SOLUTIONS TO *H*-SYSTEMS BY TOPOLOGICAL AND ITERATIVE METHODS

P. AMSTER AND M. C. MARIANI

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We study H-systems with a Dirichlet boundary data g. Under some conditions, we show that if the problem admits a solution for some (H_0, g_0) , then it can be solved for any (H, g) close enough to (H_0, g_0) . Moreover, we construct a solution of the problem applying a Newton iteration.

1. Introduction

We consider the Dirichlet problem in a bounded $C^{1,1}$ domain $\Omega \subset \mathbb{R}^2$ for a vector function $X : \overline{\Omega} \to \mathbb{R}^3$ which satisfies the equation of prescribed mean curvature

$$\Delta X = 2H(u, v, X)X_u \wedge X_v \quad \text{in } \Omega,$$

$$X = g \quad \text{on } \partial \Omega,$$
(1.1)

where \land denotes the exterior product in \mathbb{R}^3 , $H : \overline{\Omega} \times \mathbb{R}^3 \to \mathbb{R}$ is a given continuous function, and the boundary data g is smooth. Problem (1.1) above arises in the Plateau and Dirichlet problems for the prescribed mean curvature equation that has been studied, for example, in [1, 2, 3, 4, 5].

In Section 2, we prove the following theorem.

THEOREM 1.1. Let $X_0 \in W^{2,p}(\Omega,\mathbb{R}^3)$ be a solution of (1.1) for some (H_0,g_0) with $g_0 \in W^{2,p}(\Omega,\mathbb{R}^3)$ $(2 and <math>H_0$ continuously differentiable with respect to X over the graph of X_0 . Set

$$k = -2 \inf_{(u,v,Y) \in \Omega \times \mathbb{R}^3, |Y| = 1} \left(\frac{\partial H_0}{\partial X} (u,v,X_0) Y \right) ((X_{0_u} \wedge X_{0_v}) Y)$$
(1.2)

and assume that

$$k + 2\sqrt{\lambda_1} ||H_0(\cdot, X_0)||_{\infty} ||\nabla X_0||_{\infty} < \lambda_1,$$
 (1.3)

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where λ_1 is the first eigenvalue of $-\Delta$. Then there exists a neighborhood \Re of (H_0,g_0) in the space $C(\overline{\Omega}\times\mathbb{R}^3,\mathbb{R})\times W^{2,p}(\Omega,\mathbb{R}^3)$ such that (1.1) is solvable for any $(H,g) \in \mathcal{B}$.

Remark 1.2. It is clear that

$$0 \leq -2 \inf_{(u,v)\in\Omega} \frac{\partial H_0}{\partial X} (u,v,X_0) (X_{0_u} \wedge X_{0_v})$$

$$\leq k \leq 2 \left\| \frac{\partial H_0}{\partial X} (\cdot,X_0) \right\|_{\infty} \left\| X_{0_u} \wedge X_{0_v} \right\|_{\infty}.$$
(1.4)

Moreover, a simple computation shows that k = 0 if and only if $(\partial H_0/\partial X)(\cdot, X_0)$ and $X_{0_u} \wedge X_{0_v}$ are linearly dependent, with $(\partial H_0/\partial X)(u,v,X_0)(X_{0_u} \wedge X_{0_v}) \ge 0$ for every $(u, v) \in \Omega$.

In Section 3, we show that the solution provided by Theorem 1.1 can be obtained by a Newton iteration. For simplicity, we consider the case where H does not depend on *X* and prove the following theorem.

THEOREM 1.3. Let $X_0 \in W^{2,p}(\Omega,\mathbb{R}^3)$ be a solution of (1.1) for some (H_0,g_0) with $g_0 \in W^{2,p}(\Omega,\mathbb{R}^3)$ $(2 and <math>H_0$ continuous, and assume that

$$2||H_0||_{\infty}||\nabla X_0||_{\infty} < \sqrt{\lambda_1}. \tag{1.5}$$

Then, if H and g are close enough to H_0 and g_0 , respectively, the sequence given by

$$\Delta X_{n+1} = 2H \left[\left(X_{n_u} \wedge \left(X_{n+1} - X_n \right)_{\nu} + \left(X_{n+1} - X_n \right)_{u} \wedge X_{n_{\nu}} \right) - X_{n_u} \wedge X_{n_{\nu}} \right],$$

$$X_{n+1} \mid_{\partial \Omega} = g$$
(1.6)

is well defined and converges in $W^{2,p}(\Omega,\mathbb{R}^3)$ to a solution of (1.1).

2. Proof of Theorem 1.1

First we will prove a slight extension of a well-known result for linear elliptic second-order operators.

