

More on λ -closed sets in topological spaces

Más sobre conjuntos λ -cerrados en espacios topológicos

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ABSTRACT. In this paper, we introduce and study topological properties of λ -derived, λ -border, λ -frontier and λ -exterior of a set using the concept of λ -open sets. We also present and study new separation axioms by using the notions of λ -open and λ -closure operator.

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RESUMEN. En este artículo introducimos y estudiamos propiedades topológicas de λ -derivada, λ -borde, λ -frontera y λ -exterior de un conjunto usando el concepto de λ -conjunto abierto. Presentamos un nuevo estudio de axiomas de separación usando las nociones de operador λ -abierto y λ -clausura.

Palabras y frases clave. Espacios topológicos, Λ -conjuntos, conjuntos λ -abiertos, conjuntos λ -cerrados, espacios λ - R_0 , espacios λ - R_1 .

1. Introduction

Maki [12] introduced the notion of Λ -sets in topological spaces. A Λ -set is a set A which is equal to its kernel(= saturated set), i.e. to the intersection of all open supersets of A . Arenas et al. [1] introduced and investigated the notion of λ -closed sets and λ -open sets by involving Λ -sets and closed sets. This enabled them to obtain some nice results. In this paper, for these sets, we introduce the notions of λ -derived, λ -border, λ -frontier and λ -exterior of a set and show that some of their properties are analogous to those for open

sets. Also, we give some additional properties of λ -closure. Moreover, we offer and study new separation axioms by utilizing the notions of λ -open sets and λ -closure operator.

Throughout this paper we adopt the notations and terminology of [12] and [1] and the following conventions: (X, τ) , (Y, σ) and (Z, ν) (or simply X , Y and Z) will always denote spaces on which no separation axioms are assumed unless explicitly stated.

Definition 1. Let B be a subset of a space (X, τ) . B is a Λ -set (resp. V -set) [12] if $B = B^\Lambda$ (resp. $B = B^V$), where:

$$B^\Lambda = \bigcap \{U \mid U \supset B, U \in \tau\} \quad \text{and} \quad B^V = \bigcup \{F \mid B \supset F, F^c \in \tau\}.$$

Theorem 1.1 ([12]). Let A , B and $\{B_i \mid i \in I\}$ be subsets of a space (X, τ) . Then the following properties are valid:

- a) $B \subset B^\Lambda$.
- b) If $A \subset B$ then $A^\Lambda \subset B^\Lambda$.
- c) $B^{\Lambda\Lambda} = B^\Lambda$.
- d) $\left(\bigcup_{i \in I} B_i\right)^\Lambda = \bigcup_{i \in I} B_i^\Lambda$.
- e) If $B \in \tau$, then $B = B^\Lambda$ (i.e. B is a Λ -set).
- f) $(B^c)^\Lambda = (B^V)^c$.
- g) $B^V \subset B$.
- h) If $B^c \in \tau$, then $B = B^V$ (i.e. B is a V -set).
- i) $\left(\bigcap_{i \in I} B_i\right)^\Lambda \subset \bigcap_{i \in I} B_i^\Lambda$.
- j) $\left(\bigcup_{i \in I} B_i\right)^V \supset \bigcup_{i \in I} B_i^V$.
- k) If B_i is a Λ -set ($i \in I$), then $\bigcup_{i \in I} B_i$ is a Λ -set.
- l) If B_i is a Λ -set ($i \in I$), then $\bigcap_{i \in I} B_i$ is a Λ -set.
- m) B is a Λ -set if and only if B^c is a V -set.
- n) The subsets \emptyset and X are Λ -sets.

2. Applications of λ -closed sets and λ -open sets

Definition 2. A subset A of a space (X, τ) is called λ -closed [1] if $A = B \cap C$, where B is a Λ -set and C is a closed set.

Lemma 2.1. For a subset A of a space (X, τ) , the following statements are equivalent [1]:

- (a) A is λ -closed.
- (b) $A = L \cap Cl(A)$, where L is a Λ -set.
- (c) $A = A^\Lambda \cap Cl(A)$.

Lemma 2.2. *Every Λ -set is a λ -closed set.*

Proof. Take $A \cap X$, where A is a Λ -set and X is closed. ✓

Remark 2.3. [1]. *Since locally closed sets and λ -sets are concepts independent of each other, then a λ -closed set need not be locally closed or be a Λ -set. Moreover, in each T_0 non- T_1 space there are singletons which are λ -closed but not a Λ -set.*

Definition 3. *A subset A of a space (X, τ) is called λ -open if $A^c = X \setminus A$ is λ -closed.*

We denote the collection of all λ -open (resp. λ -closed) subsets of X by $\lambda O(X)$ or $\lambda O(X, \tau)$ (resp. $\lambda C(X)$ or $\lambda C(X, \tau)$). We set $\lambda O(X, x) = \{V \in \lambda O(X) \mid x \in V\}$ for $x \in X$. We define similarly $\lambda C(X, x)$.

Theorem 2.4. *The following statements are equivalent for a subset A of a topological space X :*

- (a) *A is λ -open.*
- (b) *$A = T \cup C$, where T is a V -set and C is an open set.*

Lemma 2.5. *Every V -set is λ -open.*

Proof. Take $A = A \cup \emptyset$, where A is V -set, X is Λ -set and $\emptyset = X \setminus X$. ✓

Definition 4. *Let (X, τ) be a space and $A \subset X$. A point $x \in X$ is called λ -cluster point of A if for every λ -open set U of X containing x , $A \cap U \neq \emptyset$. The set of all λ -cluster points is called the λ -closure of A and is denoted by $Cl_\lambda(A)$.*

Lemma 2.6. *Let A, B and A_i ($i \in I$) be subsets of a topological space (X, τ) . The following properties hold:*

