# DIAMETER BOUNDS FOR EQUAL AREA PARTITIONS OF THE UNIT SPHERE* 

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#### Abstract

The recursive zonal equal area (EQ) sphere partitioning algorithm is a practical algorithm for partitioning higher dimensional spheres into regions of equal area and small diameter. Another such construction is due to Feige and Schechtman. This paper gives a proof for the bounds on the diameter of regions for each of these partitions.


Key words. sphere, partition, area, diameter, zone
AMS subject classifications. $11 \mathrm{~K} 38,31-04,51 \mathrm{M} 15,52 \mathrm{C} 99,74 \mathrm{G} 65$

1. Introduction. Stolarsky [12, p. 581] asserts the existence for any natural number $N$ of a partition of the unit sphere $\mathbb{S}^{d} \subset \mathbb{R}^{d+1}$ into $N$ regions of equal area and small diameter. The recursive zonal equal area (EQ) sphere partitioning algorithm [8, Section 3] is a practical means to achieve such a partition. Feige and Schechtman [5] give a construction which can easily be modified to give another such partition.

In this paper we prove that the both EQ partition and the modified Feige-Schechtman partition satisfy Stolarsky's assertion. This paper is the companion to [8] and is meant to be read in conjunction with that paper. Any definitions and notation not found here are to be found in [8]. The proofs given here are based on those in the Ph.D. thesis [7] and much of the technical detail which has been omitted here can be found there.

This paper is organized as follows. Section 2 repeats enough of the definitions and theorems of [8] to orient the reader. Section 3 contains the continuous model of the EQ partition which is used in the proof of the properties of this partition. Section 4 proves that the EQ partition satisfies Stolarsky's assertion. Section 5 contains estimates which will be used in the remainder of the paper. Section 6 provides a proof that the modified Feige-Schechtman construction satisfies Stolarsky's assertion. An appendix provides proofs for some of the lemmas. Further proofs and more details can be found in [7].
2. Preliminaries. For convenience, this section repeats some of the definitions and restates some of the theorems given in [8].

For any two points $\mathbf{a}, \mathbf{b} \in \mathbb{S}^{d}$, the Euclidean and spherical distances are related by

$$
\|\mathbf{a}, \mathbf{b}\|=\Upsilon(s(\mathbf{a}, \mathbf{b}))
$$

where

$$
\begin{equation*}
\Upsilon(\theta):=\sqrt{2-2 \cos \theta}=2 \sin \frac{\theta}{2} \tag{2.1}
\end{equation*}
$$

For $d \geqslant 0$, the area of $\mathbb{S}^{d} \subset \mathbb{R}^{d+1}$ is given by [9, p. 1]

$$
\sigma\left(\mathbb{S}^{d}\right)=\frac{2 \pi^{\frac{d+1}{2}}}{\Gamma\left(\frac{d+1}{2}\right)}
$$

[^0]For all that follows, we will use the following abbreviations. For $d \geqslant 1$, we define

$$
\omega:=\sigma\left(\mathbb{S}^{d-1}\right) \quad \text { and } \quad \Omega:=\sigma\left(\mathbb{S}^{d}\right)
$$

The area of a spherical cap $S(\mathbf{a}, \theta)$ of spherical radius $\theta$ and center a is [6, Lemma 4.1 p. 255]

$$
\begin{equation*}
\mathcal{V}(\theta):=\sigma(S(\mathbf{a}, \theta))=\omega \int_{0}^{\theta}(\sin \xi)^{d-1} d \xi \tag{2.2}
\end{equation*}
$$

The function $\Theta$ is the inverse of $\mathcal{V}$.
This paper considers the Euclidean diameter of regions, defined as follows.
DEFINITION 2.1. The diameter of a region $R \in \mathbb{S}^{d} \subset \mathbb{R}^{d+1}$ is

$$
\operatorname{diam} R:=\sup \{\|\mathbf{x}-\mathbf{y}\| \mid \mathbf{x}, \mathbf{y} \in R\}
$$

The following definitions are specific to the main theorems stated here.
DEFInITION 2.2. A set $Z$ of partitions of $\mathbb{S}^{d}$ is said to be diameter-bounded with diameter bound $K \in \mathbb{R}_{+}$if for all $P \in Z$, for each $R \in P$,

$$
\operatorname{diam} R \leqslant K|P|^{-\frac{1}{d}}
$$

DEFINITION 2.3. The set of recursive zonal equal area partitions of $\mathbb{S}^{d}$ is defined as

$$
\mathrm{EQ}(d):=\left\{\mathrm{EQ}(d, N) \mid N \in \mathbb{N}_{+}\right\}
$$

where $\mathrm{EQ}(d, N)$ denotes the recursive zonal equal area partition of the unit sphere $\mathbb{S}^{d}$ into $N$ regions, which is defined via the algorithm given in [8, Section 3].

The partition $\mathrm{EQ}(d, N)$ has the following properties.
THEOREM 2.4. For $d \geqslant 1$ and $N \geqslant 1$, the partition $\mathrm{EQ}(d, N)$ is an equal area partition of $\mathbb{S}^{d}$.

The proof of Theorem 2.4 is straightforward, following immediately from the construction of the EQ partition [8, Section 3].

THEOREM 2.5. For $d \geqslant 1, \mathrm{EQ}(d)$ is diameter-bounded in the sense of Definition 2.2.
Theorem 2.5 is a special case of Stolarsky's assertion:
THEOREM 2.6. [12, p. 581] For each $d>0$, there is a constant $c_{d}$ such that for all $N>0$, there is a partition of the unit sphere $\mathbb{S}^{d}$ into $N$ regions, with each region having area $\Omega / N$ and diameter at most $c_{d} N^{-\frac{1}{d}}$.

We will also often refer to the following quantities, defined in steps 1 to 3 of the EQ partition algorithm for $\mathrm{EQ}(d, N)$ [8, Section 3.2].

$$
\begin{equation*}
\mathcal{V}_{R}:=\frac{\Omega}{N}, \quad \theta_{c}:=\Theta\left(\mathcal{V}_{R}\right), \quad \delta_{I}:=\mathcal{V}_{R}^{\frac{1}{d}}, \quad n_{I}:=\frac{\pi-2 \theta_{c}}{\delta_{I}} \tag{2.3}
\end{equation*}
$$

3. A continuous model of the partition algorithm. Step 4 of the EQ partition algorithm $[8,3.2]$ is the first rounding step, which produces $n$ from $n_{I}$. We define

$$
\rho:=\frac{n_{I}}{n}
$$

so that

$$
\begin{equation*}
\delta_{F}=\rho \delta_{I} . \tag{3.1}
\end{equation*}
$$

For $N>2$, if $n_{I} \geqslant \frac{1}{2}$ then Step 4 yields

$$
n \in\left(n_{I}-\frac{1}{2}, n_{I}+\frac{1}{2}\right]
$$

and therefore [7, Lemma 3.5.1, p. 87]

$$
\rho \in\left[1-\frac{1}{2 n_{I}+1}, 1+\frac{1}{2 n_{I}-1}\right) .
$$

We see that bounds for $\rho$ are given by lower bounds for $n_{I}$. The crudest such bound is given by $n_{I}>\frac{1}{2}$ which merely implies that $\rho>1 / 2$.

