A REMARK ON kTH-ORDER LINEAR FUNCTIONAL EQUATIONS WITH CONSTANT COEFFICIENTS

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Abel functional equations are associated to a linear homogeneous functional equation with constant coefficients. The work uses the space *S* of continuous strictly monotonic functions. Generalized terms are used, because of the space *S*, like composite function, iterates of a function, Abel functional equation, and linear homogeneous functional equation in *S* with constant coefficients. The classical theory of linear homogeneous functional and difference equations is obtained as a special case of the theory in space *S*. Equivalence of points and orbits of a point are introduced to show the connection between the linear functional and the linear difference equations in *S*. Asymptotic behavior at infinity is studied for a solution of the linear functional equation.

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1. Introduction

The linear functional equations are considered in the space of real-valued functions of a real variable $x \in \mathcal{J}$, $\mathcal{J} = (-\infty, \infty)$. The set \mathbb{N} denotes the set of positive integers. The set \mathbb{Z} denotes integers, and the set \mathbb{R} denotes real numbers. Symbol $C_0(\mathcal{J})$ is the set of continuous functions on the interval \mathcal{J} .

Definitions of the terms which we generalize in the space S can be found in [1-5]. In particular, we generalize the notions of iterates and linear homogeneous functional equations with constant coefficients.

- **1.1. Definition of the space** *S*. A function $f \in C_0(\mathcal{J})$ belongs to *S* if and only if it maps the interval \mathcal{J} one-to-one onto the interval (a,b), where $a \in \mathbb{R}$ or $a = -\infty$, $b \in \mathbb{R}$ or $b = \infty$.
- **1.2. Multiplication in** *S***.** Let us choose in *S* an arbitrary function *X*, a so-called *canonical function*, and let X^* be the inverse function to *X*. Let $F, G \in S$. The composite function $H = FX^*G(x)$ will be called a *product* and denoted by $\mathbf{H} = \mathbf{F} \circ \mathbf{G}$.

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It is easy to show that $H \in S$. The set S with the operation of multiplication \circ forms a noncommutative group \mathcal{G} , where the canonical function X is the neutral element. Further, to each element $F \in S$ there is an inverse element $F^{-1} = XF^*X$ in \mathcal{G} , where $F^* \in S$ is the inverse function to $F \in S$.

Boldface promotion of symbols will be used to denote elements of \mathcal{G} . Then $F,G \in S$ correspond to $F,G \in \mathcal{G}$ and \mathcal{G} -multiplication is defined by composition:

$$\mathbf{F} \circ \mathbf{G}(x) \equiv F(X^*(G(x))). \tag{1.1}$$

If $f \in C_0(\mathcal{J})$, $\Phi \in S$, then the product $f \circ \Phi(x)$ (not necessarily in \mathcal{G}) is defined to be the composite function $f(X^*(\Phi(x))) \in C_0(\mathcal{J})$. In general, f is not one-to-one; boldface promotion of f is disallowed, because $f \notin S$.

1.3. Iteration in *S***.** Let $X \in S$ be the canonical function. Let $\Phi \in S$. The *iterates* of the function Φ in S are given by group operations as follows:

$$\mathbf{\Phi}^{0}(x) = X(x),$$

$$\mathbf{\Phi}^{n+1}(x) = \mathbf{\Phi} \circ \mathbf{\Phi}^{n}(x), \quad x \in \mathcal{J}, \ n = 0, 1, 2, \dots,$$

$$\mathbf{\Phi}^{n-1}(x) = \mathbf{\Phi}^{-1} \circ \mathbf{\Phi}^{n}(x), \quad x \in \mathcal{J}, \ n = 0, -1, -2, \dots,$$

$$(1.2)$$

where Φ^{-1} is the inverse element to the element Φ in S according to multiplication \circ in group \mathcal{G} .