- (1) *If A_i is λ -closed for each $i \in I$, then $\bigcap_{i \in I} A_i$ is λ -closed.*
- (2) *If A_i is λ -open for each $i \in I$, then $\bigcup_{i \in I} A_i$ is λ -open.*
- (3) *A is λ -closed if and only if $A = Cl_\lambda(A)$.*
- (4) *$Cl_\lambda(A) = \bigcap \{F \in \lambda C(X, \tau) \mid A \subset F\}$.*
- (5) *$A \subset Cl_\lambda(A) \subset Cl(A)$.*
- (6) *If $A \subset B$, then $Cl_\lambda(A) \subset Cl_\lambda(B)$.*
- (7) *$Cl_\lambda(A)$ is λ -closed.*

Proof. (1) It is shown in [1], 3.3
 (2) It is an immediate consequence of (1).
 (3) Straightforward.
 (4) Let $H = \bigcap \{F \mid A \subset F, F \text{ is } \lambda\text{-closed}\}$. Suppose that $x \in H$. Let U be a λ -open set containing x such that $A \cap U = \emptyset$. And so, $A \subset X \setminus U$. But $X \setminus U$ is λ -closed and hence $Cl_\lambda(A) \subset X \setminus U$. Since $x \notin X \setminus U$, we obtain $x \notin Cl_\lambda(A)$ which is contrary to the hypothesis.

On the other hand, suppose that $x \in Cl_\lambda(A)$, i.e., that every λ -open set of X containing x meets A . If $x \notin H$, then there exists a λ -closed set F of X

such that $A \subset F$ and $x \notin F$. Therefore $x \in X \setminus F \in \lambda O(X)$. Hence $X \setminus F$ is a λ -open set of X containing x , but $(X \setminus F) \cap A = \emptyset$. But this is a contradiction and thus the claim.

(5) It follows from the fact that every closed set is λ -closed. □

In general the converse of 2.6(5) may not be true.

Example 2.7. Let $X = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, \{b\}, \{a, b\}, X\}$. Then $Cl(\{a\}) = \{a, c\} \not\subset Cl_\lambda(\{a\}) = \{a\}$.

Definition 5. Let A be a subset of a space X . A point $x \in X$ is said to be λ -limit point of A if for each λ -open set U containing x , $U \cap (A \setminus \{x\}) \neq \emptyset$. The set of all λ -limit points of A is called a λ -derived set of A and is denoted by $D_\lambda(A)$.

Theorem 2.8. For subsets A, B of a space X , the following statements hold:

- (1) $D_\lambda(A) \subset D(A)$ where $D(A)$ is the derived set of A .
- (2) If $A \subset B$, then $D_\lambda(A) \subset D_\lambda(B)$.
- (3) $D_\lambda(A) \cup D_\lambda(B) \subset D_\lambda(A \cup B)$ and $D_\lambda(A \cap B) \subset D_\lambda(A) \cap D_\lambda(B)$.
- (4) $D_\lambda(D_\lambda(A)) \setminus A \subset D_\lambda(A)$.
- (5) $D_\lambda(A \cup D_\lambda(A)) \subset A \cup D_\lambda(A)$.

Proof. (1) It suffices to observe that every open set is λ -open.

(3) it is an immediate consequence of (2).

(4) If $x \in D_\lambda(D_\lambda(A)) \setminus A$ and U is a λ -open set containing x , then $U \cap (D_\lambda(A) \setminus \{x\}) \neq \emptyset$. Let $y \in U \cap (D_\lambda(A) \setminus \{x\})$. Then since $y \in D_\lambda(A)$ and $y \in U$, $U \cap (A \setminus \{y\}) \neq \emptyset$. Let $z \in U \cap (A \setminus \{y\})$. Then $z \neq x$ for $z \in A$ and $x \notin A$. Hence $U \cap (A \setminus \{x\}) \neq \emptyset$. Therefore $x \in D_\lambda(A)$.

(5) Let $x \in D_\lambda(A \cup D_\lambda(A))$. If $x \in A$, the result is obvious. So let $x \in D_\lambda(A \cup D_\lambda(A)) \setminus A$, then for λ -open set U containing x , $U \cap (A \cup D_\lambda(A) \setminus \{x\}) \neq \emptyset$. Thus $U \cap (A \setminus \{x\}) \neq \emptyset$ or $U \cap (D_\lambda(A) \setminus \{x\}) \neq \emptyset$. Now it follows from (4) that $U \cap (A \setminus \{x\}) \neq \emptyset$. Hence $x \in D_\lambda(A)$. Therefore, in any case $D_\lambda(A \cup D_\lambda(A)) \subset A \cup D_\lambda(A)$. □

In general the converse of (1) may not be true and the equality does not hold in (3) of Theorem 2.8.

Example 2.9. Let $X = \{a, b, c\}$ with topology $\tau = \{\emptyset, \{a\}, \{a, c\}, X\}$. Thus $\lambda O(X, \tau) = \{\emptyset, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, X\}$. Take:

- (i) $A = \{a\}$. We obtain $D(A) \not\subset D_\lambda(A)$.
- (ii) $C = \{a\}$ and $E = \{b, c\}$. Then $D_\alpha(C \cup E) \neq D_\alpha(C) \cup D_\alpha(E)$.

Theorem 2.10. For any subset A of a space X , $Cl_\lambda(A) = A \cup D_\lambda(A)$.

Proof. Since $D_\lambda(A) \subset Cl_\lambda(A)$, $A \cup D_\lambda(A) \subset Cl_\lambda(A)$. On the other hand, let $x \in Cl_\lambda(A)$. If $x \in A$, then the proof is complete. If $x \notin A$, then each λ -open set U containing x intersects A at a point distinct from x . Therefore $x \in D_\lambda(A)$. Thus $Cl_\lambda(A) \subset A \cup D_\lambda(A)$ which completes the proof. □

Definition 6. A point $x \in X$ is said to be a λ -interior point of A if there exists a λ -open set U containing x such that $U \subset A$. The set of all λ -interior points of A is said to be λ -interior of A and is denoted by $Int_\lambda(A)$.