We can re-express the bound $n_{I}>\frac{1}{2}$ in terms of a lower bound on $N$ by means of the function $\nu$, where

$$
\begin{equation*}
\nu(x):=\left(\frac{x}{\Omega}\right)^{\frac{1}{d}}\left(\pi-2 \Theta\left(\frac{\Omega}{x}\right)\right) \tag{3.2}
\end{equation*}
$$

The function $\nu$ defined by (3.2) satisfies $\nu(2)=0, \nu(N)=n_{I}$, and $\nu(x)$ is monotonically increasing in $x$ for $x \geqslant 2$ [7, Lemma 3.5.2, p. 87]. As a consequence, it is possible to define the inverse function $\mathcal{N}_{0}$ where

$$
\begin{equation*}
\mathcal{N}_{0}(y):=\nu^{-1}(y) \tag{3.3}
\end{equation*}
$$

for $y \geqslant 0$. We then have $\mathcal{N}_{0}(\nu(x))=x$ and $\nu\left(\mathcal{N}_{0}(y)\right)=y$ for $x \geqslant 2$ and $y \geqslant 0$, and by the inverse function theorem, $\mathcal{N}_{0}(y)$ is monotonic increasing in $y$ for $y \geqslant 0$.

For $N>x$ such that $x>\mathcal{N}_{0}(1 / 2)$, we then have

$$
\begin{equation*}
n_{I}>\nu(x)>\frac{1}{2} \tag{3.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\rho \in\left[\rho_{L}(x), \rho_{H}(x)\right] \tag{3.5}
\end{equation*}
$$

where

$$
\begin{equation*}
\rho_{L}(x):=1-\frac{1}{2 \nu(x)+1} \quad \text { and } \quad \rho_{H}(x):=1+\frac{1}{2 \nu(x)-1} . \tag{3.6}
\end{equation*}
$$

We can make $\rho_{L}(x)$ and $\rho_{H}(x)$ arbitrarily close to 1 by making $x$ large enough. More precisely,

$$
\begin{equation*}
\rho_{L}(x) \nearrow 1, \text { and } \rho_{H}(x) \searrow 1 \text { as } x \rightarrow \infty . \tag{3.7}
\end{equation*}
$$

Step 6 of the EQ partition algorithm is the second rounding step, which produces $m_{i}$ from $y_{i}$. By examining steps 5 to 7 of the EQ partition algorithm, it is straightforward to verify that for $d>1, N>1$ and $i \in\{1, \ldots, n\}$ the following relationships hold [7, Lemmas 3.5.3, 3.5.4, pp. 88-89]:

$$
\begin{aligned}
a_{i} & \in\left[-\frac{1}{2}, \frac{1}{2}\right], \quad a_{n}=0, \quad \sum_{i=1}^{n} y_{i}=\sum_{i=1}^{n} m_{i}=N-2, \\
m_{i} & =y_{i}+a_{i-1}-a_{i}=\frac{\mathcal{V}\left(\vartheta_{i+1}\right)-\mathcal{V}\left(\vartheta_{i}\right)}{\mathcal{V}_{R}} \in \mathbb{N}_{0}, \\
\mathcal{V}\left(\vartheta_{i}\right) & =\mathcal{V}\left(\vartheta_{F, i}\right)+a_{i-1} \mathcal{V}_{R} .
\end{aligned}
$$

To make it easier to find bounds for functions which vary from zone to zone, such as $y$ and $m$, we define and use continuous analogs of these functions. This way, instead of having to find a bound for a function value over $n+2$ points, where $n$ varies with $N$, we need only find a bound for a function over a fixed number of points and continuous intervals. We therefore define the functions

$$
\begin{align*}
\text { 8) }(\vartheta) & :=\frac{\mathcal{V}\left(\vartheta+\delta_{F}\right)-\mathcal{V}(\vartheta)}{\mathcal{V}_{R}}, & \mathcal{M}(\tau, \beta, \vartheta) & :=\mathcal{Y}(\vartheta)+\tau+\beta,  \tag{3.8}\\
\mathcal{T}(\tau, \vartheta) & :=\Theta\left(\mathcal{V}(\vartheta)-\tau \mathcal{V}_{R}\right), & \mathcal{B}(\beta, \vartheta) & :=\Theta\left(\mathcal{V}\left(\vartheta+\delta_{F}\right)+\beta \mathcal{V}_{R}\right), \\
\Delta(\tau, \beta, \vartheta) & :=\mathcal{B}(\beta, \vartheta)-\mathcal{T}(\tau, \vartheta), & \mathcal{W}(\tau, \beta, \vartheta) & :=\max _{\xi \in[\mathcal{T}(\tau, \vartheta), \mathcal{B}(\beta, \vartheta)]} \sin \xi, \\
\mathcal{P}(\tau, \beta, \vartheta) & :=\mathcal{W}(\tau, \beta, \vartheta) \mathcal{M}(\tau, \beta, \vartheta)^{\frac{1}{1-\alpha},} & &
\end{align*}
$$

so that for $i \in\{1, \ldots, n\}$, we have

$$
\begin{array}{rlrl}
\mathcal{Y}\left(\vartheta_{F, i}\right) & =y_{i}, & \mathcal{M}\left(-a_{i-1}, a_{i}, \vartheta_{F, i}\right) & =m_{i}, \\
\mathcal{T}\left(-a_{i-1}, \vartheta_{F, i}\right) & =\vartheta_{i}, & \mathcal{B}\left(a_{i}, \vartheta_{F, i}\right)=\vartheta_{i+1}, \\
\Delta\left(-a_{i-1}, a_{i}, \vartheta_{F, i}\right) & =\delta_{i}, & \mathcal{W}\left(-a_{i-1}, a_{i}, \vartheta_{F, i}\right)=w_{i}, \\
\mathcal{P}\left(-a_{i-1}, a_{i}, \vartheta_{F, i}\right) & =p_{i} . &
\end{array}
$$

These functions have symmetries which follow from the symmetries of the trigonometric functions. The function $\mathcal{Y}$ satisfies

$$
\mathcal{Y}(\pi-\vartheta)=\mathcal{Y}\left(\vartheta-\delta_{F}\right)
$$

The functions $\mathcal{T}$ and $\mathcal{B}$ satisfy the identities

$$
\begin{aligned}
& \mathcal{T}(\tau, \pi-\vartheta)=\pi-\mathcal{B}\left(\tau, \vartheta-\delta_{F}\right) \quad \text { and } \\
& \mathcal{B}(\beta, \pi-\vartheta)=\pi-\mathcal{T}\left(\beta, \vartheta-\delta_{F}\right)
\end{aligned}
$$

For each $f \in\{\mathcal{M}, \Delta, \mathcal{W}, \mathcal{P}\}$, the function $f$ satisfies

$$
f(\tau, \beta, \pi-\vartheta)=f\left(\beta, \tau, \vartheta-\delta_{F}\right)
$$

