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## DETERMINANT PRESERVING TRANSFORMATIONS ON SYMMETRIC MATRIX SPACES\*

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**Abstract.** Let  $S_n(\mathbf{F})$  be the vector space of  $n \times n$  symmetric matrices over a field  $\mathbf{F}$  (with certain restrictions on cardinality and characteristic). The transformations  $\phi$  on the space which satisfy one of the following conditions:

1.  $\det(A + \lambda B) = \det(\phi(A) + \lambda \phi(B))$  for all  $A, B \in S_n(\mathbf{F})$  and  $\lambda \in \mathbf{F}$ ;

2.  $\phi$  is surjective and det $(A + \lambda B) = det(\phi(A) + \lambda \phi(B))$  for all A, B and two specific  $\lambda$ ;

3.  $\phi$  is additive and preserves determinant

are characterized.

Key words. Linear preserving problem, Rank, Symmetric matrix, Determinant.

AMS subject classifications. 15A03, 15A04.

1. Introduction and statement of the results. Linear preserving problems is an active research area in matrix theory. The first result on linear preservers is due to Frobenius [1] who studied linear transformations on matrix algebras preserving the determinant. Let  $M_n(\mathbf{F})$  be the vector space of  $n \times n$  matrices over a field  $\mathbf{F}$ . Frobenius characterized a linear map  $\phi: M_n(\mathbf{F}) \to M_n(\mathbf{F})$  satisfying

(1.1) 
$$\det(\phi(A)) = \det(A), \quad \text{for all } A \in M_n(\mathbf{F})$$

when  $\mathbf{F} = \mathbb{C}$  (the complex field).

Recently, Dolinar and Šemrl [2] and Tan and Wang [4] respectively modified the problem by removing the linearity of  $\phi$  and changing condition (1.1) to

 $det(\phi(A) + \lambda\phi(B)) = det(A + \lambda B)$ , for all  $A, B \in M_n(\mathbf{F})$  and all  $\lambda \in \mathbf{F}$ .

This paper is motivated by [2] and [4]. We study determinant preservers on the vector space of symmetric matrices.

Let  $\mathbf{F}$  be a field. Let  $\mathbf{F}^*$  denote the set of all nonzero elements in  $\mathbf{F}$ . Let  $S_n(\mathbf{F})$ be the vector space of all  $n \times n$  symmetric matrices over  $\mathbf{F}$ . For  $A \in S_n(\mathbf{F})$ , let  $a_{ij}$ denote the (i, j)- entry of A,  $A^{ij}$  the (i, j)-cofactor of A, and adj A the adjoint of A. Let E(i, j) denote the matrix with 1 at the (i, j)- entry and 0 elsewhere,  $I_n$  the  $n \times n$ identity matrix and D(i, j) the matrix E(i, j) + E(j, i) for all i < j. For  $A \in M_n(\mathbf{F})$ , we denote by  $A^t$  the transpose of A. For  $A \in S_n(\mathbf{F})$ , we denote by  $v_A$  the column vector

$$(a_{11}, a_{12}, \cdots, a_{1n}, a_{22}, a_{23}, \cdots, a_{2n}, \cdots, a_{n-1,n-1}, a_{n-1,n}, a_{nn})^{\iota}.$$

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We define a map  $\sigma$  from  $S_n(\mathbf{F})$  to the column space  $\mathbf{F}^{\frac{n(n+1)}{2}}$  by  $\sigma(A) = v_A$  for all  $A \in S_n(\mathbf{F})$ . Obviously,  $\sigma$  is a nonsingular linear map. For  $A, B \in S_n(\mathbf{F})$ , we use  $D_{A,B}(t)$  to denote the polynomial det(A + tB). It is easy to see that the coefficient of  $t^{n-1}$  in  $D_{A,B}(t)$  is equal to  $\sum_{i=1}^n \sum_{j=1}^n a_{ij} B^{ij}$ .

In this paper we will prove the following main results.