2. Linear functional equations of the kth order with constant coefficients

Let $a_i \in \mathbb{R}$, j = 0, 1, 2, ..., k. Then the equation

$$a_k f \circ \Phi^k(x) + a_{k-1} f \circ \Phi^{k-1}(x) + \dots + a_1 f \circ \Phi^1(x) + a_0 f \circ \Phi^0(x) = 0$$
 (2.1)

in S is called a *linear homogeneous functional equation of kth order with constant coefficients*. The *coefficients* are the constants a_j , j=0,1,2,...,k. It is assumed that $a_k \neq 0$. A *solution* of (2.1) is a function $f \in C_0(\mathcal{J})$ that satisfies the equation for all x. It is not assumed that f is one-to-one.

Let g(x) = X(x+1) and let $\Phi \in S$. The generalized Abel functional equation

$$\boldsymbol{\alpha} \circ \boldsymbol{\Phi}(x) = \mathbf{g} \circ \boldsymbol{\alpha}(x) \tag{2.2}$$

is called the *associated functional equation* to (2.1). A *solution* of (2.2) is a function $\alpha \in S$ such that (2.2) holds for all x.

The algebraic equation

$$a_k \lambda^k + a_{k-1} \lambda^{k-1} + \dots + a_1 \lambda + a_0 = 0$$
 (2.3)

is called the *characteristic equation* of (2.1). The left side of (2.3) is called the *characteristic polynomial* of (2.1).

THEOREM 2.1. Let (2.1) be given. Let $\lambda_1, \lambda_2, ..., \lambda_k$ be simple positive roots of the characteristic equation (2.3). Let α be a continuous solution of the associated Abel functional equation (2.2). Then the functions

$$f_1 = \lambda_1^{X^* \alpha(x)}, \qquad f_2 = \lambda_2^{X^* \alpha(x)}, \dots, f_k = \lambda_k^{X^* \alpha(x)},$$
 (2.4)

are linearly independent solutions of (2.1).

Proof. Functions (2.4) have the form

$$f = \lambda^{X^* \alpha(x)}, \tag{2.5}$$

where $\alpha \in S$ is a solution of the Abel equation (2.2) and $X^*\alpha(x)$ denotes the composite function $X^*(\alpha(x))$. Substitute (2.5) into (2.1), then

$$\sum_{n=0}^{k} a_n \lambda^{X^* \alpha \circ \Phi^n(x)} = 0. \tag{2.6}$$

Abel functional equation (2.2) implies

$$X^* \alpha \circ \Phi^n(x) = X^* X (X^* \alpha(x) + n) = X^* \alpha(x) + n,$$
 (2.7)

n = 0, 1, 2, ..., k, and then

$$\lambda^{X^*\alpha(x)} \left[\sum_{n=0}^k a_n \lambda^n \right] = 0. \tag{2.8}$$

Thus the function (2.5) is a solution of (2.1) if λ is a root of the characteristic equation (2.3). Roots of the characteristic equation have to be positive for the functions (2.5) to be defined.

To show the solutions (2.4) are linearly independent, consider a linear combination $c_1 f_1(x) + \cdots + c_k f_k(x) = 0$ for all x. Choose samples $x = X^*(x_0), x = X^*(\Phi(x_0)), x = X^*(\Phi(x_0))$ $X^*(\Phi^2(x_0))$, and so forth, and form the matrix equation $A\mathbf{c} = \mathbf{0}$ for the coefficients \mathbf{c} , using the sampling matrix

$$A = \begin{pmatrix} f_{1} \circ \mathbf{\Phi}^{0}(x_{0}) & f_{2} \circ \mathbf{\Phi}^{0}(x_{0}) & \cdots & f_{k} \circ \mathbf{\Phi}^{0}(x_{0}) \\ f_{1} \circ \mathbf{\Phi}^{1}(x_{0}) & f_{2} \circ \mathbf{\Phi}^{1}(x_{0}) & \cdots & f_{k} \circ \mathbf{\Phi}^{1}(x_{0}) \\ \vdots & \vdots & \vdots & \vdots \\ f_{1} \circ \mathbf{\Phi}^{k-1}(x_{0}) & f_{2} \circ \mathbf{\Phi}^{k-1}(x_{0}) & \cdots & f_{k} \circ \mathbf{\Phi}^{k-1}(x_{0}) \end{pmatrix}.$$
(2.9)