For our feasible domain we therefore use the set $\mathbb{D}$, defined as follows.
Definition 3.1. The feasible domain $\mathbb{D}$ is defined as

$$
\mathbb{D}:=\mathbb{D}_{t} \cup \mathbb{D}_{m} \cup \mathbb{D}_{b},
$$

where

$$
\begin{align*}
\mathbb{D}_{t} & :=\left\{(\tau, \beta, \vartheta) \mid \tau=0, \beta \in\left[-\frac{1}{2}, \frac{1}{2}\right], \vartheta=\vartheta_{c}\right\}  \tag{3.9}\\
\mathbb{D}_{m} & :=\left\{(\tau, \beta, \vartheta) \left\lvert\, \tau \in\left[-\frac{1}{2}, \frac{1}{2}\right]\right., \beta \in\left[-\frac{1}{2}, \frac{1}{2}\right], \vartheta \in\left[\vartheta_{F, 2}, \pi-\vartheta_{c}-2 \delta_{F}\right]\right\} \\
\mathbb{D}_{b} & :=\left\{(\tau, \beta, \vartheta) \left\lvert\, \tau \in\left[-\frac{1}{2}, \frac{1}{2}\right]\right., \beta=0, \vartheta=\pi-\vartheta_{c}-\delta_{F}\right\}
\end{align*}
$$

We can now use the feasible domain $\mathbb{D}$ and the analogue functions $\Delta$ and $\mathcal{P}$ to bound the maximum diameter of regions of the EQ partition.

Lemma 3.2. [7, Lemma 3.5.11] Assume that $d>1$ and that $\mathrm{EQ}(d-1)$ has diameter bound $\kappa$. Then for $N>2$, if we define

$$
\operatorname{maxdiam}(d, N):=\max _{R \in \mathrm{EQ}(d, N)} \operatorname{diam} R
$$

then

$$
\operatorname{maxdiam}(d, N) \leqslant \sqrt{\left(\max _{\mathbb{D}} \Delta\right)^{2}+\kappa^{2}\left(\max _{\mathbb{D}} \mathcal{P}\right)^{2}}
$$

We need only consider the northern hemisphere to obtain a valid bound for the diameter of a region of the recursive zonal equal area partition of $\mathbb{S}^{d}$. First define the following subdomains of the feasible domain $\mathbb{D}$,

$$
\begin{align*}
\mathbb{D}_{+} & :=\left\{(\tau, \beta, \vartheta) \in \mathbb{D} \left\lvert\, \vartheta \leqslant \frac{\pi}{2}-\frac{\delta_{F}}{2}\right.\right\}, \\
\mathbb{D}_{-} & :=\left\{(\tau, \beta, \vartheta) \in \mathbb{D} \left\lvert\, \vartheta>\frac{\pi}{2}-\frac{\delta_{F}}{2}\right.\right\}, \\
\mathbb{D}_{m+} & :=\mathbb{D}_{m} \cap \mathbb{D}_{+} . \tag{3.10}
\end{align*}
$$

The following result then holds.
Lemma 3.3. [7, Lemma 3.5.12] For $f \in\{\mathcal{M}, \Delta, \mathcal{W}, \mathcal{P}\}$ and $(\tau, \beta, \vartheta) \in \mathbb{D}_{-}$, we can find $\left(\tau^{\prime}, \beta^{\prime}, \vartheta^{\prime}\right) \in \mathbb{D}_{+}$such that $f\left(\tau^{\prime}, \beta^{\prime}, \vartheta^{\prime}\right)=f(\tau, \beta, \vartheta)$. In particular, if $(\tau, \beta, \vartheta) \in \mathbb{D}_{b}$, then $\left(\tau^{\prime}, \beta^{\prime}, \vartheta^{\prime}\right) \in \mathbb{D}_{t}$, and if $(\tau, \beta, \vartheta) \in \mathbb{D}_{m-}$, then $\left(\tau^{\prime}, \beta^{\prime}, \vartheta^{\prime}\right) \in \mathbb{D}_{m+}$.

Corollary 3.4. For $f \in\{\mathcal{M}, \Delta, \mathcal{W}, \mathcal{P}\}$,

$$
\max _{\mathbb{D}} f=\max _{\mathbb{D}_{+}} f
$$

An analysis of the diameter of the polar caps is not needed for the proof of Theorem 2.5. It is included for completeness, and for comparison to the Feige-Schechtman bound to be examined below. This is a consequence of the isodiametric inequality for $\mathbb{S}^{d}$.

THEOREM 3.5. (Isodiametric inequality for $\mathbb{S}^{d}$ ) Any region $R \subset \mathbb{S}^{d}$ of spherical diameter $\delta<\pi$ has area bounded by

$$
\sigma(R) \leqslant \mathcal{V}\left(\frac{\delta}{2}\right)
$$

## Equality holds only for spherical caps of spherical radius $\frac{\delta}{2}$.

This result is well known; see [2] for a proof of a generalized version of this inequality, based on the proof of [1].

We have the following upper bound for the diameter of a polar cap of $\mathrm{EQ}(d, N)$.
LEMmA 3.6. For $d>1$ and $N \geqslant 2$, the diameter of each polar cap of $\operatorname{EQ}(d, N)$ is bounded above by $K_{c} N^{-\frac{1}{d}}$, where

$$
K_{c}:=2\left(\frac{\Omega d}{\omega}\right)^{\frac{1}{d}}
$$

The following two bounds are used in the proof of Theorem 2.5.
Lemma 3.7. For $d>1$, there is a positive constant $N_{\Delta} \in \mathbb{N}$ and a monotonic decreasing positive real function $K_{\Delta}$ such that for each partition $\mathrm{EQ}(d, N)$ with
$N>x \geqslant N_{\Delta}$,

$$
\max _{\mathbb{D}} \Delta \leqslant K_{\Delta}(x) N^{-\frac{1}{d}}
$$

Lemma 3.8. For $d>1$, there is a positive constant $N_{P} \in \mathbb{N}$ and a monotonic decreasing positive real function $C_{P}$ such that for each partition $\mathrm{EQ}(d, N)$ with $N>x \geqslant N_{P}$,

$$
\max _{\mathbb{D}} \mathcal{P} \leqslant C_{P}(x) N^{-\frac{1}{d}}
$$

## 4. Proofs of main theorems.

Proof of Theorem 2.5. The theorem is true for $d=1$, with EQ(1) having diameter bound $K_{1}=2 \pi$, since the recursive zonal equal area partition algorithm partitions the circle $\mathbb{S}^{1}$ into $N$ equal segments, each of arc length $2 \pi / N$, and therefore each segment has diameter less than $2 \pi / N$.

