

GENERALIZATION SPATIAL PARAMETRIZATION IN THE I.N. VEKUA'S SHELL THEORY

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Let's consider an shell which points are described by radius-vectors:

$$\vec{r}(x^1, x^2, x^3) = \overset{(-)}{\vec{r}}(x^1, x^2) + x^3 \left(\overset{(+)}{\vec{r}}(x^1, x^2) - \overset{(-)}{\vec{r}}(x^1, x^2) \right) \quad (1)$$

Vector relations

$$\overset{(-)}{\vec{r}} = \overset{(-)}{\vec{r}}(x^1, x^2) \quad \text{and} \quad \overset{(+)}{\vec{r}} = \overset{(+)}{\vec{r}}(x^1, x^2) \quad (2)$$

define base surfaces $s^{(-)}$ and $s^{(+)}$ parametrization (1) of shell space. A vector

$$\vec{h}(x^1, x^2) = \overset{(+)}{\vec{r}}(x^1, x^2) - \overset{(-)}{\vec{r}}(x^1, x^2) \quad (3)$$

puts in conformity of a point of base surfaces with identical Gauss coordinates (x^1, x^2) .

Entered (1) parametrization of shell space can be considered as generalization of the spatial coordinate systems normally connected to a base surface, entered by I.N.Vekua. Such systems turn out from the general case when the vector \vec{h} is perpendicular surfaces $s^{(-)}$ and $s^{(+)}$. Entered parametrization is especially convenient by consideration of multilayered environments when acceptance as basic obverse surfaces of layers allows continuously on Gauss coordinates to pass from a layer to a layer. From group transformations of spatial coordinates we shall allocate transformations of a kind

$$x^{\alpha'} = x^{\alpha'}(x^1, x^2), x^{3'} = x^3,$$

which we shall name the generalized S -transformations. The sizes possessing tension properties concerning such transformations of coordinates, we shall name generalized S -tensors.

The three of vectors $(\vec{r}_1, \vec{r}_2, \vec{r}_3)$ form covariant mobile base of shell space. The two of vectors $(\vec{r}_1^-, \vec{r}_2^-)$ and $(\vec{r}_1^+, \vec{r}_2^+)$ form covariant mobile basis, corresponding base surfaces.

Metric tensor of shell spaces $g_{ij} = \vec{r}_i \cdot \vec{r}_j$ it is completely expressed through the value on one of base surfaces $g_{ij}^- = \vec{r}_i^- \cdot \vec{r}_j^-$ or $g_{ij}^+ = \vec{r}_i^+ \cdot \vec{r}_j^+$ and metric carry tensor $g_{ij}^{\pm\pm} = \vec{r}_i^{\pm} \cdot \vec{r}_j^{\pm}$.

Through components of these tensors factors of the second metric form of base shell surfaces, for example are expressed:

$$b_{\alpha\beta}^- = \sqrt{g_{33}^-} (g_{\alpha 3, \beta}^- - g_{\beta \alpha}^- + g_{\alpha\beta}^-) + \frac{1}{2} \frac{g_{\gamma 3}^-}{\sqrt{g_{33}^-}} (g_{\alpha\gamma, \beta}^- + g_{\beta\gamma, \alpha}^- - g_{\alpha\beta, \gamma}^-)$$

For a determinant of the metric form g we have:

$$\sqrt{g} = \vec{r}_1 \vec{r}_2 \vec{r}_3 = \sqrt{\bar{g}} \left((1-x^3)^2 + x^3(1-x^3)(g_1^{\bar{1}} + g_2^{\bar{2}}) + (x^3)^2 (g_1^{\bar{1}} g_2^{\bar{2}} - g_2^{\bar{1}} g_1^{\bar{2}}) \right)$$

Here \bar{g} value of a determinant on a base surface $s^{(-)} : \sqrt{\bar{g}} = \vec{r}_1 \vec{r}_2 \vec{r}_3 = \sqrt{g} |_{x^3=0}$.