

EXISTENCE AND ALGORITHM OF SOLUTIONS FOR GENERALIZED NONLINEAR VARIATIONAL-LIKE INEQUALITIES

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We introduce and study a new class of generalized nonlinear variational-like inequalities. Under suitable conditions, we prove the existence of solutions for the class of generalized nonlinear variational-like inequalities. A new iterative algorithm for finding the approximate solutions of the generalized nonlinear variational-like inequality is given and the convergence of the algorithm is also proved. The results presented in this paper improve and generalize some results in recent literature.

1. Introduction

Variational-like inequalities are a useful and important generalization of variational inequalities [3, 8, 26]. They have potential and significant applications in optimization theory, structural analysis, and economics, see [3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29]. Some mixed variational-like inequalities have been studied by Parida and Sen [26], Tian [27], and Yao [29] by using the Berge maximum theorem in finite- and infinite-dimensional spaces. Huang and Deng [10] extended the auxiliary principle technique to study the existence of solutions for a class of generalized strongly nonlinear mixed variational-like inequalities. By using the minimax inequality technique, Ding [5, 6] studied some classes of nonlinear variational-like inequalities in reflexive Banach spaces.

The purpose of this paper is to introduce and study a new class of generalized nonlinear variational-like inequalities, which includes several kinds of variational-like inequalities as special cases. A few existence results of solutions for the generalized nonlinear variational-like inequality are established. We construct an iterative algorithm for finding the approximate solutions of the generalized nonlinear variational-like inequality and obtain the convergence of the algorithm under certain conditions.

2. Preliminaries

Let H be a real Hilbert space endowed with an inner product $\langle \cdot, \cdot \rangle$ and norm $\| \cdot \|$, respectively. Let K be a nonempty closed convex subset of H , let $A, C, F : K \rightarrow H$, $N : H \times H \rightarrow H$, and $\eta : K \times K \rightarrow H$ be mappings, and let $f : K \rightarrow (-\infty, \infty]$ be a real functional.

Suppose that $a : H \times H \rightarrow (-\infty, \infty)$ is a coercive continuous bilinear form, that is, there exist positive constants c and d such that

$$(C1) \quad a(v, v) \geq c\|v\|^2, \text{ for all } v \in H;$$

$$(C2) \quad a(u, v) \leq d\|u\|\|v\|, \text{ for all } u, v \in H.$$

Clearly, $c \leq d$.

We consider the following generalized nonlinear variational-like inequality problem.

Find $u \in K$ such that

$$a(u, v - u) + f(v) - f(u) \geq \langle N(Au, Cu) + Fu, \eta(v, u) \rangle, \quad \forall v \in K. \quad (2.1)$$

Special cases. (A) If $N(Au, Cu) = Au - Cu$, $a(u, v) = 0$ and $Fu = 0$ for all $u, v \in K$, then the generalized nonlinear variational-like inequality problem (2.1) is equivalent to finding $u \in K$ such that

$$\langle Cu - Au, \eta(v, u) \rangle \geq f(u) - f(v), \quad \forall v \in K, \quad (2.2)$$

which was introduced and studied by Ding [5].

(B) If $N(Au, Cu) = Au - Cu$, $a(u, v) = 0$ and $\eta(u, v) = gu - gv$ for all $u, v \in K$, then the generalized nonlinear variational-like inequality problem (2.1) is equivalent to finding $u \in K$ such that

$$\langle Cu - Au, gv - gu \rangle \geq f(u) - f(v), \quad \forall v \in K, \quad (2.3)$$

which was studied by Yao [29].

Definition 2.1. Let $A, C : K \rightarrow H$, $N : H \times H \rightarrow H$ and $\eta : K \times K \rightarrow H$ be mappings.

(1) A is said to be *Lipschitz continuous* with constant α if there exists a constant $\alpha > 0$ such that

$$\|Au - Av\| \leq \alpha\|u - v\|, \quad \forall u, v \in K. \quad (2.4)$$

(2) N is said to be *Lipschitz continuous* with constant β in the first argument if there exists a constant $\beta > 0$ such that

$$\|N(u, w) - N(v, w)\| \leq \beta\|u - v\|, \quad \forall u, v, w \in H. \quad (2.5)$$

(3) N is said to be η -*antimonotone* with respect to A in the first argument if

$$\langle N(Au, w) - N(Av, w), \eta(u, v) \rangle \leq 0, \quad \forall u, v \in K, w \in H. \quad (2.6)$$

(4) N is said to be η -*relaxed Lipschitz* with constant γ with respect to C in the second argument if there exists a constant $\gamma > 0$ such that

$$\langle N(w, Cu) - N(w, Cv), \eta(u, v) \rangle \leq -\gamma\|u - v\|^2, \quad \forall u, v \in K, w \in H. \quad (2.7)$$

(5) η is said to be *Lipschitz continuous* with constant δ if there exists a constant $\delta > 0$ such that

$$\|\eta(u, v)\| \leq \delta\|u - v\|, \quad \forall u, v \in K. \quad (2.8)$$

Similarly, we can define the Lipschitz continuity of N in the second argument.