LEMMA 2.1. Let $L: W^{2,p}(\Omega,\mathbb{R}^3) \to L^p(\Omega,\mathbb{R}^3)$ be the linear elliptic operator given by $LX = \Delta X + AX_u + BX_v + CX$ with $A, B, C \in L^{\infty}(\Omega, \mathbb{R}^{3\times 3})$ (2 , and assume that $r:=((\||A|^2+|B|^2\|_{\infty})/\lambda_1)^{1/2}<1$ and that $CY\cdot Y\leq \kappa |Y|^2$ for every $Y \in \mathbb{R}^3$ with $\kappa < \lambda_1(1-r)$. Then $L|_{W_0^{1,p}(\Omega,\mathbb{R}^3)} : W^{2,p} \cap W_0^{1,p}(\Omega,\mathbb{R}^3) \to L^p(\Omega,\mathbb{R}^3)$ is an isomorphism.

Proof. Let $Z_n \in W^{2,p} \cap W_0^{1,p}(\Omega, \mathbb{R}^3)$ be a sequence such that $||LZ_n||_p \to 0$. Then $||LZ_n||_2 \to 0$, and from the inequalities

$$-\int LZ_{n}Z_{n} \geq ||\nabla Z_{n}||_{2}^{2} - ||(|A|^{2} + |B|^{2})^{1/2}||_{\infty} ||\nabla Z_{n}||_{2} ||Z_{n}||_{2} - \int CZ_{n}Z_{n}$$

$$\geq \left(1 - r - \frac{\kappa}{\lambda_{1}}\right) ||\nabla Z_{n}||_{2}^{2}, \tag{2.1}$$

we deduce that $\|\nabla Z_n\|_2 \to 0$. Thus, $\|Z_n\|_2 \to 0$ and hence $\|\Delta Z_n\|_2 \to 0$. From the invertibility of Δ , there exists a subsequence (still denoted Z_n) such that $\|Z_n\|_{2,2} \to 0$. By Sobolev imbedding, $\|Z_n\|_{1,p} \to 0$ and we conclude that $\|\Delta Z_n\|_p \to 0$. In order to prove that L is onto, it suffices to consider for any $\varphi \in L^p(\Omega)$, the homotopy

$$\Delta X = \sigma (\varphi - AX_u - BX_v - CX) \tag{2.2}$$

and apply a Leray-Schauder argument.

Now we are able to prove Theorem 1.1. Consider a pair (H,g) with $||g - g_0||_{2,p} < \delta$ and $||(H - H_0)|_K||_{\infty} < \varepsilon$ for some compact K containing a neighborhood of the graph of X_0 . Setting $Y = X - X_0$, equation (1.1) is equivalent to the problem

$$LY = F(u, v, Y, Y_u, Y_v) \quad \text{in } \Omega,$$

$$Y = g - g_0 \quad \text{on } \partial\Omega,$$
(2.3)

where *L* is the linear operator given by

$$LY = \Delta Y - 2H_0(u, v, X_0) \left[X_{0_u} \wedge Y_v + Y_u \wedge X_{0_v} \right] - 2 \left(\frac{\partial H_0}{\partial X} (u, v, X_0) Y \right) X_{0_u} \wedge X_{0_v}$$
(2.4)

and

$$F(u, v, Y, Y_{u}, Y_{v})$$

$$:= 2\Big(H(u, v, X_{0} + Y)Y_{u} \wedge Y_{v} + [H(u, v, X_{0} + Y) - H_{0}(u, v, X_{0})](X_{0_{u}} \wedge Y_{v} + Y_{u} \wedge X_{0_{v}}) + \Big[H(u, v, X_{0} + Y) - H_{0}(u, v, X_{0}) - \frac{\partial H_{0}}{\partial X}(u, v, X_{0})Y\Big]X_{0_{u}} \wedge X_{0_{v}}\Big).$$
(2.5)

We define an operator $T: C^1(\overline{\Omega}, \mathbb{R}^3) \to C^1(\overline{\Omega}, \mathbb{R}^3)$ given by $T(\overline{Y}) = Y$ where Y is the unique solution of the linear problem

$$LY = F(u, v, \overline{Y}, \overline{Y}_u, \overline{Y}_v) \quad \text{in } \Omega,$$

$$Y = g - g_0 \quad \text{on } \partial\Omega.$$
(2.6)

As L satisfies the hypothesis of Lemma 2.1, it is immediate to prove that T is well defined and continuous. Furthermore, the range of a bounded set is bounded with $\| \|_{2,p}$, and by Sobolev imbedding, we conclude that T is compact. More precisely, for $\|\overline{Y}\|_{1,\infty} \le R$, we obtain

$$||T(\overline{Y})||_{1,\infty} \le ||g - g_0||_{1,\infty} + c||T(\overline{Y}) - (g - g_0)||_{2,p}$$

$$\le ||g - g_0||_{1,\infty} + c_1 (||L(T(\overline{Y}))||_p + ||L(g - g_0)||_p)$$

$$\le k_0 \delta + c_1 ||F(\cdot, \overline{Y}, \overline{Y}_u, \overline{Y}_v)||_p$$
(2.7)

for some constants k_0 and c_1 .