THEOREM 1.1. Let  $\mathbf{F}$  be a field with  $|\mathbf{F}| \ge n$ ,  $|\mathbf{F}| > 3$  and  $\operatorname{ch} \mathbf{F} \ne 2$ , or  $\mathbf{F} = \mathbf{F}_2$ and n = 2. Then  $\phi : S_n(\mathbf{F}) \to S_n(\mathbf{F})$  is a transformation which satisfies the condition

(1.2) 
$$\det(A + \lambda B) = \det(\phi(A) + \lambda \phi(B)), \text{ for all } A, B \in S_n(\mathbf{F}) \text{ and all } \lambda \in \mathbf{F}$$

if and only if  $\phi$  has the form

(1.3) 
$$\phi(A) = \alpha P A P^t, \text{ for all } A \in S_n(\mathbf{F})$$

where  $\alpha \in \mathbf{F}^*$ ,  $P \in GL_n(\mathbf{F})$  (the set of all nonsingular matrices in  $M_n(\mathbf{F})$ ) and  $\det(\alpha P^2) = 1$ .

THEOREM 1.2. Let **F** be a field with  $|\mathbf{F}| \ge n$ ,  $|\mathbf{F}| > 3$  and  $\operatorname{ch} \mathbf{F} \ne 2$  and  $\phi$ :  $S_n(\mathbf{F}) \rightarrow S_n(\mathbf{F})$  be a surjective transformation satisfying

$$\det(A + \lambda_i B) = \det(\phi(A) + \lambda_i \phi(B)), \quad \text{for all } A, B \in S_n(\mathbf{F})$$

and i = 1, 2, where  $\lambda_i \in \mathbf{F}^*$  and  $(\lambda_1/\lambda_2)^k \neq 1$  for  $1 \leq k \leq n-2$ . Then  $\phi$  is of the form as given by (1.3).

THEOREM 1.3. Let **F** be a field such that  $\operatorname{ch} \mathbf{F} = 0$  or  $\operatorname{ch} \mathbf{F} \ge n$  and  $|\mathbf{F}| > 3$ , and let  $\phi : S_n(\mathbf{F}) \to S_n(\mathbf{F})$  be an additive transformation. If  $\phi$  satisfies the condition det  $A = \operatorname{det} \phi(A)$  for all  $A \in S_n(\mathbf{F})$ , then  $\phi$  is of the form as given by (1.3).

Because the proofs of Theorems 1.2 and 1.3 are similar to those for Theorems 2 and 3 of [4], they are omitted. In section 2 we will prove Theorem 1.1.

**2.** The proof of Theorem 1.1. In order to prove Theorem 1.1, we need several lemmas.

LEMMA 2.1. [5] Suppose  $\mathbf{F}$  is a field with  $|\mathbf{F}| > 3$ , and  $\phi : S_n(\mathbf{F}) \to S_n(\mathbf{F})$  is a nonsingular linear transformation which is a rank-one preserver. Then  $\phi$  is of the form

$$\phi(A) = \alpha P A P^t \quad for \ all \ A \in S_n(\mathbf{F}),$$

where  $\alpha \in \mathbf{F}^*$  and  $P \in GL_n(\mathbf{F})$ .

Recall that a matrix  $A \in M_n(\mathbf{F})$  is said to be alternate if  $x^t A x = 0$  for all  $x \in \mathbf{F}^n$ . The following result is known ([3, p.155; p.161, Theorem 7; p.171, Theorem 10]):

REMARK 2.2. Let **F** be a field and let  $A \in S_n(\mathbf{F})$ . Then there exists  $P \in GL_n(\mathbf{F})$  such that

(i)  $P^tAP$  is a diagonal matrix if  $ch\mathbf{F} \neq 2$ , or  $ch\mathbf{F} = 2$  and A is not alternate; and

(ii)  $P^t A P$  is of the form diag $(S, \ldots, S, 0, \ldots, 0)$ , where  $S = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$  if ch $\mathbf{F} = 2$  and A is alternate.

