

REMARKS ON CERTAIN SELECTED FIXED POINT THEOREMS

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Received 8 July 1999 and in revised form 27 March 2000

Fixed point theorems due to Lal et al. (1996) and Jungck (1988) are used to derive two common fixed point theorems involving six mappings in complete and compact metric spaces, respectively.

2000 Mathematics Subject Classification: 54H25, 47H10.

Let \mathbb{R}^+ denote the set of nonnegative reals and let ψ be the family of mappings ϕ from $(\mathbb{R}^+)^5$ into \mathbb{R}^+ such that

- (i) ϕ is nondecreasing,
- (ii) ϕ is upper semi-continuous in each coordinate variable,
- (iii) $\gamma(t) = \phi(t, t, a_1 t, a_2 t, t) < t$, where $\gamma : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is a mapping with $\gamma(0) = 0$ and $a_1 + a_2 = 2$.

Theorem 3.2 of Lal et al. [11] for commuting mappings can be stated as follows.

THEOREM 1. *Let A, S, I , and J be self-mappings of a complete metric space (X, d) such that the pairs (A, I) and (S, J) are commuting and $A(X) \subset J(X)$ and $S(X) \subset I(X)$ such that*

$$\begin{aligned}
 & [1 + p d(Ax, Sy)] d(Ix, Jy) \\
 & \leq p \max \{ d(Ix, Ax) \cdot d(Sy, Jy), d(Ix, Sy) \cdot d(Jy, Ax) \} \\
 & \quad + \phi(d(Ax, Sy), d(Ix, Ax), d(Sy, Jy), d(Ix, Sy), d(Jy, Ax)),
 \end{aligned} \tag{1}$$

for all $x, y \in X$ where $p \geq 0$ and $\phi \in \Psi$. Then A, S, I , and J have a unique common fixed point provided one of these four functions is continuous.

REMARK 2. [Theorem 1](#) was originally proved for “weakly compatible mappings of type (A)” (cf. [11]) but for a more natural setting we have adopted it for commuting mappings.

In this paper, as an application of [Theorem 1](#), we derive a common fixed point theorem for six mappings which runs as follows.

THEOREM 3. *Let A, B, S, T, I , and J be self-mappings of a complete metric space (X, d) such that the pairs (A, B) , $(A, I)(B, I)$, (S, T) , (S, J) , and (T, J) are commuting and $AB(X) \subset J(X)$, $ST(X) \subset I(X)$ satisfying the inequality*

$$\begin{aligned}
 & [1 + p d(ABx, STy)] d(Ix, Jy) \\
 & \leq p \max \{ d(Ix, ABx) \cdot d(STy, Jy), d(Ix, STy) \cdot d(Jy, ABx) \} \\
 & \quad + \phi(d(ABx, STy), d(Ix, ABx), d(STy, Jy), d(Ix, STy), d(Jy, ABx)),
 \end{aligned} \tag{2}$$

for all $x, y \in X$ where $p \geq 0$ and $\phi \in \Psi$. Then A, B, S, T, I , and J have a unique common fixed point provided one of these four mappings AB, ST, I , and J is continuous.

PROOF. We begin by observing that continuity of AB (resp., ST) does not demand the continuities of the component maps A or B or both (resp., S or T or both). Since the pairs (A, B) , (A, I) , (B, I) , (S, T) , (S, J) , and (T, J) are commuting which force the pairs (AB, I) and (ST, J) to be commuting. After observing this we note that all the conditions of [Theorem 1](#) for four mappings AB, ST, I , and J are satisfied, hence (in view of [Theorem 1](#)) AB, ST, I , and J have a unique common fixed point z .

Here one can note that z also remains the unique common fixed point of the pairs (AB, I) and (ST, J) separately. Now it remains to show that z is also a common fixed point of A, B, S, T, I , and J . For this let z be the unique common fixed point of the pair (AB, I) , then

$$\begin{aligned} Az &= A(ABz) = A(BAz) = AB(Az), & Az &= A(Iz) = I(Az), \\ Bz &= B(ABz) = BA(Bz) = AB(Bz), & Bz &= B(Iz) = I(Bz), \end{aligned} \quad (3)$$

which shows that Az and Bz are other fixed points of the pair (AB, I) yielding thereby

$$Az = Bz = Iz = ABz = z \quad (4)$$

in view of the uniqueness of common fixed point of the pair (AB, I) .

Similarly, it can be shown that z is also the unique common fixed point of S, T, ST , and J . This completes the proof. \square

REMARK 4. By choosing ϕ suitably one can derive improved versions of a multitude of relevant known common fixed point theorems involving six mappings especially those contained in Singh and Meade [\[14\]](#), Husain and Sehgal [\[5\]](#), Khan and Imdad [\[10\]](#), Jungck [\[6\]](#), Ćirić [\[1\]](#), S. L. Singh and S. P. Singh [\[13\]](#), Fisher [\[3, 4\]](#), Das and Naik [\[2\]](#), Kannan [\[9\]](#), Rhoades [\[12\]](#), and several others. Also setting $p = 0$ and choosing A, B, S, T, I, J , and ϕ suitably one can deduce the results proved in the above cited references and many others.

Next we wish to indicate a similar result in compact metric spaces. For this purpose one can adopt a general fixed point theorem for commuting mappings in compact metric spaces due to Jungck [\[8\]](#), which was originally proved for compatible mappings (a notion due to Jungck [\[7\]](#)).

THEOREM 5 (see [\[8\]](#)). *Let A, S, I , and J be self-mappings of a compact metric space (X, d) with $A(X) \subset J(X)$ and $S(X) \subset I(X)$. If the pairs (A, I) and (S, J) are commuting and*

$$d(Ax, Sy) < M(x, y), \quad (5)$$

for all $x, y \in X$ where

$$M(x, y) = \max \left\{ d(Ix, Jy), d(Ix, Ax), d(Jy, Sy), \frac{1}{2} [d(Ix, Sy) + d(Jy, Ax)] \right\} \quad (6)$$

with $M(x, y) > 0$, then A, S, I , and J have a unique common fixed point provided all four mappings A, S, I , and J are continuous.

As an application of [Theorem 5](#) one can derive the following theorem in compact metric spaces involving six mappings.

THEOREM 6. *Let $A, B, S, T, I,$ and J be self-mappings of a compact metric space (X, d) with $AB(X) \subset J(X)$ and $ST(X) \subset I(X)$. If the pairs $(A, B), (A, I)(B, I), (S, T), (S, J),$ and (T, J) are commuting and*

$$d(ABx, STy) < M(x, y), \quad (7)$$

for all $x, y \in X$ where

$$M(x, y) = \max \left\{ d(Ix, Jy), d(Ix, ABx), d(Jy, STy), \frac{1}{2} [d(Ix, STy) + d(Jy, ABx)] \right\} \quad (8)$$

with $M(x, y) > 0$, then $A, B, S, T, I,$ and J have a unique common fixed point provided all four mappings $AB, ST, I,$ and J are continuous.

PROOF. The proof is essentially the same as that of [Theorem 3](#), hence we omit the proof. \square

REMARK 7. By choosing $A, B, S, T, I,$ and J suitably one can derive a multitude of known theorems.

ACKNOWLEDGEMENT. The author is grateful to both the learned referees for their pertinent remarks which has significantly improved the contents of an earlier version of this paper.

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