On the other hand, a simple computation shows that

$$||F(\cdot, \overline{Y}, \overline{Y}_u, \overline{Y}_v)||_p \le k_1 R^2 + k_2 \varepsilon R + k_3 \varepsilon$$
 (2.8)

for some constants k_1 , k_2 , and k_3 . Hence, if δ and ε are small, it is possible to choose R such that $T(B_R) \subset B_R$ and the result follows by Schauder's Theorem.

3. A Newton iteration for problem (1.1)

In this section, we apply a Newton iteration to (1.1). For simplicity, we will assume that H does not depend on X.

Let X_0 be a solution of (1.1) for some H_0 and g_0 with

$$2||H_0||_{\infty}||\nabla X_0||_{\infty} < \sqrt{\lambda_1}.$$
 (3.1)

In order to define a sequence that converges to a solution of (1.1) for (H,g) close to (H_0,g_0) , we consider the function $F: g + (W^{2,p} \cap W_0^{1,p}(\Omega,\mathbb{R}^3)) \to L^p(\Omega,\mathbb{R}^3)$ given by

$$F(X) = \Delta X - 2HX_u \wedge X_v. \tag{3.2}$$

Thus, the problem is equivalent to find a zero of *F*. The well-known Newton method consists in defining a recursive sequence

$$X_{n+1} = X_n - (DF(X_n))^{-1}(F(X_n))$$
(3.3)

or equivalently

$$DF(X_n)(X_{n+1} - X_n) = -F(X_n). (3.4)$$

A simple computation shows that in this case,

$$DF(X)(Y) = \Delta Y - 2H(X_u \wedge Y_v + Y_u \wedge X_v). \tag{3.5}$$

According to this, we start at X_0 and define the sequence $\{X_n\}$ from the following problem:

$$\Delta X_{n+1} - 2H(X_{n_u} \wedge (X_{n+1} - X_n)_v + (X_{n+1} - X_n)_u \wedge X_{n_v}) = 2HX_{n_u} \wedge X_{n_v}$$
 (3.6)

with Dirichlet condition

$$X_{n+1}|_{\partial\Omega} = g. (3.7)$$

We will prove that if H and g are close enough to H_0 and g_0 , respectively, this sequence is well defined (i.e., $DF(X_n)$ is invertible for every n) and converges.

Fix a positive *R* such that

$$R < \frac{\sqrt{\lambda_1}}{2||H_0(\cdot, X_0)||_{\infty}} - ||\nabla X_0||_{\infty}$$
 (3.8)

and set

$$\mathscr{C} = \left\{ X \in W^{2,p}(\Omega, \mathbb{R}^3) : X|_{\partial\Omega} = g, \ ||X - X_0||_{2,p} \le R \right\}. \tag{3.9}$$

We will assume that

$$||H - H_0||_{\infty} < \varepsilon, \qquad ||g - g_0||_{2,p} < \delta \le R$$
 (3.10)

with

$$\varepsilon < \frac{\sqrt{\lambda_1}}{2(||\nabla X_0||_{\infty} + R)} - ||H(\cdot, X_0)||_{\infty}. \tag{3.11}$$

For each $X \in \mathcal{C}$, we define the linear operator L_X given by

$$L_X Y = \Delta Y - 2H(X_u \wedge Y_v + Y_u \wedge X_v). \tag{3.12}$$

By Lemma 2.1, $L_X|_{W_0^{1,p}(\Omega)}$ is invertible for any $X \in \mathscr{C}$. Furthermore, we claim that $\|L_X^{-1}\|$ is bounded over \mathscr{C} . Indeed, for $Z \in W^{2,p} \cap W_0^{1,p}(\Omega,\mathbb{R}^3)$ and $X,Y \in \mathscr{C}$, we have

$$||L_{Y}Z||_{p} \ge ||L_{X}Z||_{p} - ||(L_{X} - L_{Y})Z||_{p}$$

$$\ge \left(\frac{1}{||L_{X}^{-1}||} - 2||H||_{\infty}||\nabla(X - Y)||_{\infty}\right)||Z||_{2,p}.$$
(3.13)

Taking, for example, Y such that $\|\nabla(Y - X)\|_{\infty} \le 1/(4\|H\|_{\infty}\|L_X^{-1}\|) := R_X$, we obtain

$$||L_Y^{-1}|| \le 2||L_X^{-1}||.$$
 (3.14)

