right. \\
& F(t, x, y) \cdot \nabla \Xi_{r}^{2}(t, x, y)  \tag{5.8}\\
& \quad=\frac{2}{r^{2}}\left(-y^{2}+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)\left(x y \sin (\phi t)-y^{2} \cos (\phi t)\right)\right.
\end{align*}
$$

For any $(t, x, y) \in K_{r}^{-}$, there is $|x|=r$ and $|y| \leq r$, hence, by (5.7),

$$
F(t, x, y) \cdot \nabla \Xi_{r}^{1}(t, x, y) \geq \frac{2}{r^{2}}\left(r^{2}-6 r^{2} \cdot 2 r^{2}\right)=2-24 r^{2}
$$

and (5.5) is satisfied. If $(t, x, y) \in K_{r}^{+}$then by (5.8) it follows analogously that

$$
F(t, x, y) \cdot \nabla \Xi_{r}^{2}(t, x, y) \leq-2+24 r^{2}
$$

hence (5.6) follows, and Lemma 3 is proved.

Let $\omega>0, k \in \mathbb{Z}$ and $t \in\left[\frac{2 \pi}{\phi} k, \frac{2 \pi}{\phi} k+R / \omega\right]$. Put

$$
\begin{aligned}
\Pi_{R, \omega}^{1}(t, x, y) & =\frac{1}{\left(R-\omega\left(t-\frac{2 \pi}{\phi} k\right)\right)^{2}} x^{2}-1 \\
\Pi_{R, \omega}^{2}(t, x, y) & =\frac{1}{\left(R-\omega\left(t-\frac{2 \pi}{\phi} k\right)\right)^{2}} y^{2}-1
\end{aligned}
$$

and

$$
\begin{aligned}
& P_{r, R, \omega}=\left\{(t, x, y) \in\left[\frac{2 \pi}{\phi} k, \frac{2 \pi}{\phi} k+\frac{R-r}{\omega}\right] \times \mathbb{R}^{2}: \Pi_{R, \omega}^{i}(t, x, y) \leq 0, i=1,2\right\}, \\
& P_{r, R, \omega}^{+}=\left\{(t, x, y) \in\left[\frac{2 \pi}{\phi} k, \frac{2 \pi}{\phi} k+\frac{R-r}{\omega}\right] \times \mathbb{R}^{2}: \Pi_{R, \omega}^{1}(t, x, y)=0, \Pi_{R, \omega}^{2}(t, x, y) \leq 0\right\}, \\
& P_{r, R, \omega}^{+}=\left\{(t, x, y) \in\left[\frac{2 \pi}{\phi} k, \frac{2 \pi}{\phi} k+\frac{R-r}{\omega}\right] \times \mathbb{R}^{2}: \Pi_{R, \omega}^{1}(t, x, y) \leq 0, \Pi_{R, \omega}^{2}(t, x, y)=0\right\} .
\end{aligned}
$$

Lemma 4. For $\phi>0$ sufficiently small and $\omega \leq \frac{r}{2}$

$$
\begin{array}{cc}
F(t, x, y) \cdot \nabla \Pi_{R, \omega}^{1}(t, x, y)>0 & \left((t, x, y) \in P_{r, R, \omega}^{-}\right), \\
F(t, x, y) \cdot \nabla \Pi_{R, \omega}^{2}(t, x, y)<0 & \left((t, x, y) \in P_{r, R, \omega}^{+}\right) . \tag{5.10}
\end{array}
$$

Proof.

