# SPACE CURVES AND THEIR DUALS 

F.J. Craveiro de Carvalho and S.A. Robertson

In the real projective plane $P^{2}$, the duality between lines and points induces a map $\delta$ from the set of smooth $\left(\mathbf{C}^{\infty}\right)$ immersions $f: \mathbb{R} \rightarrow P^{2}$ to the set of all smooth maps $g: \mathbb{R} \rightarrow P^{2}$. Thus $\delta(f)=g$, where for all $s \in \mathbb{R}, g(s)$ is the polar of the tangent line to $f$ at $f(s)$. In order that $g$ itself be an immersion, it is necessary to restrict $f$ to have nowhere zero geodesic curvature. The map $\delta$ is then an involution on the set of such immersions.

In this paper, we examine these ideas in the slightly broader setting of smooth immersions $f: \mathbb{R} \rightarrow E^{3}$ in Euclidean 3 -space. In particular, suppose that $M$ and $N$ are smooth surfaces in $E^{3}$ such that, for any immersion $f: \mathbb{R} \rightarrow E^{3}, f(\mathbb{R}) \subset M$ implies $f_{*}(\mathbb{R}) \subset N$, and vice-versa, where $f_{*}$ is defined in $\S 1$. Then $M$ and $N$ are either both spheres with centre 0 or both cones with apex 0 . If $M$ is the unit sphere $S^{2}$ or is the circular cone of apex angle $\pi / 2$ then $M=N$. Accordingly, we concentrate attention on these cases.

## 1 - The dual of a space curve

Let $f: \mathbb{R} \rightarrow E^{3}$ be a smooth immersion. Then we can define a unit tangent vector field $t$ along $f(\mathbb{R})$ by $t(s)=f^{\prime}(s) /\left\|f^{\prime}(s)\right\|, s \in \mathbb{R}$. The dual $\delta(f)=f_{*}$ : $\mathbb{R} \rightarrow E^{3}$ of $f$ is then given by

$$
f_{*}=f \wedge t
$$

Of course, although $f_{*}$, is smooth, it need not be an immersion. Thus $f_{*}^{\prime}=$ $f^{\prime} \wedge t+f \wedge t^{\prime}=f \wedge t^{\prime}$, so $f_{*}$ is an immersion iff, for all $s \in \mathbb{R}, f(s)$ and $t^{\prime}(s)$ are linearly independent.

For such an $f$,

$$
\begin{aligned}
f_{* *} & =\left(f_{*}\right)_{*}=f_{*} \wedge\left(f_{*}^{\prime} /\left\|f_{*}^{\prime}\right\|\right) \\
& =\frac{1}{\left\|f \wedge t^{\prime}\right\|}(f \wedge t) \wedge\left(f \wedge t^{\prime}\right) \\
& =\frac{1}{\left\|f \wedge t^{\prime}\right\|}\left(f \wedge t . t^{\prime}\right) f-(f \wedge t . f) t^{\prime} \\
& =-\cos \theta f
\end{aligned}
$$

where $\theta$ is the angle between $f \wedge t^{\prime}$ and $t, 0 \leq \theta \leq \pi$. This shows that for at least some immersions $f, \delta$ has an involutory character.

We now examine the case of immersions $f: \mathbb{R} \rightarrow S^{2}$ where $\theta=0$ or $\pi$.

## 2 - Curves on $S^{2}$

Let $f: \mathbb{R} \rightarrow S^{2}$ be a smooth immersion into the unit sphere. Then $f_{*}$ is a smooth immersion iff the geodesic curvature $\kappa_{g}(s)$ of $f$ at $s$ is nonzero, for all $s \in \mathbb{R}$, since $\nu(s) \kappa_{g}(s)=f(s) .\left(t(s) \wedge t^{\prime}(s)\right) \neq 0$ iff $t^{\prime}(s)$ is not perpendicular to $S^{2}$ at $f(s)$, with $\nu(s)=\left\|f^{\prime}(s)\right\|$.

Suppose, then, that $G$ denotes the set of all smooth immersions $f: \mathbb{R} \rightarrow S^{2}$ for which $\kappa_{g}$ is nowhere zero. Then $G$ is the disjoint union of $G_{+}$and $G_{-}$where $f \in G_{+}$or $G_{-}$according as $\kappa_{g}>0$ or $\kappa_{g}<0$. Trivially, the antipodal involution $\alpha: G \rightarrow G$, given by $\alpha(f)(s)=-f(s)$, interchanges $G_{+}$and $G_{-}$.

Proposition 1. For all $f \in G, f_{* *}=f$ if $f \in G_{+}$and $f_{* *}=-f$ if $f \in G_{-}$.
Proof: We have shown in $\S 1$ above that $f_{* *}=(-\cos \theta) f$, where $\theta$ is the angle between $f \wedge t^{\prime}$ and $t$. Since $\kappa_{g}=\frac{1}{\nu} f .\left(t \wedge t^{\prime}\right)=-\frac{1}{\nu}\left(f \wedge t^{\prime}\right) . t$ and $\left|\kappa_{g}\right|=\frac{1}{\nu}\left\|f \wedge t^{\prime}\right\|$, where $\nu=\left\|f^{\prime}\right\|$ is the velocity function as above, the result follows.