Definition 2.2. Let K be a nonempty closed convex subset of a Hilbert space H and $f : K \rightarrow (-\infty, \infty]$ be a real functional.

(1) f is said to be *convex* if for any $u, v \in K$ and for any $\alpha \in [0, 1]$,

$$f(\alpha u + (1 - \alpha)v) \leq \alpha f(u) + (1 - \alpha)f(v). \tag{2.9}$$

(2) f is said to be *lower semicontinuous* on K if for each $\alpha \in (-\infty, \infty]$, the set $\{u \in K : f(u) \leq \alpha\}$ is closed in K .

LEMMA 2.3 [1, 2]. *Let X be a nonempty closed convex subset of a Hausdorff linear topological space E , and let $\phi, \psi : K \times K \rightarrow R$ be mappings satisfying the following conditions:*

- (a) $\psi(x, y) \leq \phi(x, y)$, for all $x, y \in X$, and $\psi(x, x) \geq 0$, for all $x \in X$;
- (b) for each $x \in X$, $\phi(x, y)$ is upper semicontinuous with respect to y ;
- (c) for each $y \in X$, the set $\{x \in X : \psi(x, y) < 0\}$ is a convex set;
- (d) there exists a nonempty compact set $K \subset X$ and $x_0 \in K$ such that $\psi(x_0, y) < 0$, for all $y \in X \setminus K$.

Then there exists $\hat{y} \in K$ such that $\phi(x, \hat{y}) \geq 0$, for all $x \in X$.

3. Existence theorems

In this section, we give four existence theorems of solutions for the generalized nonlinear variational-like inequality (2.1).

THEOREM 3.1. *Let K be a nonempty closed convex subset of a Hilbert space H . Let $a : H \times H \rightarrow (-\infty, \infty)$ be a coercive continuous bilinear form with (C1) and (C2) and let $f : K \rightarrow (-\infty, \infty]$ be a proper convex lower semicontinuous functional with $\text{int}(\text{dom } f) \cap K \neq \emptyset$. Suppose that $A, C : K \rightarrow H$ and $N : H \times H \rightarrow H$ are continuous mappings, $\eta : K \times K \rightarrow H$ is Lipschitz continuous with constant δ , for each $v \in K$, $\eta(\cdot, v)$ is continuous and $\eta(v, u) = -\eta(u, v)$ for all $u, v \in K$. Assume that N is η -antimonotone with respect to A in the first argument and η -relaxed Lipschitz with constant ξ with respect to C in the second argument. Suppose that for given $x, y \in H$ and $v \in K$, the mapping $u \mapsto \langle N(x, y), \eta(u, v) \rangle$ is concave and upper semicontinuous. If $F : K \rightarrow H$ is completely continuous, then the generalized nonlinear variational-like inequality (2.1) has a solution $u \in K$.*

Proof. We first prove that for each fixed $\hat{u} \in K$, there exists a unique $\hat{w} \in K$ such that

$$a(\hat{w}, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(A\hat{w}, C\hat{w}) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.1}$$

Let \hat{u} be in K . Define the functionals ϕ and $\psi : K \times K \rightarrow R$ by

$$\begin{aligned} \phi(v, w) &= a(v, v - w) + f(v) - f(w) - \langle N(Av, Cv) + F\hat{u}, \eta(v, w) \rangle, \\ \psi(v, w) &= a(w, v - w) + f(v) - f(w) - \langle N(Aw, Cw) + F\hat{u}, \eta(v, w) \rangle \end{aligned} \tag{3.2}$$

for all $v, w \in K$.