$$
\begin{gathered}
F(t, x, y) \cdot \nabla \Pi_{R, \omega}^{1}(t, x, y)=\frac{2 \omega x^{2}}{\left(R-\omega\left(t-\frac{2 \pi}{\phi} k\right)\right)^{3}}+ \\
\frac{2}{\left(R-\omega\left(t-\frac{2 \pi}{\phi} k\right)\right)^{2}}\left(x^{2}+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)\left(x^{2} \cos (\phi t)+x y \sin (\phi t)\right)\right), \\
F(t, x, y) \cdot \nabla \Pi_{R, \omega}^{2}(t, x, y)=\frac{2 \omega y^{2}}{\left(R-\omega\left(t-\frac{2 \pi}{\phi}\right)\right)^{3}}+ \\
\frac{2}{\left(R-\omega\left(t-\frac{2 \pi}{\phi}\right)\right)^{2}}\left(-y^{2}+\left(\cos \left(t^{2}\right)+2\right)\left(x^{2}+y^{2}\right)\left(x y \sin (\phi t)-y^{2} \cos (\phi t)\right)\right) .
\end{gathered}
$$

Let $\phi>0$ be so small that

$$
\begin{equation*}
\cos (\phi t)>0 \quad \text { for } t \in\left[\frac{2 \pi}{\phi} k, \frac{2 \pi}{\phi} k+\frac{R-r}{\omega}\right], \tag{5.11}
\end{equation*}
$$

and $(t, x, y) \in P_{R, \omega}^{-}$, so $|x|=R-\omega\left(t-\frac{2 \pi}{\phi} k\right)$ and $|y| \leq R-\omega\left(t-\frac{2 \pi}{\phi} k\right)$. For a sufficiently small $\phi>0$ we obtain

$$
\begin{gathered}
F(t, x, y) \cdot \nabla \Pi_{R, \omega}^{1}(t, x, y)>\frac{2 \omega}{r}+2-2\left(R-\omega\left(t-\frac{2 \pi}{\phi} k\right)\right)^{2} \phi\left(t-\frac{2 \pi}{\phi} k\right) \\
\geq 2-6 R^{2} \phi \frac{R-r}{\omega} \geq 1 .
\end{gathered}
$$

Similarly we conclude that if $(t, x, y) \in P_{R, \omega}^{+}$then for a sufficiently small $\phi>0$

$$
F(t, x, y) \cdot \nabla \Pi_{R, \omega}^{2}(t, x, y)<-2+\frac{2 \omega}{r}+6 R^{2} \phi \frac{R-r}{\omega} \leq-1+\frac{2 \omega}{r} .
$$

We have assumed that $\omega \leq r / 2$ thus the proof of Lemma 4 is finished.

For $t \in\left[\frac{2 \pi}{\phi} k-\frac{R-r}{\omega}, \frac{2 \pi}{\phi} k\right]$ we put

$$
\begin{gathered}
\Sigma_{R, \omega}^{1}(t, x, y)=\Pi_{R, \omega}^{1}\left(\frac{2 \pi}{\phi} k-t, x, y\right) \\
\Sigma_{R, \omega}^{2}(t, x, y)=\Pi_{R, \omega}^{2}\left(\frac{2 \pi}{\phi} k-t, x, y\right) \\
S_{r, R, \omega}=\left\{(t, x, y) \in\left[\frac{2 \pi}{\phi} k-\frac{R-r}{\omega}, \frac{2 \pi}{\phi} k\right] \times \mathbb{R}^{2}: \Sigma_{R, \omega}^{i}(t, x, y) \leq 0, i=1,2\right\} \\
S_{r, R, \omega}^{-}=\left\{(t, x, y) \in\left[\frac{2 \pi}{\phi} k-\frac{R-r}{\omega}, \frac{2 \pi}{\phi} k\right] \times \mathbb{R}^{2}: \Sigma_{R, \omega}^{1}(t, x, y)=0, \Sigma_{R, \omega}^{2}(t, x, y) \leq 0\right\} \\
S_{r, R, \omega}^{+}=\left\{(t, x, y) \in\left[\frac{2 \pi}{\phi} k-\frac{R-r}{\omega}, \frac{2 \pi}{\phi} k\right] \times \mathbb{R}^{2}: \Sigma_{R, \omega}^{1}(t, x, y) \leq 0, \Sigma_{R, \omega}^{2}(t, x, y)=0\right\}
\end{gathered}
$$