LEMMA 2.3. Suppose  $\phi$  is a linear transformation from  $S_n(\mathbf{F})$  into itself satisfying det  $A = \det \phi(A)$ , for all  $A \in S_n(\mathbf{F})$ . Then  $\phi$  is bijective.



*Proof.* It is sufficient to prove that  $\phi$  is an injective transformation, or to show that  $\phi(A) = 0$  implies that A = 0. Consider any  $A \in S_n(\mathbf{F})$  such that  $\phi(A) = 0$ . Then det  $A = \det \phi(A) = 0$ . This means rank A < n. By Remark 2.2, it is readily seen that there exists  $B \in S_n(\mathbf{F})$  such that rank  $B = n - \operatorname{rank} A$  and det $(A + B) \neq 0$ . Then we get det  $B = \det \phi(B) = \det \phi(A + B) = \det(A + B) \neq 0$ . Thus we have rank B = n. This implies rank A = 0, i.e., A = 0.  $\Box$ 

LEMMA 2.4. Suppose  $\mathbf{F}$  is a field with  $|\mathbf{F}| > 2$  and  $\operatorname{ch} \mathbf{F} \neq 2$ , and  $\phi$  is a linear transformation from  $S_n(F)$  into itself satisfying det  $A = \operatorname{det} \phi(A)$ , for all  $A \in S_n(\mathbf{F})$ . Then  $\phi$  is a rank-one preserver.

*Proof.* We need to show that for every rank-one matrix  $A \in S_n(\mathbf{F})$  we have rank  $\phi(A) = 1$ . By Remark 2.2, we may write A as  $aNE(1,1)N^t$  where  $a \in \mathbf{F}^*$  and  $N \in GL_n(\mathbf{F})$ . By Lemma 2.3,  $\phi$  is injective; so  $\phi(A) \neq 0$ . If rank  $\phi(A) = r > 1$ , since  $ch\mathbf{F} \neq 2$ , by Remark 2.2 we may assume that  $\phi(A) = M(D_r \oplus O)M^t$ , where  $M \in GL_n(\mathbf{F})$ ,  $D_r = diag(b_1, \dots, b_r)$  with  $b_1, \dots, b_r \in \mathbf{F}^*$ . Set  $B = M(diag(0, -b_2, \dots, -b_r) \oplus I_{n-r})M^t$ . By Lemma 2.3,  $\phi$  is surjective; so there exists  $C \in S_n(\mathbf{F})$  such that  $\phi(NCN^t) = B$ . Hence for every  $\lambda \in \mathbf{F}$ , we have

(i) 
$$\det(\lambda a E(1,1) + C)$$

$$= (\det N)^{-2} \det(N(\lambda a E(1,1) + C)N^{t})$$

$$= (\det N)^{-2} \det(\lambda A + NCN^{t})$$

$$= (\det N)^{-2} \det(\lambda \phi(A) + B)$$

$$= (\det M)^{2} (\det N)^{-2} \det(\lambda(b_{1}) \oplus (\lambda - 1) \operatorname{diag}(b_{2}, \cdots, b_{r}) \oplus I_{n-r}).$$

In particular, when  $\lambda = 0$  and 1 we obtain, respectively,

(ii) det  $C = (\det M)^2 (\det N)^{-2} \det(\operatorname{diag}(0, -b_2, \cdots, -b_r) \oplus I_{n-r}) = 0;$  and (iii) det $(aE(1, 1) + C) = (\det M)^2 (\det N)^{-2} \det((b_1) \oplus O_{r-1} \oplus I_{n-r}) = 0.$ Write C as  $\begin{bmatrix} c & w^t \\ w & C_1 \end{bmatrix}$ , where  $C_1 \in S_{n-1}(\mathbf{F})$ . By (ii) and (iii) we have  $a \det C_1 = \det C + \det \begin{bmatrix} a & w^t \\ 0 & C_1 \end{bmatrix} = \det(aE(1, 1) + C) = 0.$ 