Theorem 2.11. For subsets A, B of a space X , the following statements are true:

- (1) $Int_\lambda(A)$ is the largest λ -open set contained in A .
- (2) A is λ -open if and only if $A = Int_\lambda(A)$.
- (3) $Int_\lambda(Int_\lambda(A)) = Int_\lambda(A)$.
- (4) $Int_\lambda(A) = A \setminus D_\lambda(X \setminus A)$.
- (5) $X \setminus Int_\lambda(A) = Cl_\lambda(X \setminus A)$.
- (6) $X \setminus Cl_\lambda(A) = Int_\lambda(X \setminus A)$.
- (7) $A \subset B$, then $Int_\lambda(A) \subset Int_\lambda(B)$.
- (8) $Int_\lambda(A) \cup Int_\lambda(B) \subset Int_\lambda(A \cup B)$.
- (9) $Int_\lambda(A) \cap Int_\lambda(B) \supset Int_\lambda(A \cap B)$.

Proof. (4) If $x \in A \setminus D_\lambda(X \setminus A)$, then $x \notin D_\lambda(X \setminus A)$ and so there exists a λ -open set U containing x such that $U \cap (X \setminus A) = \emptyset$. Then $x \in U \subset A$ and hence $x \in Int_\lambda(A)$, i.e., $A \setminus D_\lambda(X \setminus A) \subset Int_\lambda(A)$. On the other hand, if $x \in Int_\lambda(A)$, then $x \notin D_\lambda(X \setminus A)$ since $Int_\lambda(A)$ is λ -open and $Int_\lambda(A) \cap (X \setminus A) = \emptyset$. Hence $Int_\lambda(A) = A \setminus D_\lambda(X \setminus A)$.

(5) $X \setminus Int_\lambda(A) = X \setminus (A \setminus D_\lambda(X \setminus A)) = (X \setminus A) \cup D_\lambda(X \setminus A) = Cl_\lambda(X \setminus A)$. □

Definition 7. $b_\lambda(A) = A \setminus Int_\lambda(A)$ is said to be the λ -border of A .

Theorem 2.12. For a subset A of a space X , the following statements hold:

- (1) $b_\lambda(A) \subset b(A)$ where $b(A)$ denotes the border of A .
- (2) $A = Int_\lambda(A) \cup b_\lambda(A)$.
- (3) $Int_\lambda(A) \cap b_\lambda(A) = \emptyset$.
- (4) A is a λ -open set if and only if $b_\lambda(A) = \emptyset$.
- (5) $b_\lambda(Int_\lambda(A)) = \emptyset$.
- (6) $Int_\lambda(b_\lambda(A)) = \emptyset$.
- (7) $b_\lambda(b_\lambda(A)) = b_\lambda(A)$.
- (8) $b_\lambda(A) = A \cap Cl_\lambda(X \setminus A)$.
- (9) $b_\lambda(A) = D_\lambda(X \setminus A)$.

Proof. (6) If $x \in Int_\lambda(b_\lambda(A))$, then $x \in b_\lambda(A)$. On the other hand, since $b_\lambda(A) \subset A$, $x \in Int_\lambda(b_\lambda(A)) \subset Int_\lambda(A)$. Hence $x \in Int_\lambda(A) \cap b_\lambda(A)$ which contradicts (3). Thus $Int_\lambda(b_\lambda(A)) = \emptyset$.

(8) $b_\lambda(A) = A \setminus Int_\lambda(A) = A \setminus (X \setminus Cl_\lambda(X \setminus A)) = A \cap Cl_\lambda(X \setminus A)$.

(9) $b_\lambda(A) = A \setminus Int_\lambda(A) = A \setminus (A \setminus D_\lambda(X \setminus A)) = D_\lambda(X \setminus A)$. □

Definition 8. $Fr_\lambda(A) = Cl_\lambda(A) \setminus Int_\lambda(A)$ is said to be the λ -frontier of A .

Theorem 2.13. For a subset A of a space X , the following statements are hold:

- (1) $Fr_\lambda(A) \subset Fr(A)$ where $Fr(A)$ denotes the frontier of A .

- (2) $Cl_\lambda(A) = Int_\lambda(A) \cup Fr_\lambda(A)$.
 (3) $Int_\lambda(A) \cap Fr_\lambda(A) = \emptyset$.
 (4) $b_\lambda(A) \subset Fr_\lambda(A)$.
 (5) $Fr_\lambda(A) = b_\lambda(A) \cup D_\lambda(A)$.
 (6) A is a λ -open set if and only if $Fr_\lambda(A) = D_\lambda(A)$.
 (7) $Fr_\lambda(A) = Cl_\lambda(A) \cap Cl_\lambda(X \setminus A)$.
 (8) $Fr_\lambda(A) = Fr_\lambda(X \setminus A)$.
 (9) $Fr_\lambda(A)$ is λ -closed.
 (10) $Fr_\lambda(Fr_\lambda(A)) \subset Fr_\lambda(A)$.
 (11) $Fr_\lambda(Int_\lambda(A)) \subset Fr_\lambda(A)$.
 (12) $Fr_\lambda(Cl_\lambda(A)) \subset Fr_\lambda(A)$.
 (13) $Int_\lambda(A) = A \setminus Fr_\lambda(A)$.

Proof. (2) $Int_\lambda(A) \cup Fr_\lambda(A) = Int_\lambda(A) \cup (Cl_\lambda(A) \setminus Int_\lambda(A)) = Cl_\lambda(A)$.

(3) $Int_\lambda(A) \cap Fr_\lambda(A) = Int_\lambda(A) \cap (Cl_\lambda(A) \setminus Int_\lambda(A)) = \emptyset$.

(5) Since $Int_\lambda(A) \cup Fr_\lambda(A) = Int_\lambda(A) \cup b_\lambda(A) \cup D_\lambda(A)$; $Fr_\lambda(A) = b_\lambda(A) \cup D_\lambda(A)$.

(7) $Fr_\lambda(A) = Cl_\lambda(A) \setminus Int_\lambda(A) = Cl_\lambda(A) \cap Cl_\lambda(X \setminus A)$.

(9) $Cl_\lambda(Fr_\lambda(A)) = Cl_\lambda(Cl_\lambda(A) \cap Cl_\lambda(X \setminus A)) \subset Cl_\lambda(Cl_\lambda(A)) \cap Cl_\lambda(Cl_\lambda(X \setminus A)) = Fr_\lambda(A)$. Hence $Fr_\lambda(A)$ is λ -closed.