Now assume that $d>1$ and $N>2$. We know from Lemma 3.2 that

$$
\operatorname{maxdiam}(d, N) \leqslant \sqrt{\left(\max _{\mathbb{D}} \Delta\right)^{2}+\kappa^{2}\left(\max _{\mathbb{D}} \mathcal{P}\right)^{2}}
$$

From Lemma 3.7, we know that there is a positive constant $N_{\Delta} \in \mathbb{N}$ and a monotonic decreasing positive real function $K_{\Delta}$ such that for each partition $\mathrm{EQ}(d, N)$ with $N>x \geqslant N_{\Delta}$,

$$
\max _{\mathbb{D}} \Delta \leqslant K_{\Delta}(x) N^{-\frac{1}{d}}
$$

From Lemma 3.8, we know that there is a positive constant $N_{P} \in \mathbb{N}$ and a monotonic decreasing positive real function $C_{P}$ such that for each partition EQ $(d, N)$ with $N>x \geqslant N_{P}$,

$$
\max _{\mathbb{D}} \mathcal{P} \leqslant C_{P}(x) N^{-\frac{1}{d}}
$$

Define

$$
N_{H}:=\max \left(N_{\Delta}, N_{P}\right)
$$

Assuming that $\mathrm{EQ}(d-1)$ is diameter bounded, with diameter bound $\kappa$, then for $N>N_{H}$, we have maxdiam $(d, N) \leqslant K_{H} N^{-\frac{1}{d}}$, where

$$
K_{H}:=\sqrt{K_{\Delta}\left(N_{H}\right)^{2}+\kappa^{2} C_{P}\left(N_{H}\right)^{2}}
$$

For $d>1$ and $N \leqslant N_{H}$, we note that the diameter of $\mathbb{S}^{d}$ is 2 , and so the diameter of any region is bounded by 2 . Therefore for $N \leqslant N_{H}$, maxdiam $(d, N) \leqslant K_{L} N^{-\frac{1}{d}}$, where

$$
K_{L}:=2 N_{H}^{\frac{1}{d}}
$$

Finally, we see by induction that for $d>1, \operatorname{maxdiam}(d, N) \leqslant K_{d} N^{-\frac{1}{d}}$, where

$$
K_{d}:=\max \left(K_{L}, K_{H}\right)
$$

5. Estimates for caps. Later we will need to compare $\sin \theta$ with $\sin (\theta+\phi)$, for various $\theta$ and $\phi$. The following estimate is useful for this task. For all $\theta, \phi \in \mathbb{R}$, we have

$$
\sin (\theta+\phi)-\sin \theta=2 \sin \frac{\phi}{2} \cos \left(\theta+\frac{\phi}{2}\right)
$$

Therefore for $\phi \in(0, \pi], \theta \in(0, \pi / 2-\phi / 2]$, we have $\sin (\theta+\phi)>\sin \theta>0$.
In the estimate below, we assume that $\theta \in(0, \xi], \xi \in(0, \pi / 2]$, and use the well-known sine ratio function

$$
\operatorname{sinc} \theta:=\frac{\sin \theta}{\theta}
$$

We have the well-known estimate

$$
\begin{equation*}
\sin \theta \in[\operatorname{sinc} \xi, 1] \theta \tag{5.1}
\end{equation*}
$$

In the estimates below we assume that $\theta \in(0, \xi], \xi \in(0, \pi / 2]$. From (2.2) we have $D \mathcal{V}(\theta)=\omega \sin ^{d-1} \theta$. Using the estimate (5.1) therefore gives us

$$
D \mathcal{V}(\theta) \in\left[(\operatorname{sinc} \xi)^{d-1}, 1\right] \omega \theta^{d-1}
$$

Thus,

$$
\begin{equation*}
\mathcal{V}(\theta) \in\left[(\operatorname{sinc} \xi)^{d-1}, 1\right] \frac{\omega}{d} \theta^{d} \tag{5.2}
\end{equation*}
$$

If we then substitute $\Theta(v)$ for $\theta$, we obtain for $v \in[0, \mathcal{V}(\xi)]$ that

$$
\begin{equation*}
\Theta(v) \in\left[1,(\operatorname{sinc} \xi)^{\frac{1-d}{d}}\right]\left(\frac{d}{\omega}\right)^{\frac{1}{d}} v^{\frac{1}{d}} \tag{5.3}
\end{equation*}
$$

The estimates (5.2) and (5.3) are crude. There are instances where we need a sharper upper bound than that given by (5.2). The estimate below is more accurate for large $d$ for $\theta$ away from $\pi / 2$.

Lemma 5.1. [7, Lemma 2.3.18] For $d \geqslant 2$ and $\theta \in[0, \pi / 2)$ we have

$$
\begin{equation*}
\mathcal{V}(\theta) \leqslant \frac{\omega}{d} \frac{\sin ^{d} \theta}{\cos \theta} \tag{5.4}
\end{equation*}
$$

with equality only when $\theta=0$.
If we combine (5.2) with (5.4), we obtain the following result.
Corollary 5.2. For $d \geqslant 2$ and $\theta \in[0, \pi / 2)$ we have

$$
\begin{equation*}
\mathcal{V}(\theta) \in\left[\frac{1}{\operatorname{sinc} \theta}, \frac{1}{\cos \theta}\right] \frac{\omega}{d} \sin ^{d} \theta \tag{5.5}
\end{equation*}
$$

Recall from (2.3) that $\vartheta_{c}=\Theta\left(\frac{\Omega}{N}\right)$ and define

$$
\begin{equation*}
J_{c}(x):=\operatorname{sinc} \Theta\left(\frac{\Omega}{x}\right) \tag{5.6}
\end{equation*}
$$

As a result of (5.3), for $N \geqslant x \geqslant 2$, we have

$$
\begin{equation*}
\vartheta_{c} \in\left[1, J_{c}(x)^{\frac{1-d}{d}}\right]\left(\frac{d}{\omega}\right)^{\frac{1}{d}} \delta_{I} \tag{5.7}
\end{equation*}
$$

Using Lemma 5.1, we obtain the following upper bound for $\sin \vartheta_{c}$.
Lemma 5.3. [7, Lemma 3.5.14] For $x \geqslant 2$,

$$
\begin{equation*}
x^{\frac{1}{d}} \sin \Theta\left(\frac{\Omega}{x}\right) \leqslant\left(\frac{\Omega d}{\omega}\right)^{\frac{1}{d}} \tag{5.8}
\end{equation*}
$$

Therefore, for $N \geqslant 2$,

$$
\begin{equation*}
\sin \vartheta_{c} \leqslant\left(\frac{d}{\omega}\right)^{\frac{1}{d}} \delta_{I} \tag{5.9}
\end{equation*}
$$

Combining (5.6), (5.7), and (5.9), we have the estimate

$$
\begin{equation*}
\sin \vartheta_{c} \in\left[J_{c}(x), 1\right]\left(\frac{d}{\omega}\right)^{\frac{1}{d}} \delta_{I} \tag{5.10}
\end{equation*}
$$

for $N \geqslant x \geqslant 2$.
6. The modified Feige and Schechtman construction. Feige and Schechtman [5] give a constructive proof of the following lemma, which can be used to prove Stolarsky's assertion.

Lemma 6.1. [5, Lemma 21, pp. 430-431] For each $0<\gamma<\pi / 2$ the sphere $\mathbb{S}^{d-1}$ can be partitioned into $N=(O(1) / \gamma)^{d}$ regions of equal area, each of diameter at most $\gamma$.

Lemma 6.1 corresponds to a diameter bound of order $\mathrm{O}\left(N^{\frac{1}{d+1}}\right)$ rather than $\mathrm{O}\left(N^{\frac{1}{d}}\right)$, but the construction given in the proof [5, pp. 430-431] is easily modified to yield the following upper bound on the smallest maximum diameter of an equal area partition of $\mathbb{S}^{d}$.