One can check that

Lemma 5. For a sufficiently small $\phi>0$,

$$
\begin{array}{ll}
F(t, x, y) \cdot \nabla \Sigma_{R, \omega}^{1}(t, x, y)>0 & \left((t, x, y) \in S_{r, R, \omega}^{-}\right) \\
F(t, x, y) \cdot \nabla \Sigma_{R, \omega}^{2}(t, x, y)<0 & \left((t, x, y) \in S_{r, R, \omega}^{+}\right) \tag{5.13}
\end{array}
$$

Lemma 6. If $\phi<\frac{2 \omega}{R}$ then $P_{r, R, \omega} \subset L_{R}$ and $S_{r, R, \omega} \subset L_{R}$.
Proof. Essentially, it is lemma 6 in $\mathbf{1 5}$.
Proof of Theorem 2, All the estimates in the above lemmas are satisfied for $R=3, r=1 / 4, \omega=1 / 8$, and a sufficiently small $\phi>0$. Let us define

$$
\begin{gathered}
U=P_{\frac{1}{4}, 3, \frac{1}{8}} \cup K_{\frac{1}{4}} \cup S_{\frac{1}{4}, 3, \frac{1}{8}} \\
Z=L_{3}
\end{gathered}
$$

By Lemmas 2, 3, 4, and 5, pairs $\left(U, U^{-}\right)$and $\left(Z, Z^{-}\right)$are admissible proper pairs with the sequence $t_{n}=\frac{2 \pi}{\phi} n$, and

$$
\begin{aligned}
U_{0} & =Z_{0}=\left\{(x, y) \in \mathbb{R}^{2}:|x| \leq 3,|y| \leq 3\right\} \\
U_{0}^{-} & =Z_{0}^{-}=\left\{(x, y) \in \mathbb{R}^{2}:|x|=3,|y| \leq 3\right\}
\end{aligned}
$$

The set $Z$ is a twisted prism with a square base, its successive cross-sections $Z_{t}$ are obtained by the rotation of $Z_{0}$ by the angle $\phi t / 2(t \in \underset{\sim}{f}[0,2 \pi])$. Thus we can take the map $(x, y) \rightarrow(-x,-y)$ as a homeomorphism $\tilde{h}$ corresponding to $Z$. Hence

$$
\mu_{Z_{t_{n}, t_{n}+1}} \circ \mu_{Z_{t_{n}, t_{n}+1}}=\operatorname{id}_{H\left(U_{0}, U_{0}^{-}\right)}, \quad \operatorname{Lef}\left(\mu_{W}\right)=1
$$

$U$ is a regular square-based prism, broadening at $t_{n}$, hence

$$
\mu_{U_{t_{n}, t_{n}+1}}=\mathrm{id}_{H\left(U_{0}, U_{0}^{-}\right)}
$$

Moreover, $K_{\frac{1}{6}} \subset L_{3}$, so $U \subset Z$ and Lemma 6 is valid; hence

$$
\chi\left(U_{0}, U_{0}^{-}\right)=-1
$$

Thus all conditions (a), (b), and (c) are satisfied.
6. Appendix. Let $n$ be an odd natural number. For a $p \in \mathbb{N}$ and an $r \in \mathbb{Z}$, define:

$$
\begin{equation*}
S_{n}(p, r)=\sum_{\substack{0 \leq s \leq p \\ n \mid s-r}}(-1)^{s-r}\binom{p}{s} \tag{6.1}
\end{equation*}
$$

It is easy to check that

$$
S_{n}(0, r)= \begin{cases}(-1)^{r} & \text { if } r=k \cdot n \\ 0 & \text { otherwise }\end{cases}
$$

The following two lemmas gather some useful properties of $S_{n}(p, r)$
Lemma 7. $S_{n}(p, r)=S_{n}(p-1, r)+S_{n}(p-1, r-1)$.
Proof.