(10) $Fr_\lambda(Fr_\lambda(A)) = Cl_\lambda(Fr_\lambda(A)) \cap Cl_\lambda(X \setminus Fr_\lambda(A)) \subset Cl_\lambda(Fr_\lambda(A)) = Fr_\lambda(A)$.

(12) $Fr_\lambda(Cl_\lambda(A)) = Cl_\lambda(Cl_\lambda(A)) \setminus Int_\lambda(Cl_\lambda(A)) = Cl_\lambda(A) \setminus Int_\lambda(Cl_\lambda(A)) = Cl_\lambda(A) \setminus Int_\lambda(A) = Fr_\lambda(A)$.

(13) $A \setminus Fr_\lambda(A) = A \setminus (Cl_\lambda(A) \setminus Int_\lambda(A)) = Int_\lambda(A)$. □

The converses of (1) and (4) of the Theorem 2.13 are not true in general as are shown by Example 2.14.

Example 2.14. Consider the topological space (X, τ) given in Example 2.7. If $A = \{a\}$. Then $Fr(A) \not\subseteq Fr_\lambda(A)$ and if $B = \{a, c\}$, then $Fr_\lambda(B) \not\subseteq b_\lambda(B)$.

Recall that a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be λ -continuous [1] if $f^{-1}(V) \in \lambda C(X)$ for every closed subset V of Y .

Theorem 2.15. For a function $f : X \rightarrow Y$, the following are equivalent:

- (1) f is λ -continuous;
 (2) for every open subset V of Y , $f^{-1}(V) \in \lambda O(X)$;
 (3) for each $x \in X$ and each $V \in O(Y, f(x))$, there exists $U \in \lambda O(X, x)$ such that $f(U) \subset V$.

Proof. (1) \rightarrow (2) : This follows from $f^{-1}(Y \setminus V) = X \setminus f^{-1}(V)$.

(1) \rightarrow (3) : Let $V \in O(Y)$ and $f(x) \in V$. Since f is λ -continuous $f^{-1}(V) \in \lambda O(X)$ and $x \in f^{-1}(V)$. Put $U = f^{-1}(V)$. Then $x \in U$ and $f(U) \subset V$.

(3) \rightarrow (1) : Let V be an open set of Y and $x \in f^{-1}(V)$. Then $f(x) \in V$. Therefore by (3) there exists a $U_x \in \lambda O(X)$ such that $x \in U_x$ and $f(U_x) \subset V$. Therefore $x \in U_x \subset f^{-1}(V)$. This implies that $f^{-1}(V)$ is a union of λ -open sets of X . Consequently $f^{-1}(V) \in \lambda O(X)$. Hence f is λ -continuous. □

In the following theorem $\sharp\Lambda.c.$ denotes the set of points x of X for which a function $f : (X, \tau) \rightarrow (Y, \sigma)$ is not λ -continuous.

Theorem 2.16. $\sharp\Lambda.c.$ is identical with the union of the λ -frontiers of the inverse images of λ -open sets containing $f(x)$.

Proof. Suppose that f is not λ -continuous at a point x of X . Then there exists an open set $V \subset Y$ containing $f(x)$ such that $f(U)$ is not a subset of V for every $U \in \lambda O(X)$ containing x . Hence we have $U \cap (X \setminus f^{-1}(V)) \neq \emptyset$ for every $U \in \lambda O(X)$ containing x . It follows that $x \in Cl_\lambda(X \setminus f^{-1}(V))$. We also have $x \in f^{-1}(V) \subset Cl_\lambda(f^{-1}(V))$. This means that $x \in Fr_\lambda(f^{-1}(V))$.

Now, let f be λ -continuous at $x \in X$ and $V \subset Y$ be any open set containing $f(x)$. Then $x \in f^{-1}(V)$ is a λ -open set of X . Thus $x \in Int_\lambda(f^{-1}(V))$ and therefore $x \notin Fr_\lambda(f^{-1}(V))$ for every open set V containing $f(x)$. \square

Definition 9. $Ext_\lambda(A) = Int_\lambda(X \setminus A)$ is said to be a λ -exterior of A .

Theorem 2.17. For a subset A of a space X , the following statements are hold:

- (1) $Ext(A) \subset Ext_\lambda(A)$ where $Ext(A)$ denotes the exterior of A .
- (2) $Ext_\lambda(A)$ is λ -open.
- (3) $Ext_\lambda(A) = Int_\lambda(X \setminus A) = X \setminus Cl_\lambda(A)$.
- (4) $Ext_\lambda(Ext_\lambda(A)) = Int_\lambda(Cl_\lambda(A))$.
- (5) If $A \subset B$, then $Ext_\lambda(A) \supset Ext_\lambda(B)$.
- (6) $Ext_\lambda(A \cup B) \subset Ext_\lambda(A) \cup Ext_\lambda(B)$.
- (7) $Ext_\lambda(A \cap B) \supset Ext_\lambda(A) \cap Ext_\lambda(B)$.
- (8) $Ext_\lambda(X) = \emptyset$.
- (9) $Ext_\lambda(\emptyset) = X$.
- (10) $Ext_\lambda(A) = Ext_\lambda(X \setminus Ext_\lambda(A))$.
- (11) $Int_\lambda(A) \subset Ext_\lambda(Ext_\lambda(A))$.
- (12) $X = Int_\lambda(A) \cup Ext_\lambda(A) \cup Fr_\lambda(A)$.

Proof. (4) $Ext_\lambda(Ext_\lambda(A)) = Ext_\lambda(X \setminus Cl_\lambda(A)) = Int_\lambda(X \setminus (X \setminus Cl_\lambda(A))) = Int_\lambda(Cl_\lambda(A))$.

(10) $Ext_\lambda(X \setminus Ext_\lambda(A)) = Ext_\lambda(X \setminus Int_\lambda(X \setminus A)) = Int_\lambda(X \setminus (X \setminus Int_\lambda(X \setminus A))) = Int_\lambda(Int_\lambda(X \setminus A)) = Int_\lambda(X \setminus A) = Ext_\lambda(A)$.