We check that the functionals ϕ and ψ satisfy all the conditions of Lemma 2.3 in the weak topology. It follows from the definitions of ϕ and ψ that for all $v, w \in K$,

$$\begin{aligned} \phi(v, w) - \psi(v, w) &= a(v - w, v - w) - \langle N(Av, Cv) - N(Aw, Cv), \eta(v, w) \rangle \\ &\quad - \langle N(Aw, Cv) - N(Aw, Cw), \eta(v, w) \rangle \\ &\geq (c + \xi) \|v - w\|^2 \geq 0, \end{aligned} \tag{3.3}$$

which means that ϕ and ψ satisfy the condition (a) of Lemma 2.3. Notice that f is a convex lower semicontinuous functional and for given $x, y \in H, v \in K$, the mapping $u \mapsto \langle N(x, y), \eta(u, v) \rangle$ is concave and upper semicontinuous. It follows that $\phi(v, w)$ is weakly upper semicontinuous with respect to w and the set $\{v \in K : \psi(v, w) < 0\}$ is convex for each $w \in K$. Therefore, the conditions (b) and (c) of Lemma 2.3 hold. Since f is proper convex lower semicontinuous, for each $v \in \text{int}(\text{dom } f)$, $\partial f(v) \neq \emptyset$, see Ekeland and Temam [9]. Let v^* be in $\text{int}(\text{dom } f) \cap K$. It follows that

$$f(u) \geq f(v^*) + \langle r, u - v^* \rangle, \quad \forall r \in \partial f(v^*), u \in K. \tag{3.4}$$

Put

$$\begin{aligned} D &= (c + \xi)^{-1} (\|r\| + \delta \|N(Av^*, Cv^*)\| + \delta \|F\hat{u}\|), \\ T &= \{w \in K : \|w - v^*\| \leq D\}. \end{aligned} \tag{3.5}$$

Obviously, T is a weakly compact subset of K and for any $w \in K \setminus T$,

$$\begin{aligned} \psi(v^*, w) &= a(w - v^*, v^* - w) + f(v^*) - f(w) - \langle N(Aw, Cw) + F\hat{u}, \eta(v^*, w) \rangle \\ &\leq -a(w - v^*, w - v^*) - \langle r, w - v^* \rangle \\ &\quad + \langle N(Aw, Cw) - N(Av^*, Cw), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cw) - N(Av^*, Cv^*), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cv^*), \eta(w, v^*) \rangle + \langle F\hat{u}, \eta(w, v^*) \rangle \\ &\leq -\|w - v^*\| [(c + \xi) \|w - v^*\| - \|r\| - \delta \|N(Av^*, Cv^*)\| - \delta \|F\hat{u}\|] < 0, \end{aligned} \tag{3.6}$$

which yields that the condition (d) of Lemma 2.3 holds. Thus Lemma 2.3 ensures that there exists a $\hat{w} \in K$ such that $\phi(v, \hat{w}) \geq 0$ for all $v \in K$, that is,

$$a(v, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(Av, Cv) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.7}$$

Let t be in $(0, 1]$ and v be in K . Replacing v by $v_t = tv + (1 - t)\hat{w}$ in (3.7), we see that

$$a(v_t, t(v - \hat{w})) + f(v_t) - f(\hat{w}) \geq \langle N(Av_t, Cv_t) + F\hat{u}, \eta(v_t, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.8}$$

Note that a is bilinear and f is convex. From (3.8) we deduce that

$$t[a(v_t, v - \hat{w}) + f(v) - f(\hat{w})] \geq t \langle N(Av_t, Cv_t) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K, \tag{3.9}$$

which implies that

$$a(v_t, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(Av_t, Cv_t) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.10}$$

Letting $t \rightarrow 0^+$ in the above inequality, we conclude that

$$a(\hat{w}, v - \hat{w}) + f(v) - f(\hat{w}) \geq \langle N(A\hat{w}, C\hat{w}) + F\hat{u}, \eta(v, \hat{w}) \rangle, \quad \forall v \in K. \tag{3.11}$$

That is, \hat{w} is a solution of (3.1). Now we prove the uniqueness. For any two solutions $w_1, w_2 \in K$ of (3.1), we know that

$$\begin{aligned} a(w_1, w_2 - w_1) + f(w_2) - f(w_1) &\geq \langle N(Aw_1, Cw_1) + F\hat{u}, \eta(w_2, w_1) \rangle, \\ a(w_2, w_1 - w_2) + f(w_1) - f(w_2) &\geq \langle N(Aw_2, Cw_2) + F\hat{u}, \eta(w_1, w_2) \rangle. \end{aligned} \tag{3.12}$$

Adding these inequalities, we deduce that

$$\begin{aligned} c\|w_1 - w_2\|^2 &\leq a(w_1 - w_2, w_1 - w_2) \\ &\leq \langle N(Aw_1, Cw_1) - N(Aw_2, Cw_1), \eta(w_1, w_2) \rangle \\ &\quad + \langle N(Aw_2, Cw_1) - N(Aw_2, Cw_2), \eta(w_1, w_2) \rangle \\ &\leq -\xi\|w_1 - w_2\|^2, \end{aligned} \tag{3.13}$$

which yields that $w_1 = w_2$. That is, \hat{w} is a unique solution of (3.1). This means that there exists a mapping $G : K \rightarrow K$ satisfying $G(\hat{u}) = \hat{w}$, where \hat{w} is the unique solution of (3.1) for each $\hat{u} \in K$.