LEMMA 6.2. For $d>1, N>2$, there is a partition $F S(d, N)$ of the unit sphere $\mathbb{S}^{d}$ into $N$ regions, with each region $R \in F S(d, N)$ having area $\Omega / N$ and Euclidean diameter bounded above by

$$
\operatorname{diam} R \leqslant \Upsilon\left(\min \left(\pi, 8 \vartheta_{c}\right)\right)
$$

with $\Upsilon$ defined by (2.1) and $\vartheta_{c}$ defined by (2.3).
We now use the modified Feige-Schechtman construction to prove Stolarsky's assertion, Theorem 2.6.

Proof of Theorem 2.6. For $d=1$, we partition the circle into equal segments and the proof is as per the proof of Theorem 2.5. For $d>1$ and $N=1$, there is one region of diameter $2=2 N^{-\frac{1}{d}}$. For $d>1$ and $N=2$, there are two regions, each of diameter $2=2^{\frac{d+1}{d}} N^{-\frac{1}{d}}$. Otherwise, we use Lemma 6.2 and the estimates (5.7) and (5.9). Define

$$
N_{F S}=\frac{\Omega}{\mathcal{V}\left(\frac{\pi}{8}\right)}
$$

Then for $N \geqslant N_{F S}$,

$$
\vartheta_{c}=\Theta\left(\frac{\Omega}{N}\right) \leqslant \frac{\pi}{8}
$$

with equality only when $N=N_{F S}$. Therefore, for $N \geqslant N_{F S}$, Lemmas 5.3 and 6.2 give us

$$
\max _{R \in F S(d, N)} \operatorname{diam} R \leqslant 2 \sin 4 \vartheta_{c}<8 \sin \vartheta_{c}<K_{F S} N^{-\frac{1}{d}}
$$

where

$$
K_{F S}:=8\left(\frac{\Omega d}{\omega}\right)^{\frac{1}{d}}
$$

For $2<N<N_{F S}$, we have

$$
\operatorname{maxdiam} F S(d, N) \leqslant 2=2 N^{\frac{1}{d}} N^{-\frac{1}{d}}<2 N_{F S}^{\frac{1}{d}} N^{-\frac{1}{d}}
$$

Let $K_{F S L}:=2 N_{F S}^{\frac{1}{d}}$. Using (5.5), we have

$$
\mathcal{V}\left(\frac{\pi}{8}\right) \geqslant \frac{1}{\operatorname{sinc} \frac{\pi}{8}} \frac{\omega}{d} \sin ^{d} \frac{\pi}{8}>\frac{\omega}{d} \sin ^{d} \frac{\pi}{8}
$$

We also have $\sin \frac{\pi}{8}>\frac{1}{4}$, so that

$$
\mathcal{V}\left(\frac{\pi}{8}\right)>\frac{\omega}{4^{d} d}
$$

Therefore

$$
N_{F S}=\frac{\Omega}{\mathcal{V}\left(\frac{\pi}{8}\right)}<4^{d} \frac{\Omega d}{\omega}
$$

In other words,

$$
K_{F S L}^{d}=2^{d} N_{F S}<8^{d} \frac{\Omega d}{\omega}=K_{F S}^{d}
$$

We therefore have $K_{F S L}<K_{F S}$. For $d \geqslant 2$ we have [7, Lemma 2.3.20]

$$
\begin{equation*}
\frac{\Omega}{\omega}>\sqrt{\frac{2 \pi}{d}} \tag{6.1}
\end{equation*}
$$

For the case $N=2$, from (6.1) we obtain

$$
2^{d+1}<8^{d} \sqrt{2 \pi d}<8^{d} \frac{\Omega d}{\omega}=K_{F S}^{d} .
$$

Therefore Theorem 2.6 is satisfied by $c_{d}=K_{F S}$.
REMARK 6.3. The Feige-Schechtman constant $K_{F S}$ thus provides an upper bound for the minimum constant for the diameter bound of an equal area partition of $\mathbb{S}^{d}$. Theorems 2.4 and 2.5 yield an alternate proof of Theorem 2.6 , with $c_{d}=K_{d}$.

Appendix A. Proofs of Lemmas. The definitions of the functions $\Delta$ and $\mathcal{P}$ and the definition of the feasible domain $\mathbb{D}$ depend on the fitting collar angle $\delta_{F}$. Thus the proofs of Lemmas 3.7 and 3.8 need an estimate for $\delta_{F}$. Recall from (3.1) that $\delta_{F}=\rho \delta_{I}$. Therefore, from (3.5), for $N>x>\mathcal{N}_{0}(1 / 2)$, where $\mathcal{N}_{0}$ is defined by (3.3), we have

$$
\begin{equation*}
\delta_{F} \in\left[\rho_{L}(x), \rho_{H}(x)\right] \delta_{I} \tag{A.1}
\end{equation*}
$$

We also need estimates for $\vartheta_{F, i}$, as defined by Step 5 of the EQ partition algorithm [8, Section 3.2], and for $\sin \vartheta_{F, i}$ and $\mathcal{V}\left(\vartheta_{F, i}\right)$. Here and below, we generalize the definition of $\vartheta_{F, i}$, by defining

$$
\vartheta_{F, \iota}:=\vartheta_{c}+(\iota-1) \delta_{F},
$$

for $\iota \in[1, n+1]$. For $N>x>\mathcal{N}_{0}(1 / 2)$, where $\mathcal{N}_{0}$ is defined by (3.3), the estimates (5.7) and (A.1) now yield

$$
\begin{equation*}
\vartheta_{F, \iota} \in\left[\left(\frac{d}{\omega}\right)^{\frac{1}{d}}+(\iota-1) \rho_{L}(x),\left(\frac{d}{\omega}\right)^{\frac{1}{d}} J_{c}(x)^{\frac{1-d}{d}}+(\iota-1) \rho_{H}(x)\right] \delta_{I} \tag{A.2}
\end{equation*}
$$

The estimates for $\sin \vartheta_{F, \iota}$ and $\mathcal{V}\left(\vartheta_{F, \iota}\right)$ below assume that $N>x>\mathcal{N}_{0}(1 / 2)$, where $\mathcal{N}_{0}$ is defined by (3.3), and the lower bounds for these estimates also assume that

$$
\begin{equation*}
\Theta\left(\frac{\Omega}{x}\right)+(\iota-1) \rho_{H}(x)\left(\frac{\Omega}{x}\right)^{\frac{1}{d}} \leqslant \frac{\pi}{2} \tag{A.3}
\end{equation*}
$$