Abel equation can be used to show that $det(A) \neq 0$ for any x_0 in \mathcal{J} . The idea is born from the relation $f_r \circ \Phi^n(x) = f_r(x)\lambda_r^n$ and the theory of Vandermonde determinants. Therefore, $\mathbf{c} = \mathbf{0}$ and the functions are independent. The proof is complete.

Automorphic functions. A function $p \in C_0(\mathcal{J})$ is called automorphic over Φ provided $p = p \circ \Phi$. While constant functions are automorphic with respect to any Φ , there are examples of nonconstant automorphic functions. One such is $p(x) = \sin(\pi(x-n))$ on

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 $n \le x < n+1$, which satisfies p(x) = p(x+1) or $p = p \circ \Phi$ for $\Phi(x) = x+1$. Others can be constructed from this example.

THEOREM 2.2. Let (2.1) be given having solution f_0 . Let p be a continuous automorphic function, $p = p \circ \Phi$. Then $f(x) = p(x) f_0(x)$ is also a solution of (2.1).

A more general solution is of the form

$$c_1 f_1 + c_2 f_2 + \dots + c_k f_k,$$
 (2.10)

where $c_1, c_2, ..., c_k$ are automorphic functions over Φ and $f_1, ..., f_k$ are solutions of (2.1).

Proof. The details to show f_0 satisfies (2.1) are as follows:

$$\sum_{n=0}^{k} a_{n}(p f_{0}) \circ \Phi^{n}(x) = \sum_{n=0}^{k} a_{n}(p \circ \Phi^{n}(x)) (f_{0} \circ \Phi^{n}(x))$$

$$= \sum_{n=0}^{k} a_{n}(p(x)) (f_{0} \circ \Phi^{n}(x))$$

$$= p(x) \sum_{n=0}^{k} a_{n}(f_{0} \circ \Phi^{n}(x))$$

$$= 0$$
(2.11)

The proof is complete.

Theorem 2.3. Let (2.1) be given. Let λ_0 be a positive real root of characteristic equation (2.3), of multiplicity s, $1 \le s \le k$. Let $\alpha(x)$ be a continuous solution of Abel functional equation (2.2) and let X^* be the inverse function to canonical function X. Then the functions

$$f_r = (X^* \alpha(x))^r \lambda_0^{X^* \alpha(x)}, \quad 0 \le r < s,$$
 (2.12)

are independent solutions of (2.1).

Proof. Let $p(\lambda)$ denote the characteristic polynomial. Assume for the first part of the proof that X is the identity map. Define $f(x) = (\alpha(x))^r \lambda_0^{\alpha(x)}$. The following lemmas will be applied to complete the proof.

Lemma 2.4. If
$$L = \lambda(d/d\lambda)$$
, then $L^q(p(\lambda)) = \sum_{n=0}^k n^q a_n \lambda^n$ for $q \ge 0$.

LEMMA 2.5. If
$$\lambda = \lambda_0$$
 and $0 \le m \le r < s$, then $\sum_{n=0}^k n^{r-m} a_n \lambda^n = 0$.

Lemma 2.6. $\{(\alpha(x))^r \lambda_0^{\alpha(x)}\}_{r=0}^{s-1}$ are independent if and only if the powers $\{(\alpha(x))^r\}_{r=0}^{s-1}$ are independent.