(11) $Int_\lambda(A) \subset Int_\lambda(Cl_\lambda(A)) = Int_\lambda(X \setminus Int_\lambda(X \setminus A)) = Int_\lambda(X \setminus Ext_\lambda(A)) = Ext_\lambda(Ext_\lambda(A))$. \square

Example 2.18. Consider the topological space (X, τ) given in Example 2.7. Hence, if $A = \{a\}$ and $B = \{b\}$, Then $Ext_\lambda(A) \not\subset Ext(A)$, $Ext_\lambda(A \cap B) \neq Ext_\lambda(A) \cap Ext_\lambda(B)$ and $Ext_\lambda(A \cup B) \neq Ext_\lambda(A) \cup Ext_\lambda(B)$.

3. Some new separation axioms

We recall with the following notions which will be used in the sequel:

A space (X, τ) is said to be R_0 [3] (resp. λ - R_0 [2]) if every open set contains the closure of each of its singletons. A space (X, τ) is said to be R_1 [3] (resp. λ - R_1 [2]) if for x, y in X with $Cl(\{x\}) \neq Cl(\{y\})$, there exist disjoint open sets U and V such that $Cl(\{x\})$ is a subset of U and $Cl(\{y\})$ is a subset of V . A space is T_0 if for $x, y \in X$ such that $x \neq y$ there exists a open set U of X containing x but not y or an open set V of X containing y but not x . A space (X, τ) is T_1 if to each pair of distinct points x and y of X , there exists a pair of open sets one containing x but not y and the other containing y but not x . A space (X, τ) is T_2 if to each pair of distinct points x and y of X , there exists a pair of disjoint open sets, one containing x and the other containing y . Recall that a space (X, τ) is called a $T_{\frac{1}{2}}$ -space [11] if every generalized closed subset of X is closed or equivalently if every singleton is open or closed [6]. In [1], Arenas et al. have shown that a space (X, τ) is called a $T_{\frac{1}{2}}$ -space if and only if every subset of X is λ -closed.

Definition 10. Let X be a space. A subset $A \subset X$ is called a λ -Difference set (in short λ - D -set) if there are two λ -open sets U, V in X such that $U \neq X$ and $A = U \setminus V$.

It is true that every λ -open set $U \neq X$ is a λ - D -set since $U = U \setminus \emptyset$.

Definition 11. A space (X, τ) is said to be:

- (i) λ - D_0 (resp. λ - D_1) if for $x, y \in X$ such that $x \neq y$ there exists a λ - D -set of X containing x but not y or (resp. and) a λ - D -set containing y but not x .
- (ii) A topological space (X, τ) is λ - D_2 if for $x, y \in X$ such that $x \neq y$ there exist disjoint λ - D -sets G and E such that $x \in G$ and $y \in E$.
- (iii) λ - T_0 (resp. λ - T_1) if for $x, y \in X$ such that $x \neq y$ there exists a λ -open set U of X containing x but not y or (resp. and) a λ -open set V of X containing y but not x .
- (iv) λ - T_2 if for $x, y \in X$ such that $x \neq y$ there exist disjoint λ -open sets U and V such that $x \in U$ and $y \in V$.

Remark 3.1.

- (i) If (X, τ) is λ - T_i , then it is λ - T_{i-1} , $i = 1, 2$.
- (ii) Obviously, if (X, τ) is λ - T_i , then (X, τ) is λ - D_i , $i = 0, 1, 2$.
- (iii) If (X, τ) is λ - D_i , then it is λ - D_{i-1} , $i = 1, 2$.

Theorem 3.2. For a space (X, τ) the following statements are true:

- (1) (X, τ) is λ - D_0 if and only if (X, τ) is λ - T_0 .
- (2) (X, τ) is λ - D_1 if and only if (X, τ) is λ - D_2 .

Proof. The sufficiency for (1) and (2) follows from the Remark 3.1.

Necessity condition for (1). Let (X, τ) be λ - D_0 so that for any distinct pair of points x and y of X at least one belongs to a λ - D set O . Therefore we choose $x \in O$ and $y \notin O$. Suppose $O = U \setminus V$ for which $U \neq X$ and U and V are λ -open sets in X . This implies that $x \in U$. For the case that $y \notin O$ we have

(i) $y \notin U$, (ii) $y \in U$ and $y \in V$. For (i), the space X is λ - T_0 since $x \in U$ and $y \notin U$. For (ii), the space X is also λ - T_0 since $y \in V$ but $x \notin V$.

The necessity condition for (2). Suppose that X is λ - D_1 . It follows from the definition that for any distinct points x and y in X there exist λ - D sets G and E such that G containing x but not y and E containing y but not x . Let $G = U \setminus V$ and $E = W \setminus D$, where U, V, W and D are λ -open sets in X . By the fact that $x \notin E$, we have two cases, i.e. either $x \notin W$ or both W and D contain x . If $x \notin W$, then from $y \notin G$ either (i) $y \notin U$ or (ii) $y \in U$ and $y \in V$. If (i) is the case, then it follows from $x \in U \setminus V$ that $x \in U \setminus (V \cup W)$, and also it follows from $y \in W \setminus D$ that $y \in (U \cup D)$. Thus we have $U \setminus (V \cup W)$ and $W \setminus (U \cup D)$ which are disjoint. If (ii) is the case, it follows that $x \in U \setminus V$ and $y \in V$ since $y \in U$ and $y \in V$. Therefore $(U \setminus V) \cap V = \emptyset$. If $x \in W$ and $x \in D$, we have $y \in W \setminus D$ and $x \in D$. Hence $(W \setminus D) \cap D = \emptyset$. This shows that X is λ - D_2 . \square

Theorem 3.3. *If (X, τ) is λ - D_1 , then it is λ - T_0 .*

Proof. Remark 3.1(iii) and Theorem 3.2. \square

We give an example which shows that the converse of Theorem 3.3 is false.