If we define

$$
J_{F, \iota}(x):=\operatorname{sinc}\left(\Theta\left(\frac{\Omega}{x}\right)+(\iota-1) \rho_{H}(x)\left(\frac{\Omega}{x}\right)^{\frac{1}{d}}\right)
$$

then from (5.1) and (A.2) we have the estimate

$$
\sin \vartheta_{F, \iota} \in\left[J_{F, \iota}(x)\left(\left(\frac{d}{\omega}\right)^{\frac{1}{d}}+(\iota-1) \rho_{L}(x)\right),\left(\frac{d}{\omega}\right)^{\frac{1}{d}} J_{c}(x)^{\frac{1-d}{d}}+(\iota-1) \rho_{H}(x)\right] \delta_{I}
$$

and from (5.2) we have the estimate

$$
\mathcal{V}\left(\vartheta_{F, \iota}\right) \in\left[s_{L, \iota}(x), s_{H, \iota}(x)\right] \mathcal{V}_{R}
$$

where

$$
\begin{aligned}
& s_{L, \iota}(x):=J_{F, \iota}(x)^{d-1}\left(1+(\iota-1) \rho_{L}(x)\left(\frac{\omega}{d}\right)^{\frac{1}{d}}\right)^{d} \\
& s_{H, \iota}(x):=\left(J_{c}(x)^{\frac{1-d}{d}}+(\iota-1) \rho_{H}(x)\left(\frac{\omega}{d}\right)^{\frac{1}{d}}\right)^{d}
\end{aligned}
$$

If we define

$$
s_{\iota}:=\left(1+(\iota-1)\left(\frac{\omega}{d}\right)^{\frac{1}{d}}\right)^{d}
$$

then, since $J_{F, \iota}(x) \nearrow 1, J_{c}(x) \nearrow 1, \rho_{L}(x) \nearrow 1$ and $\rho_{H}(x) \searrow 1$, as $x \rightarrow \infty$ we see that

$$
s_{L, \iota}(x) \nearrow s_{\iota} \text { and } s_{H, \iota}(x) \searrow s_{\iota} \text { as } x \rightarrow \infty
$$

By making $x$ large enough and $\iota$ small enough, we can ensure that (A.3) holds.
Lemma A.1. [7, Lemma 3.5.16] If $x \geqslant \mathcal{N}_{0}(5)$, where $\mathcal{N}_{0}$ is defined by (3.3), then (A.3) holds for

$$
\iota \in\left[1, \frac{13}{4}\right]
$$

For the remainder of this paper we use the abbreviation

$$
\eta:=\frac{1}{\sqrt{8 \pi d}}
$$

The proofs of Lemmas 3.7 and 3.8 require the following results, which are proved in [7, Chapter 3].

Lemma A.2. [7, Lemma 3.5.17] There is an $x \geqslant \mathcal{N}_{0}(5)$, such that

$$
\begin{equation*}
J_{F,(1+\eta)}(x)^{d-1}\left(1+\eta \rho_{L}(x)\left(\frac{\omega}{d}\right)^{\frac{1}{d}}\right)^{d}>\frac{3}{2} \tag{A.4}
\end{equation*}
$$

Lemma A.3. [7, Lemma 3.5.19] If $x \geqslant \mathcal{N}_{0}(5)$, and $x$ satisfies (A.4), then for $N>x$ we have

$$
\begin{equation*}
\mathcal{V}\left(\vartheta_{c}+\eta \delta_{F}\right)>\frac{3}{2} \mathcal{V}_{R} \tag{A.5}
\end{equation*}
$$

As a result of (A.5), we have

$$
\mathcal{V}\left(\vartheta_{c}+\eta \delta_{F}\right)-\mathcal{V}\left(\vartheta_{c}\right)>\frac{\mathcal{V}_{R}}{2}
$$

From (2.2) and the symmetries of the sine function, for $\vartheta \in\left(0, \pi / 2-\eta \delta_{F} / 2\right]$, we have

$$
\begin{equation*}
\frac{\partial}{\partial \vartheta}\left(\mathcal{V}\left(\vartheta+\eta \delta_{F}\right)-\mathcal{V}(\vartheta)\right)=D \mathcal{V}\left(\vartheta+\eta \delta_{F}\right)-D \mathcal{V}(\vartheta) \tag{A.6}
\end{equation*}
$$

with equality only when $\vartheta=\frac{\pi}{2}-\eta \frac{\delta_{F}}{2}$. This results in the following corollary.
COROLLARY A.4. [7, Corollary 3.5.20] If $x \geqslant \mathcal{N}_{0}(5)$, and $x$ satisfies (A.4), then for $N>x$ and $\vartheta \in\left[\vartheta_{c}, \pi-\vartheta_{c}-\eta \delta_{F}\right]$ we have

$$
\begin{equation*}
\mathcal{V}\left(\vartheta+\eta \delta_{F}\right)-\mathcal{V}(\vartheta)>\frac{\mathcal{V}_{R}}{2} \tag{A.7}
\end{equation*}
$$

If $x \geqslant \mathcal{N}_{0}(5)$, and $N>x$ then $n \geqslant 5$, so $\vartheta_{F, 2}<\frac{\pi}{2}$. Since $8 \pi d \geqslant 16 \pi>49$, we therefore have

$$
\begin{equation*}
\eta \delta_{F}<\frac{\delta_{F}}{7} \tag{A.8}
\end{equation*}
$$

Proof of Lemma 3.6. Assume that $d>1$ and $N>1$. From (2.3) we know that the diameter of each of the polar caps of the partition $\mathrm{EQ}(d, N)$ is $2 \sin \vartheta_{c}$. From (5.9) we have the estimate

$$
2 \sin \vartheta_{c} \leqslant 2\left(\frac{\Omega d}{\omega}\right)^{\frac{1}{d}} N^{-\frac{1}{d}}
$$

for $N \geqslant x \geqslant 2$. $\square$
Proof of Lemma 3.7. Throughout this proof, we assume that $N>x$ where $x \geqslant \mathcal{N}_{0}(5)$, with $\mathcal{N}_{0}$ defined by (3.3), so that $n \geqslant 5$. Using Corollary 3.4, we also assume that $(\tau, \beta, \vartheta) \in \mathbb{D}_{+}$. For the top collar, $(\tau, \beta, \vartheta) \in \mathbb{D}_{t}$, (3.9) gives $\tau=0, \beta \in\left[-\frac{1}{2}, \frac{1}{2}\right], \vartheta=\vartheta_{c}$. From (2.2) we have

$$
\mathcal{V}\left(\mathcal{B}\left(\beta, \vartheta_{c}\right)\right)=\mathcal{V}\left(\vartheta_{c}+\delta_{F}\right)+\beta \mathcal{V}_{R} \leqslant \mathcal{V}\left(\vartheta_{c}+\delta_{F}\right)+\frac{\mathcal{V}_{R}}{2}
$$

Since $n \geqslant 5$, we have $\vartheta_{c}+\delta_{F} \in\left[\vartheta_{c}, \pi-\vartheta_{c}-\eta \delta_{F}\right]$, and we can use (A.7) to obtain

$$
\mathcal{V}\left(\mathcal{B}\left(\beta, \vartheta_{c}\right)\right) \leqslant \mathcal{V}\left(\vartheta_{c}+\delta_{F}\right)+\frac{\mathcal{V}_{R}}{2}<\mathcal{V}\left(\vartheta_{c}+(1+\eta) \delta_{F}\right)
$$

and therefore

$$
\mathcal{B}\left(\beta, \vartheta_{c}\right)<\vartheta_{c}+(1+\eta) \delta_{F} .
$$