From $f_{*}=f \wedge t$ and $\left|\kappa_{g}\right|=\frac{1}{\nu}\left\|f \wedge t^{\prime}\right\|$, it follows immediately that $\left\|f_{*}^{\prime}\right\|=\nu\left|\kappa_{g}\right|$.
Corollary 1. There is a well-defined map $\delta: G \rightarrow G$ given by $\delta(f)=f_{*}$.
Proof: We want to show that $f_{*} \in G$ for all $f \in G$. Since $f \in G$ implies $f \wedge t^{\prime}$ is nowhere zero, we know that $f_{*}$ is a smooth immersion. Also $\left\|f_{*}\right\|=\|f \wedge t\|=1$, since $f . t=0$ and $\|f\|=\|t\|=1$. By Proposition $1, f_{* *}= \pm f$, so $f_{* *}$ is a smooth immersion. Hence $f_{*} \in G$.

Corollary 2. $\delta(G)=G_{+}$.

Proof: If $f \in G_{+}$, then $-f \in G_{-}$and if $f \in G_{-},-f \in G_{+}$. Also, for any $f \in G,(-f)_{*}=f_{*}$. Suppose that for some $f \in G_{+}, f_{*} \in G_{-}$. Then $\left(f_{*}\right)_{* *}=-f_{*} \in G_{+}$, by Proposition 1. But $\left(f_{*}\right)_{* *}=\left(f_{* *}\right)_{*}=f_{*} \in G_{-}$, by hypothesis. So $f_{*}=-f_{*}$, which is a contradiction. It follows that $f_{*} \in G_{+}$, if $f \in G_{+}$. Likewise, if $f \in G_{-}$, then $-f \in G_{+}$and $f_{*}=(-f)_{*} \in G_{+}$.

Corollary 3. $\delta \mid G_{+}$is a fixed-point free involution.
Although $\delta \mid G_{+}$has no fixed elements, it does map each circle of radius $\sqrt{2} / 2$ to itself, and each circle of radius $r_{1}, 0<r_{1}<1$ to the parallel circle of radius $r_{2}$ in the same hemisphere, where $r_{1}^{2}+r_{2}^{2}=1$.

## 3 - Multiple points and homotopy

Let us now concentrate on smooth closed curves on $S^{2}$. Thus we confine attention to smooth immersions $f: \mathbb{R} \rightarrow S^{2}$ that are periodic. Denote by $C$ the set of all such curves that are nondegenerate in the sense of Little [1]. That is to say, $f \in C$ iff it is periodic and $f \in G$. Denote by $C_{+}$and $C_{-}$the sets of periodic elements of $G_{+}$and $G_{-}$. Now regard $C$ as a subset of the space $S$ of $\mathbf{C}^{2}$ periodic nondegenerate immersions $f: \mathbb{R} \rightarrow S^{2}$, with the $\mathbf{C}^{2}$ topology. Then Little showed that, with obvious notation, each of $S_{+}$and $S_{-}$has exactly three path components. Equivalently, there are exactly three nondegenerate regular homotopy classes on $S_{+}$and $S_{-}$. These six classes are represented by curves of the form indicated in Figure 1 for plane projection from a hemisphere of $S^{2}$.

Let $C_{+}^{i}$ denote the subsets of $C_{+}$consisting of curves in the class of types $i$, $i=1,2,3$.

Proposition 2. If $f \in C_{+}^{i}$, then $f_{*} \in C_{+}^{i}, i=1,2,3$.
Proof: This follows from work of Little [1], as we now explain. Let $f \in C_{+}$ and suppose that $s, u \in \mathbb{R}$ with $s \neq u$. Then $f_{*}(s)=f_{*}(u)$ iff $f(s) \wedge t(s)=$ $f(u) \wedge t(u)$. Thus $f_{*}(s)=f_{*}(u)$ iff the great circle that is tangent to $f$ at $f(s)$ and oriented in the direction of $t(s)$ is also tangent to $f$ at $f(u)$ in the direction of $t(u)$.

We may suppose without loss of generality that $f$ is self-transverse (modulo periodicity) and that it has only doubly tangent great circles of the above type. That is, we may suppose that both $f$ and $f_{*}$ are self-transverse.

If $f$ has 0,1 or 2 double points, then $f_{*}$ has 0,1 or 4 such double points, as indicated in Figure 2. A procedure explained by Little then shows that $f_{*} \in C_{+}^{1}$, $C_{+}^{2}$ or $C_{+}^{3}$, respectively and the proposition follows, since $\delta$ is a homeomorphism of $C_{+} \subset S_{+}$to itself.
$S$


Fig. 1 - Nondegenerate regular homotopy classes of closed curves on $S^{2}$.


Fig. 2 - Multiple points and oriented double tangents.

