

EXISTENCE OF A POSITIVE SOLUTION TO A RIGHT FOCAL BOUNDARY VALUE PROBLEM

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ABSTRACT. In this paper we apply the recent extension of the Leggett-Williams Fixed Point Theorem which requires neither of the functional boundaries to be invariant to the second order right focal boundary value problem. We demonstrate a technique that can be used to deal with a singularity and provide a non-trivial example.

1. INTRODUCTION

The recent topological proof and extension of the Leggett-Williams fixed point theorem [3] does not require either of the functional boundaries to be invariant with respect to a functional wedge and its proof uses topological methods instead of axiomatic index theory. Functional fixed point theorems (including [2, 4, 5, 6, 8]) can be traced back to Leggett and Williams [7] when they presented criteria which guaranteed the existence of a fixed point for a completely continuous map that did not require the operator to be invariant with regard to the concave functional boundary of a functional wedge. Avery, Henderson, and O'Regan [1], in a dual of the Leggett-Williams fixed point theorem, gave conditions which guaranteed the existence of a fixed point for a completely continuous map that did not require the operator to be invariant relative to the concave functional boundary of a functional wedge. We will demonstrate a technique to take advantage of the added flexibility of the new fixed point theorem for a right focal boundary value problem.

2. PRELIMINARIES

In this section we will state the definitions that are used in the remainder of the paper.

Definition 1. Let E be a real Banach space. A nonempty closed convex set $P \subset E$ is called a cone if it satisfies the following two conditions:

- (i) $x \in P, \lambda \geq 0$ implies $\lambda x \in P$;
- (ii) $x \in P, -x \in P$ implies $x = 0$.

Every cone $P \subset E$ induces an ordering in E given by

$$x \leq y \text{ if and only if } y - x \in P.$$

Definition 2. An operator is called completely continuous if it is continuous and maps bounded sets into precompact sets.

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Definition 3. A map α is said to be a nonnegative continuous concave functional on a cone P of a real Banach space E if $\alpha : P \rightarrow [0, \infty)$ is continuous and

$$\alpha(tx + (1 - t)y) \geq t\alpha(x) + (1 - t)\alpha(y)$$

for all $x, y \in P$ and $t \in [0, 1]$. Similarly we say the map β is a nonnegative continuous convex functional on a cone P of a real Banach space E if $\beta : P \rightarrow [0, \infty)$ is continuous and

$$\beta(tx + (1 - t)y) \leq t\beta(x) + (1 - t)\beta(y)$$

for all $x, y \in P$ and $t \in [0, 1]$.

Let α and ψ be non-negative continuous concave functionals on P and δ and β be non-negative continuous convex functionals on P ; then, for non-negative real numbers a, b, c and d , we define the following sets:

$$(1) \quad A := A(\alpha, \beta, a, d) = \{x \in P : a \leq \alpha(x) \text{ and } \beta(x) \leq d\},$$

$$(2) \quad B := B(\alpha, \delta, \beta, a, b, d) = \{x \in A : \delta(x) \leq b\},$$

and

$$(3) \quad C := C(\alpha, \psi, \beta, a, c, d) = \{x \in A : c \leq \psi(x)\}.$$

We say that A is a *functional wedge with concave functional boundary* defined by the concave functional α and convex functional boundary defined by the convex functional β . We say that an operator $T : A \rightarrow P$ is *invariant with respect to the concave functional boundary*, if $a \leq \alpha(Tx)$ for all $x \in A$, and that T is *invariant with respect to the convex functional boundary*, if $\beta(Tx) \leq d$ for all $x \in A$. Note that A is a convex set. The following theorem is an extension of the original Leggett-Williams fixed point theorem [7].