Example 3.4. *Let $X = \{a, b\}$ with topology $\tau = \{\emptyset, \{a\}, X\}$. Then (X, τ) is λ - T_0 , but not λ - D_1 since there is not a λ - D -set containing a but not b .*

Example 3.5. *Let $X = \{a, b, c, d\}$ with topology $\tau = \{\emptyset, \{c\}, \{b\}, \{b, c\}, \{b, c, d\}, X\}$. Then we have that $\{a\}, \{a, d\}, \{a, b, d\}$ and $\{a, c, d\}$ are λ -open and (X, τ) is a λ - D_1 , since $\{a\}, \{b\} = \{a, b, d\} \setminus \{a, d\}$, $\{c\} = \{a, c, d\} \setminus \{a, d\}$, $\{d\} = \{a, d\} \setminus \{a\}$. But (X, τ) is not λ - T_2 .*

Example 3.6.

- (1) *As a consequence of the Example 3.4, we obtain that (X, τ) is λ - T_0 , but not λ - T_1 .*
- (2) *As a consequence of the Example 3.5, we obtain that (X, τ) is λ - T_0 , but not λ - T_2 .*

A subset B_x of a space X is said to be a λ -neighbourhood of a point $x \in X$ if and only if there exists a λ -open set A such that $x \in A \subset B_x$.

Definition 12. *Let x be a point in a space X . If x does not have a λ -neighbourhood other than X , then we call x a λ -neat point. neighbourhood*

Theorem 3.7. *For a λ - T_0 space (X, τ) the following are equivalent:*

- (1) *(X, τ) is λ - D_1 ;*
- (2) *(X, τ) has no λ -neat point.*

Proof. (1) \rightarrow (2) : If X is λ - D_1 then each point $x \in X$ belongs to a λ - D -set $A = U \setminus V$; hence $x \in U$. Since $U \neq X$, thus x is not a λ -neat point.

(2) \rightarrow (1) : If X is λ - T_0 , then for each distinct pair of points $x, y \in X$, at least one of x, y , say x has a λ -neighbourhood U such that $x \in U$ and $y \notin U$.

Hence $U \neq X$ is a λ - D -set. If X does not have a λ -neat point, then y is not a λ -neat point. So there exists a λ -neighbourhood V of y such that $V \neq X$. Now $y \in V \setminus U$, $x \notin V \setminus U$ and $V \setminus U$ is a λ - D -set. Therefore X is λ - D_1 . \square

Corollary 3.8. *A λ - T_0 space X is not λ - D_1 if and only if there is a unique λ -neat point in X .*

Proof. We only prove the uniqueness of the λ -neat point. If x and y are two λ -neat points in X , then since X is λ - T_0 , at least one of x and y , say x , has a λ -neighbourhood U such that $x \in U$, $y \notin U$. Hence $U \neq X$. Therefore x is not a λ -neat point which is a contradiction. \square

Theorem 3.9. *A space X is λ - T_0 if and only if for each pair of distinct points x, y of X , $Cl_\lambda(\{x\}) \neq Cl_\lambda(\{y\})$.*

Proof. Sufficiency. Suppose that $x, y \in X$, $x \neq y$ and $Cl_\lambda(\{x\}) \neq Cl_\lambda(\{y\})$. Let z be a point of X such that $z \in Cl_\lambda(\{x\})$ but $z \notin Cl_\lambda(\{y\})$. We claim that $x \notin Cl_\lambda(\{y\})$. For, if $x \in Cl_\lambda(\{y\})$, then $Cl_\lambda(\{x\}) \subset Cl_\lambda(\{y\})$. This contradicts the fact that $z \notin Cl_\lambda(\{y\})$. Consequently x belongs to the λ -open set $[Cl_\lambda(\{y\})]^c$ to which y does not belong.

Necessity. Let X be a λ - T_0 space and x, y be any two distinct points of X . There exists a λ -open set G containing x or y , say x but not y . Then G^c is a λ -closed set which does not contain x but contains y . Since $Cl_\lambda(\{y\})$ is the smallest λ -closed set containing y (Lemma 2.6), $Cl_\lambda(\{y\}) \subset G^c$, and so $x \notin Cl_\lambda(\{y\})$. Consequently $Cl_\lambda(\{x\}) \neq Cl_\lambda(\{y\})$. \square

Theorem 3.10. *A space X is λ - T_1 if and only if the singletons are λ -closed sets.*

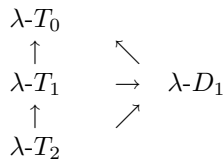
Proof. Suppose X is λ - T_1 and x is any point of X . Let $y \in \{x\}^c$. Then $x \neq y$. So there exists a λ -open set A_y such that $y \in A_y$ but $x \notin A_y$. Consequently $y \in A_y \subset \{x\}^c$ i.e., $\{x\}^c = \bigcup \{A_y / y \in \{x\}^c\}$ which is λ -open. Conversely, let $x, y \in X$ with $x \neq y$. Now $x \neq y$ implies $y \in \{x\}^c$. Hence $\{x\}^c$ is a λ -open set containing y but not x . Similarly $\{y\}^c$ is a λ -open set containing x but not y . Accordingly X is a λ - T_1 space. \square

Theorem 3.11. *A topological space X is λ - T_1 if and only if X is T_0 .*

Proof. This is proved by Theorem 3.10 and [1][Theorem 2.5]. \square

Example 3.12. *The Khalimsky line or the so-called digital line ([8], [9]) is the set of the integers, \mathbf{Z} , equipped with the topology \mathbf{K} , having $\{2n - 1, 2n, 2n + 1\} : n \in \mathbf{Z}\}$ as a subbase. This space is of great importance in the study of applications of point-set topology to computer graphics. In the digital line (\mathbf{Z}, \mathbf{K}) , every singleton is open or closed, that is, the digital line is T_0 . Thus by Theorem 3.11, the digital line is λ - T_1 which is not T_1 .*

Remark 3.13. *From Example 3.4, Example 3.5, Example 3.6 and Example 3.12 we have the following diagram:*



(1) $T_1 \implies \lambda-T_1$ and $T_2 \implies \lambda-T_2$. The converses are not true:

Example 3.14. Let (X, τ) be a topological space such that $X = \{a, b, c\}$ and $\tau = \{\emptyset, \{a\}, \{a, b\}, X\}$. Then we have that

$$\lambda O(X, \tau) = \{\emptyset, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, X\}.$$

Therefore:

- (i) (X, τ) is $\lambda-T_1$ but it is not T_1 . (see also as another example the Khalimsky line i.e., the digital line which is given in Example 3.12).
- (ii) (X, τ) is $\lambda-T_2$ but it is not T_2 .