Next we show that G is a completely continuous mapping. Let u_1 and u_2 be arbitrary elements in K . Using (3.1), we get that

$$\begin{aligned} a(Gu_1, Gu_2 - Gu_1) + f(Gu_2) - f(Gu_1) &\geq \langle N(A(Gu_1), C(Gu_1)) + Fu_1, \eta(Gu_2, Gu_1) \rangle, \\ a(Gu_2, Gu_1 - Gu_2) + f(Gu_1) - f(Gu_2) &\geq \langle N(A(Gu_2), C(Gu_2)) + Fu_2, \eta(Gu_1, Gu_2) \rangle. \end{aligned} \tag{3.14}$$

Adding (3.14), we arrive at

$$\begin{aligned} c\|Gu_1 - Gu_2\|^2 &\leq a(Gu_1 - Gu_2, Gu_1 - Gu_2) \\ &\leq \langle N(A(Gu_1), C(Gu_1)) - N(A(Gu_2), C(Gu_1)), \eta(Gu_1, Gu_2) \rangle \\ &\quad + \langle N(A(Gu_2), C(Gu_1)) - N(A(Gu_2), C(Gu_2)), \eta(Gu_1, Gu_2) \rangle \\ &\quad + \langle Fu_1 - Fu_2, \eta(Gu_1, Gu_2) \rangle \\ &\leq -\xi\|Gu_1 - Gu_2\|^2 + \delta\|Fu_1 - Fu_2\|\|Gu_1 - Gu_2\|, \end{aligned} \tag{3.15}$$

that is,

$$\|Gu_1 - Gu_2\| \leq \frac{\delta}{c + \xi} \|Fu_1 - Fu_2\|. \tag{3.16}$$

Since F is completely continuous, it follows from (3.16) that $G : K \rightarrow K$ is a completely continuous mapping. Hence the Schauder fixed point theorem guarantees that G has a fixed point $u \in K$, which means that u is a solution of the generalized nonlinear variational-like inequality (2.1). This completes the proof. \square

THEOREM 3.2. *Let a, f, C, N, F , and η be as in Theorem 3.1 and let N be Lipschitz continuous with constant ζ in the first argument. Suppose that $A : K \rightarrow H$ is Lipschitz continuous with constant ρ . If $c + \xi > \delta\zeta\rho$, then the generalized nonlinear variational-like inequality (2.1) has a solution $u \in K$.*

Proof. Put

$$D = (c + \xi - \delta\zeta\rho)^{-1} (\|r\| + \delta\|N(Av^*, Cv^*)\| + \delta\|F\hat{u}\|), \tag{3.17}$$

$$T = \{w \in K : \|w - v^*\| \leq D\}.$$

As in the proof of Theorem 3.1, we conclude that

$$\begin{aligned} \psi(v^*, w) &\leq -a(w - v^*, w - v^*) - \langle r, w - v^* \rangle \\ &\quad + \langle N(Aw, Cw) - N(Av^*, Cw), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cw) - N(Av^*, Cv^*), \eta(w, v^*) \rangle \\ &\quad + \langle N(Av^*, Cv^*), \eta(w, v^*) \rangle + \langle F\hat{u}, \eta(w, v^*) \rangle \\ &\leq -\|w - v^*\| [(c + \xi - \delta\zeta\rho)\|w - v^*\| \\ &\quad - \|r\| - \delta\|N(Av^*, Cv^*)\| - \delta\|F\hat{u}\|] < 0 \end{aligned} \tag{3.18}$$

for any $w \in K \setminus T$. The rest of the argument is now essentially the same as in the proof of Theorem 3.1 and therefore is omitted. \square

THEOREM 3.3. *Let a, f, A, C, N , and η be as in Theorem 3.1. Suppose that $F : K \rightarrow H$ is Lipschitz continuous with constant l . If $\delta l / (c + \xi) < 1$, then the generalized nonlinear variational-like inequality (2.1) has a unique solution $u \in K$.*

Proof. Let u_1 and u_2 be arbitrary elements in K . As in the proof of Theorem 3.1, we deduce that

$$\|Gu_1 - Gu_2\| \leq \frac{\delta}{c + \xi} \|Fu_1 - Fu_2\| \leq \frac{\delta l}{c + \xi} \|u_1 - u_2\|, \quad \forall u_1, u_2 \in K, \tag{3.19}$$

which yields that $G : K \rightarrow K$ is a contraction mapping and hence it has a unique fixed point $u \in K$, which is a unique solution of the generalized nonlinear variational-like inequality (2.1). This completes the proof. \square

The following theorem follows from the arguments of Theorems 3.1, 3.2 and, 3.3.