On the other hand, since  $|\mathbf{F}| > 2$ , we can choose  $\lambda \in F$ ,  $\lambda \neq 0, 1$ . Then by (i) and an argument similar to the above one we have

$$\lambda a \det C_1 = \det C + \det \begin{bmatrix} \lambda a & w^t \\ 0 & C_1 \end{bmatrix} = \det(\lambda a E(1, 1) + C) \neq 0.$$

So we arrive at a contradiction. Hence r = 1, and  $\phi(A)$  is a rank-one matrix.

LEMMA 2.5. Suppose  $\mathbf{F}$  is a field with  $|\mathbf{F}| > 3$  and  $\operatorname{ch} \mathbf{F} \neq 2$ . Then  $\phi : S_n(\mathbf{F}) \rightarrow S_n(\mathbf{F})$  is a linear transformation which satisfies  $\det A = \det \phi(A)$  for all  $A \in S_n(\mathbf{F})$ , if and only if  $\phi$  has the form as given by Theorem 1.1.

*Proof.* The "if" part is obvious. The "only if" part follows immediately from Lemmas 2.1, 2.3 and 2.4.  $\Box$ 

LEMMA 2.6. There exists a basis for  $S_n(\mathbf{F})$  consisting of nonsingular matrices.

*Proof.* Denote by W the set of all nonsingular matrices in  $S_n(F)$ . We only need to prove that  $\operatorname{span} W = S_n(F)$ , or to show that  $E(i,i), D(i,j) \in \operatorname{span} W$  for all  $i, j = 1, \ldots, n, i < j$ .

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For any  $j \geq 2$ , it is easily checked that the matrix  $D(1,j) + I_n + E(j,j)$  is nonsingular. The same is also true for the matrix  $D(1,j) + I_n + kE(1,1)$ , where k denotes the k-fold sum of the identity element of F, provided that  $chF \not| k$ . Note that we have

$$I_n + \sum_{j=2}^n \{ [D(1,j) + I_n + kE(1,1)] - [D(1,j) + I_n + E(j,j)] \} = (k(n-1) + 1)E(1,1).$$

If  $\operatorname{ch} F \not| n$ , take k = 1. Then  $nE(1,1) \neq 0$  and  $\operatorname{ch} F \not| k$  (so that  $D(1,j) + I_n + kE(1,1)$  is nonsingular); hence  $E(1,1) \in \operatorname{span} W$ . If  $\operatorname{ch} F \mid n$  but  $\operatorname{ch} F \neq 2$ , take k = 2. Then we have  $\operatorname{ch} F \not| k$  and also  $E(1,1) \in \operatorname{span} W$ . If  $\operatorname{ch} F = 2$ , then

$$E(1,1) = \left[ E(1,1) + D(1,2) + \sum_{j=3}^{n} E(j,j) \right] + \left[ D(1,2) + \sum_{j=3}^{n} E(j,j) \right];$$

so we still have  $E(1,1) \in \text{span}W$ . This proves that in all cases  $E(1,1) \in \text{span}W$ . By symmetry, we also have  $E(j,j) \in \text{span}W$  for j = 2, ..., n.

In view of the relation

$$D(1,2) = \left( \begin{bmatrix} 0 & 1\\ 1 & 0 \end{bmatrix} \oplus I_{n-2} \right) - \sum_{j=3}^{n} E(j,j),$$

and the proved fact that  $E(j, j) \in \operatorname{span} W$  for all j, we have,  $D(1, 2) \in \operatorname{span} W$ . By symmetry, we also have  $D(i, j) \in \operatorname{span} W$  for all pairs of i, j (i < j). The proof is completed.  $\Box$ 

**Proof of Theorem 1.1:** It is clear that we need only treat the "only if" part. We treat the case  $ch \mathbf{F} \neq 2$  first.