Theorem 4. [Extension of Leggett-Williams] Suppose P is a cone in a real Banach space E , α and ψ are non-negative continuous concave functionals on P , δ and β are non-negative continuous convex functionals on P , and for non-negative real numbers a, b, c and d the sets A, B and C are as defined in (1), (2) and (3). Furthermore, suppose that A is a bounded subset of P , that $T : A \rightarrow P$ is completely continuous and that the following conditions hold:

$$(A1) \quad \{x \in A : c < \psi(x) \text{ and } \delta(x) < b\} \neq \emptyset \text{ and } \{x \in P : \alpha(x) < a \text{ and } d < \beta(x)\} = \emptyset;$$

$$(A2) \quad \alpha(Tx) \geq a \text{ for all } x \in B;$$

$$(A3) \quad \alpha(Tx) \geq a \text{ for all } x \in A \text{ with } \delta(Tx) > b;$$

$$(A4) \quad \beta(Tx) \leq d \text{ for all } x \in C; \text{ and,}$$

$$(A5) \quad \beta(Tx) \leq d \text{ for all } x \in A \text{ with } \psi(Tx) < c.$$

Then T has a fixed point $x^* \in A$.

3. RIGHT FOCAL BOUNDARY VALUE PROBLEM

In this section we will illustrate the key techniques for verifying the existence of a positive solution for a boundary value problem using the newly developed extension of the Leggett-Williams fixed point theorem, applying the properties of a Green's function, bounding the

nonlinearity by constants over some intervals, and using concavity to deal with a singularity. Consider the second order nonlinear focal boundary value problem

$$(4) \quad x''(t) + f(x(t)) = 0, \quad t \in (0, 1),$$

$$(5) \quad x(0) = 0 = x'(1),$$

where $f : \mathbb{R} \rightarrow [0, \infty)$ is continuous. If x is a fixed point of the operator T defined by

$$Tx(t) := \int_0^1 G(t, s)f(x(s))ds,$$

where

$$G(t, s) = \begin{cases} t & : t \leq s, \\ s & : s \leq t, \end{cases}$$

is the Green's function for the operator L defined by

$$Lx(t) := -x'',$$

with right-focal boundary conditions

$$x(0) = 0 = x'(1),$$

then it is well known that x is a solution of the boundary value problem (4), (5). Throughout this section of the paper we will use the facts that $G(t, s)$ is nonnegative, and for each fixed $s \in [0, 1]$, the Green's function is nondecreasing in t .

Define the cone $P \subset E = C[0, 1]$ by

$$P := \{x \in E : x \text{ is nonnegative, nondecreasing, and concave}\}.$$

For fixed $\nu, \tau, \mu \in [0, 1]$ and $x \in P$, define the concave functionals α and ψ on P by

$$\alpha(x) := \min_{t \in [\tau, 1]} x(t) = x(\tau), \quad \psi(x) := \min_{t \in [\mu, 1]} x(t) = x(\mu),$$

and the convex functionals δ and β on P by

$$\delta(x) := \max_{t \in [0, \nu]} x(t) = x(\nu), \quad \beta(x) := \max_{t \in [0, 1]} x(t) = x(1).$$

In the following theorem, we demonstrate how to apply the Extension of the Leggett-Williams Fixed Point Theorem (Theorem 4), to prove the existence of at least one positive solution to (4), (5).

Theorem 5. *If $\tau, \nu, \mu \in (0, 1]$ are fixed with $\tau \leq \mu < \nu \leq 1$, d and m are positive real numbers with $0 < m \leq d\mu$ and $f : [0, \infty) \rightarrow [0, \infty)$ is a continuous function such that*

- (a) $f(w) \geq \frac{d}{\nu-\tau}$ for $w \in [\tau d, \nu d]$,
- (b) $f(w)$ is decreasing for $w \in [0, m]$ with $f(m) \geq f(w)$ for $w \in [m, d]$, and
- (c) $\int_0^\mu s f\left(\frac{ms}{\mu}\right) ds \leq \frac{2d-f(m)(1-\mu^2)}{2}$,

then the operator T has at least one positive solution $x^* \in A(\alpha, \beta, \tau d, d)$.