$$
\begin{aligned}
S_{n}(p, r) & =\sum_{\substack{0 \leq s \leq p \\
n \mid s-r}}(-1)^{s-r}\binom{p}{s} \\
& =\sum_{\substack{0 \leq s \leq p \\
n \backslash s-r}}(-1)^{s-r}\binom{p-1}{s-1}+\sum_{\substack{0 \leq s \leq p \\
n \mid s-r}}(-1)^{s-r}\binom{p-1}{s} \\
& =\sum_{\substack{1 \leq s \leq p \\
n \mid s-r}}(-1)^{s-r}\binom{p-1}{s-1}+\sum_{\substack{0 \leq s \leq p-1 \\
n \mid s-r}}(-1)^{s-r}\binom{p-1}{s} \\
& =\sum_{\substack{0 \leq s \leq p-1 \\
n \mid s+1-r}}(-1)^{s+1-r}\binom{p-1}{s}+\sum_{\substack{0 \leq s \leq p-1 \\
n \mid s-r}}(-1)^{s-r}\binom{p-1}{s} \\
& =\sum_{\substack{0 \leq s \leq p-1 \\
n \leq s-\mid r-1)}}(-1)^{s-(r-1)}\binom{p-1}{s}+\sum_{\substack{0 \leq s \leq p-1 \\
n \mid s-r}}(-1)^{s-r}\binom{p-1}{s} \\
& =S_{n}(p-1, r-1)+S_{n}(p-1, r) .
\end{aligned}
$$

Lemma 8. The bi-infinite sequence $\left\{S_{n}(p, r)\right\}_{r \in \mathbb{Z}}$ has the following properties:

1. $S_{n}(p, r)=-S_{n}(p, r+n)$;
2. $S_{n}(p, p / 2+\alpha)=S_{n}(p, p / 2-\alpha)$ for such $\alpha$ that $p / 2+\alpha \in \mathbb{Z}$.

Proof. The lemma is obvious for $p=0$.
Now suppose that it holds for $p-1$.
1.

$$
\begin{aligned}
S_{n}(p, r) & =S_{n}(p-1, r)+S_{n}(p-1, r-1) \\
& =-S_{n}(p-1, r+n)-S_{n}(p-1, r-1+n) \\
& =-S_{n}(p, r+n)
\end{aligned}
$$

2. 

$$
\begin{aligned}
S_{n}(p, p / 2+\alpha) & =S_{n}(p-1, p / 2+\alpha-1)+S_{n}(p-1, p / 2+\alpha) \\
& =S_{n}\left(p-1, \frac{(p-1)}{2}+\alpha-\frac{1}{2}\right)+S_{n}\left(p-1, \frac{(p-1)}{2}+\alpha+\frac{1}{2}\right) \\
& =S_{n}\left(p-1, \frac{(p-1)}{2}-\alpha+\frac{1}{2}\right)+S_{n}\left(p-1, \frac{(p-1)}{2}-\alpha-\frac{1}{2}\right) \\
& =S_{n}(p-1, p / 2-\alpha)+S_{n}(p-1, p / 2-\alpha-1) \\
& =S_{n}(p, p / 2-\alpha)
\end{aligned}
$$

Now we are ready to state an important property of numbers $S_{n}(p, r)$ :
Theorem 4.

$$
S_{n}(p, r) \begin{cases}=0 & \text { if } \frac{p-2 r}{n} \in 2 \mathbb{N}+1 \\ >0 & \text { if } \frac{p-2 r}{n} \in(4 k-1,4 k+1) \\ <0 & \text { if } \frac{p-2 r}{n} \in(4 k+1,4 k+3)\end{cases}
$$

for odd $n \in \mathbb{N}$ and all $p \geq n-1$.
Proof. Let $p=n-1$. Note that $\frac{p-2 r}{n}$ cannot be an odd number.
From the definition,

$$
S_{n}(n-1, r)=(-1)^{s-r}\binom{n-1}{s}
$$

where $s \in\{0,1, \ldots, n-1\}$ is such a number that there exists $k \in \mathbb{N}$ with $s-r=k n$. But $(-1)^{s-r}=(-1)^{k n}=(-1)^{k}=(-1)^{\frac{s-r}{n}}=(-1)^{\frac{r-s}{n}}$, so

$$
\begin{gathered}
S_{n}(n-1, r)>0 \Leftrightarrow \frac{r-s}{n} \in 2 \mathbb{N} \Leftrightarrow\left[\frac{r}{n}\right] \in 2 \mathbb{N} \\
\Leftrightarrow \frac{r}{n} \in[2 m, 2 m+1) \Leftrightarrow \frac{p-2 r}{n} \in\left(-4 m-1-\frac{1}{n},-4 m+1-\frac{1}{n}\right] .
\end{gathered}
$$