LEMMA 2.7. Let $t_n = \alpha(x_0) + n$. Define matrix

$$A = \begin{pmatrix} 1 & t_1 & \cdots & t_1^{s-1} \\ 1 & t_2 & \cdots & t_1^{s-1} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & t_s & \cdots & t_s^{s-1} \end{pmatrix}.$$
 (2.13)

Then $det(A) \neq 0$ and the powers of Lemma 2.6 are independent.

The proofs of the lemmas: for Lemma 2.4 use induction on q. For Lemma 2.5 the left side of the equation is $L^q(p(\lambda))$ for $q = r - m \ge 0$. Apply Lemma 2.4. Expand $L^q(p(\lambda))$ by calculus to verify that being zero at $\lambda = \lambda_0$ is possible because the derivatives $(d/d\lambda)^n p(\lambda)$ are zero at $\lambda = \lambda_0$ for $0 \le r < s$, due to multiplicity of the root λ_0 . For Lemma 2.6 write down a linear combination equal to zero. Cancel $\lambda_0^{\alpha(x)}$. For Lemma 2.7 the determinant is a Vandermonde determinant, known to be nonzero for distinct sample values t_1, \ldots, t_s . The connection to the Abel equation is made by choosing sample values $x = x_0$, x = $\Phi(x_0)$, and so forth, in the linear combination $c_1 + c_2\alpha(x) + \cdots + c_s(\alpha(x))^{s-1} = 0$, and then writing the system $A\mathbf{c} = \mathbf{0}$ for vector \mathbf{c} to show $\mathbf{c} = \mathbf{0}$.

The proof that functions (2.12) satisfy the equation proceeds by inserting f into (2.1). The binomial formula $(a+b)^r = \sum_{m=0}^r {r \choose m} a^m b^{r-m}$ is applied to give

$$\sum_{n=0}^{k} a_n f \circ \mathbf{\Phi}^n(x) = \sum_{n=0}^{k} a_n (\alpha(x) + n)^r \lambda_0^{\alpha(x) + n}$$

$$= \left(\sum_{m=0}^{r} {r \choose m} \left(\sum_{n=0}^{k} n^{r-m} a_n \lambda_0^n\right) (\alpha(x))^m \right) \lambda_0^{\alpha(x)}$$

$$= \left(\sum_{m=0}^{r} {r \choose m} (0) (\alpha(x))^m \right) \lambda_0^{\alpha(x)}$$

$$= 0,$$
(2.14)

the last step is justified by Lemma 2.5.

Independence follows directly from Lemmas 2.6 and 2.7. The details of proof for general X parallel the above steps, essentially replacing α by $X^*\alpha$. The proof is complete.

Theorem 2.8. If the characteristic equation (2.3) has conjugate complex roots $\lambda_1 = \bar{\lambda}_2 =$ $r(\cos \omega + i \sin \omega)$, then the corresponding linear homogeneous functional equation possesses two solutions in the form

$$f_1 = r^{X^*\alpha(x)}\cos(\omega X^*\alpha(x)), \qquad f_2 = r^{X^*\alpha(x)}\sin(\omega X^*\alpha(x)). \tag{2.15}$$

The proof is left to the reader.

3. An application

Let *S* be the space of all continuous functions which map the interval $(-\infty, \infty)$ one-to-one onto itself. Let the canonical function be X(x) = x (identity), then $X^*(x) = x$. Let $\Phi(x) = x + 1$. The Abel functional equation is then

$$\alpha(x+1) = \alpha(x) + 1. \tag{3.1}$$

A linear homogeneous functional equation with constant coefficients is

$$a_k f \Phi^k(x) + a_{k-1} f \Phi^{k-1}(x) + \dots + a_1 f \Phi^1(x) + a_0, f \Phi^0(x) = 0,$$
 (3.2)

where $f\Phi^j(x)$ is a composite function $f(\Phi^j(x))$, j=1,2,...,k, and Φ^j is defined by successive composition. Suppose $\lambda > 0$ is a root of the characteristic equation. By the theorems above, it has a solution of the form

$$f = \lambda^{\alpha(x)},\tag{3.3}$$

where α satisfies Abel equation (3.1).