Therefore (3.8) yields

$$
\Delta(\tau, \beta, \vartheta)=\Delta\left(0, \beta, \vartheta_{c}\right)=\mathcal{B}\left(\beta, \vartheta_{c}\right)-\mathcal{T}\left(0, \vartheta_{c}\right)=\mathcal{B}\left(\beta, \vartheta_{c}\right)-\vartheta_{c}<(1+\eta) \delta_{F}
$$

For $(\tau, \beta, \vartheta) \in \mathbb{D}_{m+}(3.10)$ gives $\tau \in\left[-\frac{1}{2}, \frac{1}{2}\right], \beta \in\left[-\frac{1}{2}, \frac{1}{2}\right], \vartheta \in\left[\vartheta_{F, 2}, \frac{\pi}{2}-\frac{\delta_{F}}{2}\right]$. Since $n \geqslant 5$, we have $\vartheta+\delta_{F} \in\left[\vartheta_{c}, \pi-\vartheta_{c}-\eta \delta_{F}\right]$, since

$$
\vartheta_{c}+\frac{3}{2} \delta_{F}<\vartheta_{c}+2 \delta_{F}<\frac{\pi}{2}
$$

yielding

$$
\vartheta+\delta_{F} \leqslant \frac{\pi}{2}+\frac{\delta_{F}}{2}<\pi-\vartheta_{c}-\delta_{F} .
$$

From (2.2), (3.8), and (A.7), we now have

$$
\mathcal{V}(\mathcal{B}(\beta, \vartheta))=\mathcal{V}\left(\vartheta+\delta_{F}\right)+\beta \mathcal{V}_{R} \leqslant \mathcal{V}\left(\vartheta+\delta_{F}\right)+\frac{\mathcal{V}_{R}}{2}<\mathcal{V}\left(\vartheta+(1+\eta) \delta_{F}\right)
$$

We therefore have

$$
\begin{equation*}
\mathcal{B}(\beta, \vartheta)<\vartheta+(1+\eta) \delta_{F} \tag{A.9}
\end{equation*}
$$

Since $\vartheta-\eta \delta_{F}>\vartheta_{c}$, using (2.2), (3.8), and (A.7), we also have

$$
\mathcal{V}(\mathcal{T}(\tau, \vartheta))=\mathcal{V}(\vartheta)+\tau \mathcal{V}_{R} \geqslant \mathcal{V}(\vartheta)-\frac{\mathcal{V}_{R}}{2}>\mathcal{V}\left(\vartheta-\eta \delta_{F}\right)
$$

so that

$$
\begin{equation*}
\vartheta-\eta \delta_{F}<\mathcal{T}(\tau, \vartheta) \tag{A.10}
\end{equation*}
$$

Combining (A.9) and (A.10) and using (3.8), we therefore have

$$
\Delta(\tau, \beta, \vartheta)=\mathcal{B}(\beta, \vartheta)-\mathcal{T}(\tau, \vartheta)<(1+2 \eta) \delta_{F}
$$

The estimate (A.1) now yields

$$
\Delta(\tau, \beta, \vartheta)<K_{\Delta}(x) N^{-\frac{1}{d}}
$$

where

$$
K_{\Delta}(x):=(1+2 \eta) \rho_{H}(x) \Omega^{\frac{1}{d}}
$$

with $\rho_{H}(x)$ defined by (3.6). We also have

$$
K_{\Delta}(x) \searrow K_{\Delta}(\infty):=(1+2 \eta) \Omega^{\frac{1}{d}} \text { as } x \rightarrow \infty
$$

since $\rho_{H}(x) \searrow 1$ as $x \rightarrow \infty, b y(3.7)$.
Proof of Lemma 3.8. Throughout this proof, we assume that $N>x$ where $x \geqslant \mathcal{N}_{0}(5)$, with $\mathcal{N}_{0}$ defined by (3.3), so that $n \geqslant 5$. Using Corollary 3.4, we also assume that $(\tau, \beta, \vartheta) \in \mathbb{D}_{+}$. We will show that

$$
\begin{aligned}
& \mathcal{W}(\tau, \beta, \vartheta) \leqslant C_{1}(x) \sin \vartheta \\
& \mathcal{M}(\tau, \beta, \vartheta) \geqslant C_{2}(x) \sin ^{d-1} N^{\frac{d-1}{d}}
\end{aligned}
$$

with $C_{1}$ monotonic non-increasing and $C_{2}$ monotonic non-decreasing. We first examine $\mathcal{W}$. Using (A.9) for $\vartheta \leqslant \pi / 2-(1+\eta) \delta_{F}$, we have

$$
\mathcal{W}(\tau, \beta, \vartheta) \leqslant \sin \left(\vartheta+(1+\eta) \delta_{F}\right)<\sin \vartheta+(1+\eta) \delta_{F} .
$$

For $\vartheta \in\left[\pi / 2(1+\eta) \delta_{F}, \pi / 2-\delta_{F} / 2\right]$, we have

$$
\sin \vartheta+(1+\eta) \delta_{F} \geqslant \frac{2}{\pi}\left(\frac{\pi}{2}-(1+\eta) \delta_{F}\right)+(1+\eta) \delta_{F} \geqslant 1
$$

Hence, $\mathcal{W}(\tau, \beta, \vartheta)<\sin \vartheta+(1+\eta) \delta_{F}$. Since $\vartheta \in\left[\vartheta_{c}, \pi-\vartheta_{c}\right]$ we have $\sin \vartheta \geqslant \sin \vartheta_{c}$ and therefore

$$
\mathcal{W}(\tau, \beta, \vartheta)<\left(1+(1+\eta) \frac{\delta_{F}}{\sin \vartheta_{c}}\right) \sin \vartheta
$$

From (A.1) we have $\delta_{F} \leqslant \rho_{H}(x) \Omega^{\frac{1}{d}} N^{\frac{-1}{d}}$. From (5.10) we have

$$
\sin \vartheta_{c} \geqslant J_{c}(x)\left(\frac{\Omega d}{\omega}\right)^{\frac{1}{d}} N^{\frac{-1}{d}}
$$

so that $\mathcal{W}(\tau, \beta, \vartheta) \leqslant C_{1}(x) \sin \vartheta$, with

$$
C_{1}(x):=1+(1+\eta) \frac{\rho_{H}(x)}{J_{c}(x)}\left(\frac{\omega}{d}\right)^{\frac{1}{d}}
$$

with $\frac{\rho_{H}(x)}{J_{c}(x)} \searrow 1$ as $x \rightarrow \infty$, since $J_{c}(x) \nearrow 1$ and $\rho_{H}(x) \searrow 1$ as $x \rightarrow \infty$. Thus $C_{1}(x)$ is monotonic nonincreasing as $x \rightarrow \infty$. Now for $\mathcal{M}$. From (3.8) we have

$$
\mathcal{M}(\tau, \beta, \vartheta) \geqslant \frac{\mathcal{V}\left(\vartheta+\delta_{F}\right)-\mathcal{V}(\vartheta)}{\mathcal{V}_{R}}-1
$$