Since $p$ is an even number, no number of the form $\frac{p-2 r}{n}$ lies in intervals of the form $\left(2 l+1-\frac{1}{n}, 2 l+1+\frac{1}{n}\right)$. Hence

$$
\frac{p-2 r}{n} \in\left(-4 m-1-\frac{1}{n},-4 m+1-\frac{1}{n}\right] \Leftrightarrow \frac{p-2 r}{n} \in(-4 m-1,-4 m+1)
$$

Similarly,

$$
\begin{aligned}
S_{n}(n-1, r) & <0 \Leftrightarrow \frac{p-2 r}{n} \in\left(-4 m+1-\frac{1}{n},-4 m+3-\frac{1}{n}\right] \\
& \Leftrightarrow \frac{p-2 r}{n} \in(-4 m+1,-4 m+3)
\end{aligned}
$$

and these equivalences complete the proof for $p=n-1$.
Suppose now that the conclusion is true for $p-1$.

1. $\frac{p-2 r}{n}=2 k+1$

From Lemma 8, 2. there follows that $S_{n}(p-1, r)=S_{n}(p-1, p-1-r)$, hence by Lemma 8.1.

$$
\begin{aligned}
S_{n}(p, r) & =S_{n}(p-1, r)+S_{n}(p-1, r-1) \\
& =S_{n}(p-1, p-1-r)+S_{n}(p-1, r-1) \\
& =S_{n}(p-1, p-1-r)+S_{n}(p-1, p-1-r+(2 r-p)) \\
& =S_{n}(p-1, p-1-r)+S_{n}(p-1, p-1-r-(2 k+1) n)=0
\end{aligned}
$$

because $(2 k+1) n$ is an odd multiplicity of $n$.
2. $\frac{p-2 r}{n} \in(4 k-1,4 k+1)$

The numbers $\frac{(p-1)-2(r-1)}{n}=\frac{p-2 r}{n}+\frac{1}{n}$ and $\frac{(p-1)-2 r}{n}=\frac{p-2 r}{n}-\frac{1}{n}$ are both of the form $\frac{q}{n}$ and differ from $\frac{p-2 r}{n}$ by $\frac{1}{n}$. Since both endpoints of the interval $[4 k-1,4 k+1]$ are of the form $\frac{q}{n}$ and $\frac{p-2 r}{n} \in(4 k-1,4 k+1)$, the numbers $\frac{(p-1)-2(r-1)}{n}, \frac{(p-1)-2 r}{n}$ must lie in $[4 k-1,4 k+1]$ and at least one of them is in the interior of $[4 k-1,4 k+1]$. Thus we have the following inequalities:

$$
S_{n}(p-1, r) \geq 0, \quad S_{n}(p-1, r-1) \geq 0
$$

and at most one of them is an equality. Hence

$$
S_{n}(p, r)=S_{n}(p-1, r)+S_{n}(p-1, r-1)>0
$$

3. $\frac{p-2 r}{n} \in(4 k+1,4 k+3)$

Analogously as above we get:

$$
S_{n}(p, r)=S_{n}(p-1, r)+S_{n}(p-1, r-1)<0
$$

As a consequence of the theorem, we obtain:
Corollary 2. $\sum_{\substack{0 \leq s \leq p \\ n \mid s}}(-1)^{p-s}\binom{p}{s}=0 \Longleftrightarrow p / n$ is an odd number.
Proof.

$$
\sum_{\substack{0 \leq s \leq p \\ n \mid s}}(-1)^{p-s}\binom{p}{s}=(-1)^{p} \cdot \sum_{\substack{0 \leq s \leq p \\ n \mid s}}(-1)^{s}\binom{p}{s}=(-1)^{p} \cdot S_{n}(p, 0)
$$