When  $\operatorname{ch} \mathbf{F} \neq 2$ , by the result of Lemma 2.5, it suffices to prove that  $\phi$  is a linear transformation. Here we are borrowing (and correcting) the arguments used in the proof of [4, Proposition 2.1]. Note that condition (2) implies that for any  $A, B \in S_n(\mathbf{F})$ , the polynomial functions defined by the polynomials  $D_{A,B}(t)$  and  $D_{\phi(A),\phi(B)}(t)$  are equal. We want to prove that they are equal as polynomials. (In the proof of [4, Proposition 2.1], the latter is taken for granted.) In view of condition (2),  $\phi$  preserves the determinant; so the coefficients of  $t^n$  in the polynomials  $D_{A,B}(t)$  and  $D_{\phi(A),\phi(B)}(t)$ , which are, respectively, det B and det  $\phi(B)$ , are the same. Hence, the polynomial  $D_{A,B}(t) - D_{\phi(A),\phi(B)}(t)$  is of degree at most n-1. On the other hand, by condition (2) again, each element of F is a root of the latter polynomial. But  $|\mathbf{F}| \geq n$ , so the latter polynomial is equal to the zero polynomial. (The preceding argument also shows that in the hypothesis of [4, Proposition 2.1], we need to add the assumption that  $|\mathbf{F}| \geq n$ .) Let  $\phi(A) = (\tilde{a}_{ij})$ , by considering the coefficient of  $t^{n-1}$ , we have

$$\sum_{i,j=1}^{n} a_{ij} B^{ij} = \sum_{i,j=1}^{n} \tilde{a}_{ij} \phi(B)^{ij}.$$

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Noting that A and B are symmetric and recalling that adj  $B = (B^{ji})$ , we can rewrite the above as

(2.1) 
$$v_{\mathrm{adj}\,B}^t \cdot \Gamma \cdot v_A = v_{\mathrm{adj}\,\phi(B)}^t \cdot \Gamma \cdot v_{\phi(A)},$$

where  $\Gamma = \text{diag}(1, 2I_{n-1}, 1, 2I_{n-2}, \dots, 1, 2I_2, 1, 2, 1)$ . Since  $\text{ch}\mathbf{F} \neq 2, \Gamma \in GL_{\frac{n(n+1)}{2}}(\mathbf{F})$ .

By Lemma 2.6 there exists a basis for  $S_n(F)$  consisting of nonsingular matrices, say  $\{C_1, C_2, \ldots, C_{\frac{n(n+1)}{2}}\}$ . Then for each k, adj  $C_k = (\det C_k)C_k^{-1}$  and a simple calculation yields adj (adj  $C_k$ ) =  $d_kC_k$ , where  $d_k = (\det C_k)^{n-2}$ . For all  $A \in S_n(F)$ , by taking in (2.1)  $B = \operatorname{adj} C_k$  for  $k = 1, \cdots, \frac{n(n+1)}{2}$ , we obtain

$$d_k v_{C_k}^t \cdot \Gamma \cdot v_A = v_{\text{adj } \phi(\text{adj } C_k)}^t \cdot \Gamma \cdot v_{\phi(A)}, \text{ for } k = 1, \dots, \frac{n(n+1)}{2}.$$

Let D, X and Y be the matrices in  $M_{\underline{n(n+1)}}(\mathbf{F})$  given by

$$D = \operatorname{diag}(d_1, \cdots, d_{\frac{n(n+1)}{2}}), \quad X = \begin{bmatrix} v_{C_1}^t \\ v_{C_2}^t \\ \vdots \\ v_{C_{\frac{n(n+1)}{2}}}^t \end{bmatrix}, \quad Y = \begin{bmatrix} v_{\operatorname{adj}}^t \phi(\operatorname{adj} C_1) \\ v_{\operatorname{adj}}^t \phi(\operatorname{adj} C_2) \\ \vdots \\ v_{\operatorname{adj}}^t \phi(\operatorname{adj} C_{\frac{n(n+1)}{2}}) \end{bmatrix}.$$