Linear system (3.2) is a linear difference equation with constant coefficients of the form

$$a_k f(x+k) + a_{k-1} f(x+k-1) + \dots + a_1 f(x+1) + a_0 f(x) = 0,$$
 (3.4)

because $\Phi(x) = x + 1$. Abel equation (3.1) has a solution $\alpha(x) = x$. If λ is a positive root of the characteristic equation, then the function $f = \lambda^x$ is a solution of (3.4).

3.1. Equivalence of points in \mathcal{J} , **orbit of a point in** S. Let $\Phi \in S$. Two points $x, y \in \mathcal{J}$ are Φ -equivalent if and only if there are numbers $\mu, \nu \in \mathbb{Z}$ such that

$$\Phi^{\mu}(x) = \Phi^{\nu}(y). \tag{3.5}$$

The equivalence is reflexive, symmetric, and transitive. It means that there is a decomposition of the set \mathcal{J} into disjoint sets of equivalent points.

The set $O_{\Phi}(x_0)$ of all points Φ-equivalent to a point $x_0 \in J$ is called the Φ-*orbit* of the point x_0 .

For the classical difference equation (3.4), in which $X(x) = X^*(x) = x$ and $\Phi(x) = x + 1$, the orbit of 0 is the set \mathbb{Z} of integers and the orbit of x_0 is the translate of this set by x_0 : $O_{\Phi}(x_0) = \{x_0 + \mu\}_{\mu = -\infty}^{\infty}$.

Lemma 3.1. Let $x_0 \in \mathcal{J}$, $\mu, \nu \in \mathbb{Z}$. Let

$$x_{\mu} = X^* \Phi^{\mu}(x_0). \tag{3.6}$$

Then the set of points $\{x_{\mu}\}_{\mu=-\infty}^{\infty}$ is the Φ -orbit of the point x_0 .

Proof. Because $\Phi^0 = X$ and $x_\mu \in \mathcal{J}$, then $x_0 = X^*\Phi^0(x_0)$. Let $p, q \in \mathbb{Z}$. To show that each two points x_p , x_q defined by (3.6) are Φ-equivalent in \mathcal{J} , we will show that there are numbers $\mu, \nu \in \mathbb{Z}$ such that

$$\mathbf{\Phi}^{\mu}(x_p) = \mathbf{\Phi}^{\nu}(x_q). \tag{3.7}$$

Use formula (3.6) to show that (3.7) is equivalent to

$$\mathbf{\Phi}^{\mu}(X^*(\mathbf{\Phi}^p(x_0))) = \mathbf{\Phi}^{\nu}(X^*(\mathbf{\Phi}^q(x_0))). \tag{3.8}$$

The definition of multiplication of implies the above is equivalent to

$$\mathbf{\Phi}^{\mu+p}(x_0) = \mathbf{\Phi}^{\nu+q}(x_0). \tag{3.9}$$

Choose $\mu = q$, $\nu = p$ to obtain (3.7).

3.2. Behavior of solutions at infinity. Consider a linear homogeneous kth-order functional equation with constant coefficients (2.1). Let the characteristic equation (2.3) have roots satisfying

$$\lambda_1 > \lambda_2 > \dots > \lambda_k > 0. \tag{3.10}$$

Let $\alpha \in S$ be a solution of the Abel functional equation (2.2) and let X^* be the inverse function to canonical function X. Assume c_1, \ldots, c_k are continuous Φ -automorphic functions on J, that is, $c_j = c_j \circ \Phi$. Then a solution of (2.1) is given by

$$f(x) = c_1(x)\lambda_1^{X^*\alpha(x)} + c_2(x)\lambda_2^{X^*\alpha(x)} + \dots + c_k(x)\lambda_k^{X^*\alpha(x)}.$$
 (3.11)