(2) T_0 implies $\lambda-T_0$ But the converse is not true as it is shown in the following example.

Example 3.15. Let $X = \{a, b\}$ with topology $\tau = \{\emptyset, \{a\}, X\}$. Then (X, τ) is $\lambda-T_0$. Observe that (X, τ) is not T_0 .

- (3) $\lambda-T_1$ implies $\lambda-T_0$ and $\lambda-T_2$ implies $\lambda-T_0$. The converses are not true (Example 3.6).
- (4) $\lambda-R_1$ implies $\lambda-R_0$. The converse is not true (Example 3.15).
- (5) $\lambda-T_1$ does not imply R_0 and $\lambda-T_0$ does not imply R_0 . (Example 3.14).
- (6) R_1 implies R_0 [3]. The converse is not true as it is shown by the following example.

Example 3.16. Let $X = \{a, b\}$ with indiscrete topology τ . Then (X, τ) is R_0 but it is not R_1 .

- (7) (i) $\lambda-R_0 \not\iff R_0$ and (ii) $\lambda-R_1 \not\iff R_1$ (Example 3.14).
- (8) (i) $T_{\frac{1}{2}}$ implies T_0 which is equivalent with $\lambda-T_1$ (see Theorem 3.11) and (ii) $T_{\frac{1}{2}}$ implies $\lambda-T_{\frac{1}{2}}$. The converses are not true. For case (i), it is well known and for case (ii), it follows from the fact that every $\lambda-T_1$ is $\lambda-T_{\frac{1}{2}}$ (where a topological space is $\lambda-T_{\frac{1}{2}}$ [2] if every singleton is λ -open or λ -closed).
- (9) $\lambda-T_1 \not\iff T_{\frac{1}{2}}$. It is shown in the following example.

Example 3.17. [1][Example 3.2]] Let X be the set of non-negative integers with the topology whose open sets are those which contain 0 and have finite complement. This space is not $T_{\frac{1}{2}}$, but it is T_0 is equivalent with $\lambda-T_1$ (see Theorem 3.11). Therefore also $\lambda-T_{\frac{1}{2}}$ does not imply $T_{\frac{1}{2}}$.

- (10) X is a $T_{\frac{1}{4}}$ -space [1] if and only if every finite subset of X is λ -closed. We see that $T_{\frac{1}{4}}$ -space is strictly placed between $T_{\frac{1}{2}}$ and λ - T_1 . On the other hand, the space $X = \{a, b, c\}$ with $\tau = \{\emptyset, \{a\}, \{a, b\}, X\}$ is λ - T_1 but not $T_{\frac{1}{4}}$. Example 3.17 is an example of a space $T_{\frac{1}{4}}$ which is not $T_{\frac{1}{2}}$.

In what follows, we refer the interested reader to [10] for the basic definitions and notations. Recall that a representation of a C^* -algebra \mathcal{A} consists of a Hilbert space \mathcal{H} and a $*$ -morphism $\pi : \mathcal{A} \rightarrow \mathcal{B}(\mathcal{H})$, where $\mathcal{B}(\mathcal{H})$ is the C^* -algebra of bounded operators on \mathcal{H} . A subspace \mathcal{I} of a C^* -algebra \mathcal{A} is called a primitive ideal if $\mathcal{I} = \ker(\pi)$ for some irreducible representation (\mathcal{H}, π) of \mathcal{A} . The set of all primitive ideals of a C^* -algebra \mathcal{A} plays a very important role in noncommutative spaces and its relation to particle physics. We denote this set by $\text{Prim } \mathcal{A}$. As Landi [10] mentions, for a noncommutative C^* -algebra, there is more than one candidate for the analogue of the topological space X :

1. The structure space of \mathcal{A} or the space of all unitary equivalence classes of irreducible $*$ -representations and
2. The primitive spectrum of \mathcal{A} or the space of kernels of irreducible $*$ -representations which is denoted by $\text{Prim } \mathcal{A}$. Observe that any element of $\text{Prim } \mathcal{A}$ is a two-sided $*$ -ideal of \mathcal{A} .

It should be noticed that for a commutative C^* -algebra, 1 and 2 are the same but this is not true for a general C^* -algebra \mathcal{A} . Natural topologies can be defined on spaces of 1 and 2. But here we are interested in the Jacobsen (or hull-kernel) topology defined on $\text{Prim } \mathcal{A}$ by means of closure operators. The interested reader may refer to [4] for basic properties of $\text{Prim } \mathcal{A}$. It follows from Theorem 3.11 that $\text{Prim } \mathcal{A}$ is also a λ - T_1 -space. Jafari [7] has shown that T_1 -spaces are precisely those which are both R_0 and λ - T_1 .

Theorem 3.18. *A space X is λ - T_2 if and only if the intersection of all λ -closed λ -neighborhoods of each point of the space is reduced to that point.*

Proof. Let X be λ - T_2 and $x \in X$. Then for each $y \in X$, distinct from x , there exist λ -open sets G and H such that $x \in G$, $y \in H$ and $G \cap H = \emptyset$. Since $x \in G \subset H^c$, then H^c is a λ -closed λ -neighborhood of x to which y does not belong. Consequently, the intersection of all λ -closed λ -neighborhood of x is reduced to $\{x\}$.