## References

1. Alessio F., Montecchiari P., Multibump solutions for a class of Lagrangian systems slowly oscillating at infinity, Ann. Inst. H. Poincaré Anal. Non Linéaire, 16, No. 1 (1999), 107135.
2. Alessio F., Caldiroli P., Montecchiari P., Genericity of the multibump dynamics for almost periodic Duffing-like systems, Proc. Roy. Soc. Edinburgh Sect. A, 129, No. 5 (1999), 885901.
3. Bolotin S., MacKay R., Multibump orbits near the anti-integrable limit for Lagrangian systems, Nonlinearity (1997), 1015-1029.
4. Conley C.C., Isolated invariant set and the Morse index, CBMS Regional Conf. Ser., No. 38, AMS, Providence R.I., 1978.
5. Coti Zelati V., Montecchiari P., Nolasco M., Multibump homoclinic solutions for a class of second order, almost periodic Hamiltonian systems, Nonlinear Differential Equations Appl., 4 (1997), 77-99.
6. Coti Zelati V., Nolasco M., Multibump solutions for Hamiltonian systems with fast and slow forcing, Boll. Unione Mat. Ital., 2, No. 3 (1999), 585-608.
7. Coti Zelati V., Rabinowitz P.H., Homoclinic orbits for second order Hamiltonian systems possesing superquadratic potentials, J. Amer. Math. Soc., 4 (1991), 693-727.
8. Dold A., Lectures on Algebraic Topology, Springer-Verlag, Berlin-Heidelberg-New York, 1980.
9. Hale J.K., Theory of Functional Differential Equations, Springer-Verlag, New York-Heidelberg-Berlin, 1977.
10. Montecchiari P., Nolesco M., Multibump solutions for perturbations of periodic second order systems, Nonlinear Anal. TMA, 27 (1996), 1355-1372.
11. Rabinowitz P. H., Multibump solutions for an almost periodically forced singular Hamiltonian system, Electronic J. Differential Equations 1995, No. 12 (1995).
12. Séreé E., Looking for the Bernoulli shift, Ann. Inst. H. Poincaré Anal. Non Linéaire, 10 (1993), 561-590.
13. Srzednicki R., Periodic and bounded solutions in block for time-periodic nonautonomous ordinary differential equations, Nonlinear Anal. TMA, 22, No. 6 (1994), 707-737.
14. Srzednicki R., A Geometric Method for the Periodic Problem in Ordinary Differential Equations, Seminaire D'Analyse Moderne No. 22, Eds.: G. Fournier, T. Kaczyński, Universite de Sherbrooke, 1992.
15. Srzednicki R., Wójcik K., A Geometric Method for Detecting Chaotic Dynamics, J. Differential Equations, 135 (1997), 66-82.
16. Wiggins S., Global Bifurcation and Chaos. Analytical Methods, Springer-Verlag, New York-Heidelberg-Berlin, 1988.
17. Wójcik K., Isolating segments and symbolic dynamics, Nonlinear Anal. TMA, 33 (1998), 575-591.
18. Wójcik K., On Some Nonautonomous Chaotic System on the Plane, Internat. J. Bifur. Chaos, Vol. 9, No. 9 (1999), 1853-1858.
19. Wójcik K., On detecting periodic solutions and chaos in the time periodically forced ODEs, Nonlinear Anal., Ser. A: Theory Methods, 45, No. 1 (2001), 19-27.

Received June 28, 2002
Jagiellonian University
Institute of Mathematics
Reymonta 4
30-059 Kraków, Poland
e-mail: pieniaze@im.uj.edu.pl
e-mail: wojcik@im.uj.edu.pl


[^0]:    Key words and phrases. dynamical systems, local process, nonautonomous ODE's, multibump solutions, periodic solutions, Lefschetz number, fixed point index, Ważewski sets.

    Research partially supported by the Foundation for Polish Science and KBN Grant No. 2 P03A 02817.