Then we have

(2.2) 
$$D \cdot X \cdot \Gamma \cdot v_A = Y \cdot \Gamma \cdot v_{\phi(A)}, \text{ for all } A \in S_n(\mathbf{F}).$$

It is clear that  $v_{C_1}^t, \dots, v_{C_{\frac{n(n+1)}{2}}}^t$  are linearly independent, as  $C_1, C_2, \dots, C_{\frac{n(n+1)}{2}}$  form a basis for  $S_n(\mathbf{F})$ . So X is nonsingular. By taking in (2.2) A = D(i, j) or E(i, i) for all  $i, j = 1, \dots, n, i < j$ , we readily obtain

$$D \cdot X \cdot \Gamma \cdot I_{\frac{n(n+1)}{2}} = Y \cdot \Gamma \cdot J,$$

where J is the  $\frac{n(n+1)}{2} \times \frac{n(n+1)}{2}$  matrix with columns  $v_{\phi(D(i,j))}$  or  $v_{\phi(E(i,j))}$  for  $1 \le i < j \le n$  arranged in the natural way. So Y is nonsingular. By (2.2) we have

$$\Gamma^{-1}Y^{-1}DX\Gamma v_A = v_{\phi(A)}$$
 for all  $A \in S_n(\mathbf{F})$ ,

which implies that the transformation  $\phi_1$  from  $\mathbf{F}^{\frac{n(n+1)}{2}}$  to itself given by

$$\phi_1(v_A) = v_{\phi(A)}$$
 for all  $v_A \in \mathbf{F}^{\frac{n(n+1)}{2}}$ ,

is linear. But  $\phi = \sigma^{-1}\phi_1\sigma$ , so  $\phi$  is a linear transformation.

Now we treat the "only if" part for the case 
$$\mathbf{F} = \mathbf{F}_2$$
 and  $n = 2$ .  
Let  $\Gamma_1 = S_2(\mathbf{F}_2) \setminus GL_2(\mathbf{F}_2)$  and  $\Gamma_2 = S_2(\mathbf{F}_2) \cap GL_2(\mathbf{F}_2)$ . Then we have

$$\Gamma_1 = \left\{ 0, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \right\},$$

$$\Gamma_2 = \left\{ I_2, \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}.$$



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We first show that  $\phi(0) = 0$ ,  $\phi\left(\begin{bmatrix} 0 & 1\\ 1 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 & 1\\ 1 & 0 \end{bmatrix}$ ,  $\phi(\Gamma_1 \setminus \{0\}) = \Gamma_1 \setminus \{0\}$ and  $\phi\left(\Gamma_2 \setminus \left\{\begin{bmatrix} 0 & 1\\ 1 & 0 \end{bmatrix}\right\}\right) = \Gamma_2 \setminus \left\{\begin{bmatrix} 0 & 1\\ 1 & 0 \end{bmatrix}\right\}$ . Since  $\phi$  preserves the determinant, we have  $\phi(\Gamma_1) \subset \Gamma_1$  for i = 1, 2. We can

Since  $\phi$  preserves the determinant, we have  $\phi(\Gamma_i) \subseteq \Gamma_i$  for i = 1, 2. We can readily verify the following:

1<sup>0</sup> det $(A + B) \neq 0$  for every pair of distinct matrices  $A, B \in \Gamma_1 \setminus \{0\}$ ;

 $2^0 \det(0+A) = 0$  for every  $A \in \Gamma_1 \setminus \{0\}$ .

Since  $\phi(\Gamma_1) = \Gamma_1$ , by 1<sup>0</sup>, 2<sup>0</sup> and condition (2) it follows that we have  $\phi(\Gamma_1 \setminus \{0\}) = \Gamma_1 \setminus \{0\}$  and  $\phi(0) = 0$ .