THEOREM 3.4. *Let a, f, A, C, N , and η be as in Theorem 3.2. Suppose that $F : K \rightarrow H$ is Lipschitz continuous with constant l . If $0 < \delta l / (c + \xi - \delta\zeta\rho) < 1$, then the generalized nonlinear variational-like inequality (2.1) has a unique solution $u \in K$.*

4. Algorithm and convergence theorems

Based on Theorem 3.1, we suggest the following iterative algorithm.

ALGORITHM 4.1. Let $A, C, F : K \rightarrow H$, $N : H \times H \rightarrow H$, and $\eta : K \times K \rightarrow H$ be mappings, and let $f : K \rightarrow (-\infty, \infty]$ be a real functional. For any given $u_0 \in K$, compute sequence $\{u_n\}_{n \geq 0}$ by the iterative scheme

$$a(u_{n+1}, v - u_{n+1}) + f(v) - f(u_{n+1}) \geq \langle N(Au_{n+1}, Cu_{n+1}) + Fu_n, \eta(v, u_{n+1}) \rangle, \tag{4.1}$$

for all $v \in K$ and $n \geq 0$.

THEOREM 4.2. Let a, f, F, N, A, C , and η be as in Theorem 3.3. If $\delta l / (c + \xi) < 1$, then the generalized nonlinear variational-like inequality (2.1) possesses a unique solution and the iterative sequence $\{u_n\}_{n \geq 0}$ generated by Algorithm 4.1 converges strongly to the unique solution.

Proof. Using Algorithm 4.1, we obtain that

$$\begin{aligned} a(u_{n+1}, u_n - u_{n+1}) + f(u_n) - f(u_{n+1}) &\geq \langle N(Au_{n+1}, Cu_{n+1}) + Fu_n, \eta(u_n, u_{n+1}) \rangle, \\ a(u_n, u_{n+1} - u_n) + f(u_{n+1}) - f(u_n) &\geq \langle N(Au_n, Cu_n) + Fu_{n-1}, \eta(u_{n+1}, u_n) \rangle, \end{aligned} \tag{4.2}$$

for all $n \geq 1$. Adding (4.2), we get that

$$\begin{aligned} c \|u_{n+1} - u_n\|^2 &\leq a(u_{n+1} - u_n, u_{n+1} - u_n) \\ &\leq \langle N(Au_{n+1}, Cu_{n+1}) - N(Au_n, Cu_{n+1}), \eta(u_{n+1}, u_n) \rangle \\ &\quad + \langle N(Au_n, Cu_{n+1}) - N(Au_n, Cu_n), \eta(u_{n+1}, u_n) \rangle \\ &\quad + \langle Fu_n - Fu_{n-1}, \eta(u_{n+1}, u_n) \rangle \\ &\leq -\xi \|u_{n+1} - u_n\|^2 + \delta l \|u_n - u_{n-1}\| \|u_{n+1} - u_n\|, \end{aligned} \tag{4.3}$$

that is,

$$\|u_{n+1} - u_n\| \leq \frac{\delta l}{c + \xi} \|u_n - u_{n-1}\|, \quad \forall n \geq 1, \tag{4.4}$$

which yields that $\{u_n\}_{n \geq 0}$ is a Cauchy sequence by $\delta l / (c + \xi) < 1$. Consequently, $\{u_n\}_{n \geq 0}$ converges to some element u in K . Letting $n \rightarrow \infty$ in (4.1), we infer that

$$a(u, v - u) + f(v) - f(u) \geq \langle N(Au, Cu) + Fu, \eta(v, u) \rangle, \quad \forall v \in K. \tag{4.5}$$

Hence u is a solution of the generalized nonlinear variational-like inequality (2.1). It follows from Theorem 3.3 that u is the unique solution of the generalized nonlinear variational-like inequality (2.1). This completes the proof. \square

Similarly we have the following result.

THEOREM 4.3. *Let $a, f, F, N, A, C,$ and η be as in Theorem 3.4. If $0 < \delta l / (c + \xi - \delta \zeta \rho) < 1,$ then the generalized nonlinear variational-like inequality (2.1) possesses a unique solution and the iterative sequence $\{u_n\}_{n \geq 0}$ generated by Algorithm 4.1 converges strongly to the unique solution.*

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