By compactness, there exist $X^1, ..., X^n \in \mathcal{C}$ such that

$$\mathscr{C} \subset \bigcup_{i=1}^{n} \left\{ Y : \left| \left| \nabla \left(Y - X^{i} \right) \right| \right|_{\infty} \le R_{X^{i}} \right\}$$
 (3.15)

and hence,

$$||L_X^{-1}|| \le 2 \max_{1 \le i \le n} ||L_{X^i}^{-1}||.$$
 (3.16)

Let $Z_n = X_{n+1} - X_n$. For n = 0, we have

$$||Z_{0}||_{2,p} \leq ||g - g_{0}||_{2,p} + ||Z_{0} - (g - g_{0})||_{2,p}$$

$$\leq ||g - g_{0}||_{2,p} + c(||L_{X_{0}}Z_{0}||_{p} + ||L_{X_{0}}(g - g_{0})||_{p})$$

$$\leq 2\delta(1 + ||H||_{\infty}||\nabla X_{0}||_{\infty}) + c||L_{X_{0}}Z_{0}||_{p}.$$
(3.17)

As

$$||L_{X_0}Z_0||_p = ||2(H - H_0)X_{0_u} \wedge X_{0_v}||_{2p}^2 \le \varepsilon ||\nabla X_0||_p,$$
 (3.18)

we conclude that

$$||Z_0||_{2,p} \le 2\delta (1 + (||H_0||_{\infty} + \varepsilon)||\nabla X_0||_{\infty}) + c\varepsilon ||\nabla X_0||_{2p}^2 := c(\delta, \varepsilon).$$
 (3.19)

Then we may establish a more precise version of Theorem 1.3.

Theorem 3.1. With the previous notations, assume that

$$c(\delta, \varepsilon) \le \frac{R}{1 + Rc_0 c(||H_0||_{\infty} + \varepsilon)},$$
 (3.20)

where c_0 is the constant of the imbedding $W^{2,p}(\Omega,\mathbb{R}^3) \hookrightarrow C^1(\overline{\Omega},\mathbb{R}^3)$. Then the sequence given by (1.6) is well defined and converges in $W^{2,p}(\Omega,\mathbb{R}^3)$ to a solution of (1.1).

Proof. By (3.20), we have that $||Z_0||_{2,p} \le c(\delta, \varepsilon) \le R$, proving that $X_1 \in \mathcal{C}$. For n > 0, we assume as inductive hypothesis that $X_k \in \mathcal{C}$ for $k \le n$, and then

$$||Z_{n}||_{2,p} \leq c||L_{X_{n}}Z_{n}||_{p} = 2c||HZ_{n-1_{u}} \wedge Z_{n-1_{v}}||_{p}$$

$$\leq c||H||_{\infty}||\nabla Z_{n-1}||_{\infty}||\nabla Z_{n-1}||_{p}$$

$$\leq c_{0}c||H||_{\infty}||Z_{n-1}||_{2}^{2}.$$
(3.21)

Inductively,

$$||Z_n||_{2,p} \le (c_0 c ||H||_{\infty})^{2^n - 1} ||Z_0||_{2,p}^{2^n} = A^{2^n - 1} ||Z_0||_{2,p},$$
 (3.22)

where $A = c_0 c \|H\|_{\infty} \|Z_0\|_{2,p}$. By hypothesis, it is immediate that A < 1, and hence

$$||X_{n+1} - X_0||_{2,p} \le \sum_{j=0}^{n} ||Z_j||_{2,p} \le ||Z_0||_{2,p} \frac{1}{1-A} \le R.$$
 (3.23)

Thus, $X_n \in \mathcal{C}$ for every n, and

$$||X_{n+k} - X_n||_{2,p} \le \frac{A^{2^n - 1}}{1 - A}$$
 (3.24)

for every $k \ge 0$. Then X_n is a Cauchy sequence, and the result follows.

Remark 3.2. It is clear from definition that $c(\delta, \varepsilon) \to 0$ for $(\delta, \varepsilon) \to (0, 0)$.

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P. Amster: Departamento de Matemática, Facultad de Ciencias Exactas y Naturales, Universidad de Buenos Aires, Ciudad Universitaria, Pabellón I, 1428 Buenos Aires, Argentina *E-mail address*: pamster@dm.uba.ar

M. C. Mariani: Departamento de Matemática, Facultad de Ciencias Exactas y Naturales, Universidad de Buenos Aires, Ciudad Universitaria, Pabellón I, 1428 Buenos Aires, Argentina

E-mail address: mcmarian@dm.uba.ar