Similar arguments apply to $C_{-}^{i}$, where we find that $f \in C_{-}^{i}$ implies that $f_{*} \in C_{+}^{i}$.

## 4 - Duality on a cone

The results obtained above depend to some extent on the fact that the origin $O$ has a privileged position in relation to $S^{2}$. Another surface where $O$ is a centre of symmetry is a right circular cone C with apex $O$. For convenience, let the axis of C be the $z$-axis in $E^{3}$. To make things work better, we also suppose that the apex angle of C is $\frac{1}{2} \pi$. The surface C is given, therefore, by the equation

$$
x^{2}+y^{2}=z^{2}, \quad z \neq 0 .
$$

Let $f: \mathbb{R} \rightarrow \mathrm{C}$ be a smooth immersion. Then there are smooth functions $z$ and $\theta$ such that, for all $s \in \mathbb{R}$,

$$
f(s)=(z(s) \cos \theta(s), z(s) \sin \theta(s), z(s)),
$$

$z(s) \neq 0$. It follows that

$$
f^{\prime}=\left(z^{\prime} \cos \theta-z \theta^{\prime} \sin \theta, z^{\prime} \sin \theta+z \theta^{\prime} \cos \theta, z^{\prime}\right)
$$

so

$$
\left\|f^{\prime}\right\|^{2}=2 z^{\prime 2}+z^{2} \theta^{\prime 2}
$$

and

$$
f_{*}=f \wedge t=\frac{1}{\left\|f^{\prime}\right\|} z^{2} \theta^{\prime}(-\cos \theta,-\sin \theta, 1)
$$

is well-defined as a smooth map $f_{*}: \mathbb{R} \rightarrow \mathrm{C}$, provided that $\theta^{\prime}$ is nowhere zero.
Moreover, $f_{*}^{\prime}=f \wedge t^{\prime}$ implies that $f_{*}^{\prime}=0$ at $s \in \mathbb{R}$ iff $f(s)$ and $t^{\prime}(s)$ are linearly dependent. Since we shall require that $\theta^{\prime}$ is nowhere zero, $f$ is transverse to the generators of C and hence the normal curvature of $f$ is nowhere zero. We conclude that $t^{\prime}(s)$ is nowhere zero, so $f_{*}^{\prime}(s) \neq 0$ for all $s \in \mathbb{R}$. Hence $f_{*}$ is a smooth immersion, transverse to the generators of C .

We have now shown that there is a well-defined map $\gamma: K \rightarrow K$ of the set $K$ of smooth immersions of $\mathbb{R}$ into C , transverse to its generators, into itself, given by $\gamma(f)=f_{*}$.

Now C has two components or sheets $\mathrm{C}_{+}$and $\mathrm{C}_{-}$given by $z>0$ and $z<0$ respectively. So $K$ may be partitioned into four disjoint subsets $K_{p q}$, where $p= \pm 1$ according as $z>0$ or $z<0$ and $q= \pm 1$ according as $\theta^{\prime}>0$ or $\theta^{\prime}<0$, for any $f \in K_{p q}$.

The following proposition is easy to establish.
Proposition 3. $\gamma\left(K_{++} \cup K_{-+}\right) \subset K_{++}$, and $\gamma\left(K_{--} \cup K_{+-}\right) \subset K_{--}$.

We do not know whether either inclusion is strict.
The map $\gamma$ cannot be an involution, even on, say $K_{++}$, as we now show.
Proposition 4. For all $f \in K$ and all $s \in \mathbb{R},\left\|f_{*}(s)\right\| \leq\|f(s)\|$ with equality iff $z^{\prime}(s)=0$.

Proof: Since $f_{*}(s)=f(s) \wedge t(s)$,

$$
\left\|f_{*}(s)\right\|=\|f(s)\|\|t(s)\| \sin \phi(s)=\|f(s)\| \sin \phi(s),
$$

where $\phi(s)$ is the angle between $t(s)$ and $f(s)$.
Proposition 4 shows that if $f \in K$ is such that $z$ has a critical point at $s \in \mathbb{R}$, then with the obvious notation, $z_{*}(s)=z(s)$. If $s$ is not a critical point of $z$, however, then $\left|z_{*}(s)\right|<|z(s)|$.

So if $\gamma$ is a closed curve on $\mathrm{C}_{+}$then the range of values of $z(s), s \in \mathbb{R}$, is a compact interval $[a, b]$, where $a<b$ except when $\gamma$ is a 'circle of latitude'. For such $\gamma$, the range of $z(s)$ for the $n$-th iteration $\gamma^{n}$ of $\gamma$, is $\left[a_{n}, b\right]$, where $a_{n+1}<a_{n}<a$, for sufficiently large $n$. We do not know whether $\alpha=\lim _{n \rightarrow \infty} a_{n}$ must be 0 or whether it can be positive.

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## REFERENCES

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## F.J. Craveiro de Carvalho,

Departamento de Matemática, Faculdade de Ciências e Tecnologia, Universidade de Coimbra, Apartado 3008, 3000 COIMBRA - PORTUGAL
and
S.A. Robertson,