The right side of (3.11) can be rearranged into the expression

$$f(x) = \lambda_1^{X^* \alpha(x)} \left[c_1(x) + c_2(x) \left(\frac{\lambda_2}{\lambda_1} \right)^{X^* \alpha(x)} + \dots + c_k(x) \left(\frac{\lambda_k}{\lambda_1} \right)^{X^* \alpha(x)} \right]. \tag{3.12}$$

The inequalities

$$0 < \frac{\lambda_j}{\lambda_1} < 1, \quad j = 2, 3, \dots, k,$$
 (3.13)

imply

$$\lim_{x \to \infty} c_j(x) \left(\frac{\lambda_j}{\lambda_1}\right)^{X^* \alpha(x)} = 0. \tag{3.14}$$

Formally, at least,

$$\lim_{x \to \infty} f(x) = \lim_{x \to \infty} c_1(x) \lambda_1^{X^* \alpha(x)}. \tag{3.15}$$

We will discuss the meaning of (3.15). The following situations can occur.

- (1) If $\lambda_1 > 1$, then $\lim_{x \to \infty} f(x) = \infty$, because $\lim_{x \to \infty} X^* \alpha(x) = \infty$.
- (2) If $\lambda_1 = 1$, then $\lim_{x \to \infty} f(x)$ does not generally exist.
- (3) If $\lambda_1 < 1$, then $\lim_{x \to \infty} f(x) = 0$, because $\lim_{x \to \infty} X^* \alpha(x) = \infty$.

Consider (2.1) on the Φ -orbit of a point $x_0 \in \mathcal{J}$. Then sequences

$$\{\lambda_1^{X^*\alpha X^*\Phi^n(x_0)}\}, \{\lambda_2^{X^*\alpha X^*\Phi^n(x_0)}\}, \dots, \{\lambda_k^{X^*\alpha X^*\Phi^n(x_0)}\}$$
(3.16)

are the solutions evaluated along the Φ -orbit. Because $\alpha \in S$ satisfies Abel functional equation (2.2), then the sequences can be written in the form

$$\{\lambda_1^{\alpha(x_0)+n}\}_{n=1}^{\infty}, \{\lambda_2^{\alpha(x_0)+n}\}_{n=1}^{\infty}, \dots, \{\lambda_k^{\alpha(x_0)+n}\}_{n=1}^{\infty}.$$
 (3.17)

Therefore, we have a solution formula

$$f(x_0+n) = c_1(x_0)\lambda_1^{\alpha(x_0)+n} + c_2(x_0)\lambda_2^{\alpha(x_0)+n} + \dots + c_k(x_0)\lambda_k^{\alpha(x_0)+n}.$$
 (3.18)

Using the ideas above, the limits at infinity are determined as follows.

- (1) If $\lambda_1 > 1$, then $\{\lambda_1^{\alpha(x_0)+n}\}$ diverges to ∞ and $\lim_{n\to\infty} f(x_0+n) = \infty$.
- (2) If $\lambda_1 = 1$, then $\{\lambda_1^{\alpha(x_0)+n}\}$ is a constant sequence of ones and the sequence $\{c_1(x_0), \lambda_1^{\alpha(x_0)+n}\}$ is a constant sequence of numbers $c_1(x_0)$. Hence $\lim_{n\to\infty} f(x_0+n) = c_1(x_0)$.
- (3) If $0 < \lambda_1 < 1$, then the sequence $\{c_1(x_0)\lambda_1^{\alpha(x_0)+n}\}$ is a decreasing sequence convergent to zero and $\lim_{n\to\infty} f(x_0+n) = 0$.

Note 3.2. The limit for $x \to -\infty$ can be determined using the same techniques of analysis.

Note 3.3. The results for behavior of solutions for difference equations can be obtained from the results for (2.1). The idea is to evaluate along the orbit $O_{\Phi}(x_0)$, $x_0 \in \mathcal{J}$.

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