But

$$
\frac{\mathcal{V}\left(\vartheta+\delta_{F}\right)-\mathcal{V}(\vartheta)}{\mathcal{V}_{R}}=\omega \int_{\vartheta}^{\vartheta+\delta_{F}} \sin ^{d-1} \xi d \xi \geqslant \omega \delta_{F} \sin ^{d-1} \vartheta
$$

for $\vartheta \in\left[0, \pi / 2-\delta_{F} / 2\right]$. Therefore,

$$
\begin{aligned}
\mathcal{M}(\tau, \beta, \vartheta) & \geqslant \omega \sin ^{d-1} \vartheta \frac{\delta_{F}}{\mathcal{V}_{R}}-1 \\
& \geqslant\left(\rho \omega \Omega^{\frac{1-d}{d}}-\frac{1}{\sin ^{d-1} \vartheta_{c} N^{\frac{d-1}{d}}}\right) \sin ^{d-1} \vartheta N^{\frac{d-1}{d}}
\end{aligned}
$$

since $\vartheta \geqslant \vartheta_{c}$. Using (3.5) and (5.10) we therefore have

$$
\mathcal{M}(\tau, \beta, \vartheta) \geqslant C_{2}(x) \sin ^{d-1} \vartheta N^{\frac{d-1}{d}},
$$

where

$$
C_{2}(x):=\rho \omega \Omega^{\frac{1-d}{d}}-J_{c}(x)^{1-d}\left(\frac{\omega}{\Omega d}\right)^{\frac{d-1}{d}}
$$

If $J_{c}(x)^{d-1} \rho_{L}(x) \omega^{\frac{1}{d}} d^{\frac{d-1}{d}}>1$ then we have $C_{2}(x)>0$. This is true for $x$ sufficiently large since $\omega d^{d-1}>1$ and since both $J_{c}(x) \nearrow 1$ and $\rho_{L}(x) \nearrow 1$ as $x \rightarrow \infty$. We also see that $C_{2}$ is monotonically nondecreasing.

Proof of Lemma 6.2. This proof uses a modified version of the construction given the proof of [5, Lemma 21] in [5, p. 430-431].

1. Given $d>1, N>2$, use (2.3) to determine $\vartheta_{c}$. Then we have $\mathcal{V}\left(\vartheta_{c}\right)=\mathcal{V}_{R}=\Omega / N$, with $\mathcal{V}_{R}$ being the area we need for each region of the partition.
2. A saturated packing of packing radius $\rho$ is a packing of spherical caps of packing radius $\rho$ such that another cap cannot be added without moving the existing caps. Create a saturated packing of $\mathbb{S}^{d}$ by caps of spherical radius $\vartheta_{c}$, constructed via a greedy algorithm so that each cap kisses at least one other cap. Let $m$ be the number of caps in the packing. We see that no point of $\mathbb{S}^{d}$ is more than $2 \vartheta_{c}$ from the centre of a cap, otherwise we could have added another cap. Therefore the $m$ centre points of the packing are also the centres of a covering of $\mathbb{S}^{d}$ by spherical caps of spherical radius $2 \vartheta_{c}$ [13, p. 1091] [14, Lemma 1, p. 2112].
3. Now partition $\mathbb{S}^{d}$ into Voronoi cells $V_{i}, i \in\{1, \ldots, m\}$ based on these $m$ centre points. The Voronoi cell $V_{i}$ corresponding to centre point $i$ consists of those points of $\mathbb{S}^{d}$ which are at least as close to the centre point $i$ as they are to of any of the other centre points. We see that the Voronoi cells must contain the packing caps and be contained in the covering caps. Thus each $V_{i}$ has area at least $\mathcal{V}_{R}$ and spherical diameter at most $\min \left(\pi, 2 \vartheta_{c}\right)$.
4. Now create a graph $\Gamma$ with a node for each centre point and an edge for each pair of kissing packing caps.
5. Take any spanning tree $S$ of $\Gamma$ (also known as a maximal tree [10, Section 6.2 pp. 101-103]). The tree $S$ has leaves, which are nodes having only one edge, and either a single centre node, or a bicentre, which is a pair of nodes joined by an edge. The centre or bicentre nodes are the nodes for which the shortest path to any leaf has the maximum number of edges [3] [4, Volume 9, p. 430] [11, Chapter 6, Section 9, p. 135]. If there is a single centre, mark it as the root node. If there is a bicentre, arbitrarily mark one of the two nodes as the root node. Now create the directed tree $T$ from $S$ by directing the edges from the leaves towards the root [11, Chapter 6, Section 7, p. 129].
6. For each leaf $j$, of $T$ define $n_{j}:=\left\lfloor\sigma\left(V_{j}\right) / \mathcal{V}_{R}\right\rfloor$, (with $\lfloor x\rfloor$ denoting the least integer function of $x$ ).
7. Partition $V_{j}$ into the super-region $U_{j}$ with $\sigma\left(U_{j}\right)=n_{j} \mathcal{V}_{R}$ and the remainder $W_{j}:=V_{j} \backslash U_{j}$.
8. For each nonleaf node $k$ other than the root, define $X_{k}=V_{k} \cup \bigcup_{(j, k) \in T} W_{j}$, that is, we add all the remainders of the daughters of $k$ to $V_{k}$ to obtain $X_{k}$.
9. Now define $n_{k}:=\left\lfloor\sigma\left(X_{k}\right) / \mathcal{V}_{R}\right\rfloor$ and partition $X_{k}$ into the super-region $U_{k}$ with $\sigma\left(U_{k}\right)=n_{k} \mathcal{V}_{R}$ and the remainder $W_{k}:=X_{k} \backslash U_{k}$.
10. Continue until only the root node is left.
11. For the root node $\ell$, if we define $U_{\ell}:=V_{\ell} \cup \bigcup_{(k, \ell) \in T} W_{k}$, we see that we must have $\sigma\left(U_{\ell}\right)=n_{\ell} \mathcal{V}_{R}$, where

$$
n_{\ell}:=N-\sum_{i \neq \ell} n_{i}
$$

that is, the area of the super-region corresponding to the root node must be an integer multiple of $\mathcal{V}_{R}$. Since at each step we have assembled $U_{i}$ only from the Voronoi cells corresponding to kissing packing caps, each $U_{i}$ is contained in a spherical cap with centre the same as the centre of the corresponding packing cap, and spherical radius $\min \left(\pi, 4 \vartheta_{c}\right)$, and so the spherical diameter of each $U_{i}$ is at $\operatorname{most} \min \left(\pi, 8 \vartheta_{c}\right)$.
12. Now partition each $U_{i}$ into $n_{i}$ regions of area $\mathcal{V}_{R}$, and let $F S(d, N)$ be the resulting partition of $\mathbb{S}^{d}$. Then $F S(d, N)$ is a partition of $\mathbb{S}^{d}$ into $N$ regions, with each region $R \in F S(d, N)$ having area $\Omega / N$ and Euclidean diameter bounded above by

$$
\operatorname{diam} R \leqslant \Upsilon\left(\min \left(\pi, 8 \vartheta_{c}\right)\right)=2 \sin \left(\min \left(\frac{\pi}{2}, 4 \vartheta_{c}\right)\right)
$$

REMARK A.5. Feige and Schechtman's proof uses a maximal packing instead of a saturated packing, but maximality is harder to achieve and the proof of Lemma 6.2 only needs a saturated packing.

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