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Kalecki's model of business cycle. Data dependence¹

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Abstract

In this paper we study date dependence for a delay equation which models a business cycle. The study is made using weakly Picard operators.

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1 Introduction

Let (X, d) be a metric space and $A : X \longrightarrow X$ an operator. We shall use the following notations:

$$P(X) := \{ Y \subseteq X \mid Y \neq \emptyset \},\$$

the set of valid parts of X;

$$F_A := \{ x \in X \mid A(x) = x \},$$

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the fixed point set of A;

$$I(A) := \{ Y \in P(X) \mid A(Y) \subset Y \},\$$

the family of the nonempty invariant subset of A.

$$A^{n+1} = A \circ A^n, A^0 = 1_X, A^1 = A, n \in \mathbb{N}$$

Definition 1.1. ([2],[3]) An operator A is weakly Picard operator (WPO) if the sequence $(A^n(x))_{n\in\mathbb{N}}$ converges, for all $x \in X$ and the limit (which depend on x) is a fixed point of A.

Definition 1.2. ([2],[3]) If the operator A is weakly Picard operator and $F_A = \{x^*\}$ then by definition A is Picard operator.

Definition 1.3. ([2],[3]) If A is weakly Picard operator, then we consider the operator

$$A^{\infty}: X \longrightarrow X, A^{\infty}(x) = \lim_{n \longrightarrow \infty} A^n(x).$$

Observation 1.1. $A^{\infty}(x) = F_A$.

Definition 1.4. ([2],[3]) Let be A an WPO and c > 0. The operator A is c-weakly Picard operator if

$$d(x, A^{\infty}(x) \le c \cdot d(x, A(X)).$$

for all $x \in X$.

Observation 1.2. ([4]) If (X, d) is a metric space and $A : X \longrightarrow X$ an operator is a a-contraction, then A is c-weakly Picard operator with $c = \frac{1}{1-a}$.

The next result it is a characteristic of weakly Picard operator, respectively c-weakly Picard.

Theorem 1.1. ([2],[3]) Let (X,d) be a metric space and $A : X \longrightarrow X$ an operator. The operator A is weakly Picard operator (*c*-weakly Picard operator) if and only if there exists a partition of X,

$$X = \bigcup_{\lambda \in \Lambda} X_{\lambda}$$

such that:

2 Main result

We consider the equation

(1)
$$I'(t) = \frac{m}{t}I(t) - (\frac{m}{\tau} + n)I(t - \tau) + nu, t \in [0, T]$$

where $\tau > 0, m = \frac{p}{1-\alpha}, p > 0, n > 0, \alpha \in (0,1), u > 0$, with the initial condition

(2)
$$I(t) = \varphi(t), t \in [-\tau, 0]$$

with $\varphi : [-\tau, 0] \longrightarrow \mathbb{R}$.

The Cauchy problem (1) + (2) is equivalent with the next integral equation

(3)
$$I(t) = \begin{cases} \varphi(0) + \int_{0}^{t} [\frac{m}{\tau}I(s) - (\frac{m}{\tau} + \eta)I(s - \tau) + nu]ds , & t \in [0, T] \\ \varphi(t) & , & t \in [-\tau, 0] \end{cases}$$

We search the solutions for the integral equation (3) in the continuous functions space $(C[-\tau, T] | \cdot |_r)$ endowed with Bielecki norm,

$$|x|_r = \sup_{t \in [-\tau,T]} |x(t)| e^{-rt}.$$

Next, we consider the operator $A: C[-\tau, T] \longrightarrow C[-\tau, T]$, defined by

$$A(I)(t) = \begin{cases} \varphi(0) + \int_{0}^{t} [\frac{m}{\tau}I(s) - (\frac{m}{\tau} + \eta)I(s - \tau) + nu]ds & , \quad t \in [0, T] \\ \varphi(t) & , \quad t \in [-\tau, 0] \end{cases}$$

Then for any $I_1, I_2 \in C[-\tau, T]$ we have

$$\begin{aligned} |A(I_1)(t) - A(I_2)(t)| &\leq \int_0^t [\frac{m}{\tau} |I_1(s) - I_2(s)| + (\frac{m}{\tau} + n)|I_1(s - \tau) - I_2(s - \tau)|] ds \leq \\ &\leq |I_1 - I_2|_r \int_0^t \frac{m}{\tau} e^{rs} + (\frac{m}{\tau} + n)e^{r(s - \tau)} ds \leq \\ &\leq I_1 - I_2|_r e^{rt} \frac{\frac{2m}{\tau} + n}{r} e^{rt} \end{aligned}$$

It follows that

$$|A(I_1) - A(I_2)|_r \le \frac{\frac{2m}{\tau} + n}{r} \cdot |I_1 - I_2|_r$$

Using the Banach principle of fixed point it results that equation (3) has, in $C[-\tau, T]$, a unique solution $I^*(\cdot, \varphi)$.

In the following lines, using the characterization theorem of the weakly Picard operator we show that equation (1) has a infinity of solutions. Indeed, for $\varphi \in C[-\tau, 0]$, we consider

$$X_{\varphi} = \{ x \in C[-\tau, T] | x_{|[-\tau, 0]} = \varphi \}.$$

We choose r > 0 thus

$$\frac{2m}{\tau} + n < 1$$

it results

$$|A(I_1) - A(I_2)|_r \le \frac{\left(\frac{2m}{\tau} + n\right)}{r} |I_1 + I_2|.$$

According to the above, the operator $A|_{X_{\varphi}} : X_{\varphi} \longrightarrow X_{\varphi}$ is a Picard operator. Then A is a weakly Picard operator and as consequence the equation (1) has a infinity of solutions.

Next we assume that it exists $\eta > 0$ thus

$$|\varphi_1(t) - \varphi_2(t)| \le \eta.$$

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Let $I^*(\cdot, \varphi_1), I^*(\cdot, \varphi_2)$ be the solution of the equation (3) with data φ_1, φ_2 . Then

$$|I^{\star}(t,\varphi_1) - I^{\star}(t,\varphi_2)| \le$$

$$\leq \eta \int_{0}^{t} \left[\frac{m}{\tau} |I^{\star}(s,\varphi_{1}) - I^{\star}(s,\varphi_{2})| + (\frac{m}{\tau} + n)|I^{\star}(s-\tau,\varphi_{1}) - I^{\star}(t,\varphi_{2})|\right] ds.$$

According with Theorem 14.6 (see [1] pp 145) we obtain

$$|I_1(t) - I_2(t)| \le \eta k(m, n, \tau) e^{\int_0^t (\frac{2m}{\tau} + n)ds} \le \eta k(m, n, \tau) e^{(\frac{2m}{\tau} + n)T}$$

So, from above we obtain the following result

Theorem 2.1. We consider the equation (1). Then:

- (a) the equation (1) has, in $(C([-\tau, T]), |\cdot|_r)$ a infity of solutions;
- (b) the problem (1)+(2) has, in $C([-\tau,T]), |\cdot|_r$, a unique solution $I^*(\cdot,\varphi)$;
- (c) if there exists $\eta > 0$ such that

$$|\varphi_1(t) - \varphi_2(t)| \le \eta,$$

for all $t \in [-\tau, T]$, then there exists $k(m.n.\tau) > 0$ such that

$$|I^{\star}(t,\varphi_1) - I^{\star}(t,\varphi_2)| \le \eta k(m,n,\tau) e^{(\frac{2m}{\tau}+n)T}.$$

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