Similarly, by making use of the fact that  $\phi(\Gamma_2) \subseteq \Gamma_2$  and that  $\det(A+B) \neq 0$ for every pair of distinct matrices  $A, B \in \Gamma_2 \setminus \left\{ \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}$ , we can also show that  $\phi\left(\Gamma_2 \setminus \left\{ \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\} \right) = \Gamma_2 \setminus \left\{ \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right\}$  and  $\phi\left( \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \right) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ . ¿From the above discussion,  $\phi(I_2)$  equals  $I_2$ ,  $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$  or  $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ . Consider the

From the above discussion,  $\phi(I_2)$  equals  $I_2$ ,  $\begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 0 \end{bmatrix}$  or  $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ . Consider the case when  $\phi(I_2) = I_2$ . Then  $\phi\left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}\right)$  equals  $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$  or  $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ . Suppose the former happens. Then  $\phi(A) = A$  for all  $A \in \Gamma_2$  and we can show that  $\phi$  is in fact the identity transformation of  $S_2(F)$  as follows.

Note that the sum of  $\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$  and  $I_2$  belongs to  $\Gamma_2$ , whereas the sum of  $I_2$ and  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  (or  $\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ ) belongs to  $\Gamma_1$ . But  $\phi$  fixes  $I_2$ , it follows that  $\phi$  also fixes  $\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ . By a similar argument, we can also show that  $\phi$  fixes  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ . So  $\phi$  is the identity transformation when  $\phi(I_2) = I_2$  and  $\phi\left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}\right) =$  $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$ . If  $\phi(I_2) = I_2$  and  $\phi\left(\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$ , then necessarily

If  $\phi(I_2) = I_2$  and  $\phi\left(\begin{bmatrix} 1 & 1\\ 1 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 & 1\\ 1 & 1 \end{bmatrix}$ , then necessarily  $\phi\left(\begin{bmatrix} 0 & 1\\ 1 & 1 \end{bmatrix}\right) = \begin{bmatrix} 1 & 1\\ 1 & 0 \end{bmatrix}$ .

Using the same kind of argument as before, we can then show that

$$\phi\left(\left[\begin{array}{cc}1&1\\1&1\end{array}\right]\right) = \left[\begin{array}{cc}1&1\\1&1\end{array}\right],$$
$$\phi\left(\left[\begin{array}{cc}1&0\\0&0\end{array}\right]\right) = \left[\begin{array}{cc}0&0\\0&1\end{array}\right]$$



and

$$\phi\left(\left[\begin{array}{cc} 0 & 0 \\ 0 & 1 \end{array}\right]\right) = \left[\begin{array}{cc} 1 & 0 \\ 0 & 0 \end{array}\right]$$

The preceding argument shows that there are at most two transformations  $\phi$  that satisfy  $\phi(I_2) = I_2$  and condition (2). Likewise, we can also show that there are at most two transformations  $\phi$  that satisfy condition (2) for which  $\phi(I_2) = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$  (or  $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ ). So altogether there are at most six transformations  $\varphi : S_2(\mathbf{F}_2) \to S_2(\mathbf{F}_2)$ that satisfy condition (2). On the other hand, there are precisely six matrices in  $GL_2(F_2)$ , namely,  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$  and  $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$ . For each such matrix P the transformation  $\phi$  given by  $\phi(A) = PAP^t$  clearly satisfies condition (2), and also it is readily checked that the six transformations arising in

this way are different. This proves our result.  $\Box$ We do not know whether Theorem 1.1 can be extended to include the cases  $ch\mathbf{F} = 2$  (but not  $\mathbf{F} = \mathbf{F}_2$  and n = 2, which is already covered), and  $|\mathbf{F}| = 3$  with

 $ch\mathbf{F} = 2$  (but not  $\mathbf{F} = \mathbf{F}_2$  and n = 2, which is already covered), and  $|\mathbf{F}| = 3$  with n = 2 or 3.

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