Conversely, let $x, y \in X$ and $x \neq y$. Then by hypothesis, there exists a λ -closed λ -neighbourhood U of x such that $y \notin U$. Now there is a λ -open set G such that $x \in G \subset U$. Thus G and U^c are disjoint λ -open sets containing x and y , respectively. Hence X is λ - T_2 . \square

Definition 13. *A space (X, τ) will be termed λ -symmetric if for any x and y in X , $x \in Cl_{\lambda}(\{y\})$ implies $y \in Cl_{\lambda}(\{x\})$.*

Definition 14. *A subset A of a space (X, τ) is called a λ -generalized closed set (briefly λ -g-closed) if $Cl_{\lambda}(A) \subset U$ whenever $A \subset U$ and U is λ -open in (X, τ) .*

Lemma 3.19. *Every λ -closed set is λ - g -closed.*

Example 3.20. *In Example 3.6, if $A = \{a\}$, then A is a λ - g -closed set, but it is not a λ -closed set (hence it is not a closed set).*

Theorem 3.21. *Let (X, τ) be a space. Then,*

- (i) *(X, τ) is λ -symmetric if and only if $\{x\}$ is λ - g -closed for each x in X .*
- (ii) *If (X, τ) is a λ - T_1 space, then (X, τ) is λ -symmetric.*
- (iii) *(X, τ) is λ -symmetric and λ - T_0 if and only if (X, τ) is λ - T_1 .*

Proof. (i) Sufficiency. Suppose $x \in Cl_\lambda(\{y\})$, but $y \notin Cl_\lambda(\{x\})$. Then $\{y\} \subset [Cl_\lambda(\{x\})]^c$ and thus $Cl_\lambda(\{y\}) \subset [Cl_\lambda(\{x\})]^c$. Then $x \in [Cl_\lambda(\{x\})]^c$, a contradiction.

Necessity. Suppose $\{x\} \subset E \in \lambda O(X, \tau) = \{B \subset X \mid B \text{ is } \lambda\text{-open}\}$, but $Cl_\lambda(\{x\}) \not\subset E$. Then $Cl_\lambda(\{x\}) \cap E^c \neq \emptyset$; take $y \in Cl_\lambda(\{x\}) \cap E^c$. Therefore $x \in Cl_\lambda(\{y\}) \subset E^c$ and $x \notin E$, a contradiction.

(ii) In a λ - T_1 space, singleton sets are λ -closed (Theorem 3.10) and therefore λ - g -closed (Lemma 3.19). By (i), the space is λ -symmetric.

(iii) By (ii) and Remark 3.1(i) it suffices to prove only the necessity condition. Let $x \neq y$. By λ - T_0 , we may assume that $x \in E \subset \{y\}^c$ for some $E \in \lambda O(X, \tau)$. Then $x \notin Cl_\lambda(\{y\})$ and hence $y \notin Cl_\lambda(\{x\})$. There exists a $F \in \lambda O(X, \tau)$ such that $y \in F \subset \{x\}^c$ and thus (X, τ) is a λ - T_1 space. ✓

Theorem 3.22. *Let (X, τ) be a λ -symmetric space. Then the following are equivalent.*

- (i) *(X, τ) is λ - T_0 ,*
- (ii) *(X, τ) is λ - D_1 ,*
- (iii) *(X, τ) is λ - T_1 .*

Proof. (i) \rightarrow (iii) : Theorem 3.21.

(iii) \rightarrow (ii) \rightarrow (i) : Remark 3.1 and Theorem 3.3. ✓

A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is called λ -irresolute if $f^{-1}(V)$ is λ -open in (X, τ) for every λ -open set V of (Y, σ) .

Example 3.23. *Let (X, τ) be as Example 3.14 and $f : (X, \tau) \rightarrow (X, \tau)$ such that $f(a) = c$, $f(b) = c$ and $f(x) = x$ for $x \neq a, b$. Then f is λ -irresolute, but it is not irresolute.*

Example 3.24 ([1]). *Consider the classical Dirichlet function $f : \mathbf{R} \rightarrow \mathbf{R}$, where \mathbf{R} is the real line with the usual topology:*

$$f(x) = \begin{cases} 1 & \text{if } x \text{ is rational} \\ 0 & \text{if } x \text{ is otherwise} \end{cases}$$

Therefore f is λ -continuous, but it is not continuous.

Theorem 3.25. *If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a λ -irresolute surjective function and S is a λ - D -set in Y , then $f^{-1}(S)$ is a λ - D -set in X .*

Proof. Let A be a λ - D -set in Y . Then there are λ -open sets U and V in Y such that $A = U \setminus V$ and $U \neq Y$. By the λ -irresoluteness of f , $f^{-1}(U)$ and $f^{-1}(V)$ are λ -open in X . Since $U \neq Y$, we have $f^{-1}(U) \neq X$. Hence $f^{-1}(A) = f^{-1}(U) \setminus f^{-1}(V)$ is a λ - D -set. \checkmark

Theorem 3.26. *If (Y, σ) is λ - D_1 and $f : (X, \tau) \rightarrow (Y, \sigma)$ is λ -irresolute and bijective, then (X, τ) is λ - D_1 .*

Proof. Suppose that Y is a λ - D_1 space. Let x and y be any pair of distinct points in X . Since f is injective and Y is λ - D_1 , there exist λ - D -sets A_x and B_y of Y containing $f(x)$ and $f(y)$ respectively, such that $f(y) \notin A_x$ and $f(x) \notin B_y$. By Theorem 3.25, $f^{-1}(A_x)$ and $f^{-1}(B_y)$ are λ - D -sets in X containing x and y , respectively. This implies that X is a λ - D_1 space. \checkmark

We now prove another characterization of λ - D_1 spaces.

Theorem 3.27. *A space X is λ - D_1 if and only if for each pair of distinct points x and y in X , there exists a λ -irresolute surjective function f of X onto a λ - D_1 space Y such that $f(x) \neq f(y)$.*

Proof. Necessity. For every pair of distinct points of X , it suffices to take the identity function on X .

Sufficiency. Let x and y be any pair of distinct points in X . By hypothesis, there exists a λ -irresolute, surjective function f of a space X onto a λ - D_1 space Y such that $f(x) \neq f(y)$. Therefore, there exist disjoint λ - D -sets A_x and B_y in Y such that $f(x) \in A_x$ and $f(y) \in B_y$. Since f is λ -irresolute and surjective, by Theorem 3.25, $f^{-1}(A_x)$ and $f^{-1}(B_y)$ are disjoint λ - D -sets in X containing x and y , respectively. Hence by Theorem 3.2(2), X is λ - D_1 space. \checkmark

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