Proof. Let $a = \tau d$, $b = \nu d = \frac{a\nu}{\tau}$, and $c = d\mu$. Let $x \in A(\alpha, \beta, a, d)$ then if $t \in (0, 1)$, by the properties of the Green's function $(Tx)''(t) = -f(x(t))$ and $Tx(0) = 0 = (Tx)'(1)$, thus

$$T : A(\alpha, \beta, a, d) \rightarrow P.$$

We will also take advantage of the following property of the Green's function. For any $y, w \in [0, 1]$ with $y \leq w$ we have

$$(6) \quad \min_{s \in [0, 1]} \frac{G(y, s)}{G(w, s)} \geq \frac{y}{w}.$$

By the Arzela-Ascoli Theorem it is a standard exercise to show that T is a completely continuous operator using the properties of G and f , and by the definition of β , we have that A is a bounded subset of the cone P . Also, if $x \in P$ and $\beta(x) > d$, then by the properties of the cone P ,

$$\alpha(x) = x(\tau) \geq \left(\frac{\tau}{1}\right) x(1) = \tau\beta(x) > \tau d = a.$$

Therefore,

$$\{x \in P : \alpha(x) < a \text{ and } d < \beta(x)\} = \emptyset.$$

For any $K \in \left(\frac{2d}{2-\mu}, \frac{2d}{2-\nu}\right)$ the function x_K defined by

$$x_K(t) \equiv \int_0^1 KG(t, s)ds = \frac{Kt(2-t)}{2} \in A,$$

since

$$\alpha(x_K) = x_K(\tau) = \frac{K\tau(2-\tau)}{2} > \frac{d\tau(2-\tau)}{2-\mu} \geq d\tau = a,$$

$$\beta(x_K) = x_K(1) = \frac{K}{2} < \frac{d}{2-\nu} \leq d,$$

and x_K has the properties that

$$\psi(x_K) = x_K(\mu) = \frac{K\mu(2-\mu)}{2} > \left(\frac{2d}{2-\mu}\right) \left(\frac{\mu(2-\mu)}{2}\right) = d\mu = c$$

and

$$\delta(x_K) = x_K(\nu) = \frac{K\nu(2-\nu)}{2} < \left(\frac{2d}{2-\nu}\right) \left(\frac{\nu(2-\nu)}{2}\right) = d\nu = b.$$

Hence

$$\{x \in A : c < \psi(x) \text{ and } \delta(x) < b\} \neq \emptyset.$$

Claim 1: $\alpha(Tx) \geq a$ for all $x \in B$.

Let $x \in B$. Thus by condition (a),

$$\begin{aligned} \alpha(Tx) &= \int_0^1 G(\tau, s) f(x(s)) ds \geq \left(\frac{a}{\tau(\nu-\tau)}\right) \int_\tau^\nu G(\tau, s) ds \\ &= \left(\frac{a}{\tau(\nu-\tau)}\right) (\tau(\nu-\tau)) = a. \end{aligned}$$

Claim 2: $\alpha(Tx) \geq a$, for all $x \in A$ with $\delta(Tx) > b$.

Let $x \in A$ with $\delta(Tx) > b$. Thus by the properties of G (6),

$$\begin{aligned}\alpha(Tx) &= \int_0^1 G(\tau, s) f(x(s)) ds \geq \left(\frac{\tau}{\nu}\right) \int_0^1 G(\nu, s) f(x(s)) ds \\ &= \left(\frac{\tau}{\nu}\right) \delta(Tx) > \left(\frac{\tau}{\nu}\right) (d\nu) = a.\end{aligned}$$

Claim 3: $\beta(Tx) \leq d$, for all $x \in C$.

Let $x \in C$, thus by the concavity of x , for $s \in [0, \mu]$ we have

$$x(s) \geq \frac{cs}{\mu} \geq \frac{ms}{\mu}.$$

Hence by properties (b) and (c),

$$\begin{aligned}\beta(Tx) &= \int_0^1 G(1, s) f(x(s)) ds = \int_0^1 s f(x(s)) ds \\ &= \int_0^\mu s f(x(s)) ds + \int_\mu^1 s f(x(s)) ds \\ &\leq \int_0^\mu s f\left(\frac{ms}{\mu}\right) ds + f(m) \int_\mu^1 s ds \\ &\leq \frac{2d - f(m)(1 - \mu^2)}{2} + \frac{f(m)(1 - \mu^2)}{2} = d.\end{aligned}$$

Claim 4: $\beta(Tx) \leq d$, for all $x \in A$ with $\psi(Tx) < c$.

Let $x \in A$ with $\psi(Tx) < c$. Thus by the properties of G (6),

$$\begin{aligned}\beta(Tx) &= \int_0^1 G(1, s) f(x(s)) ds \leq \left(\frac{1}{\mu}\right) \int_0^1 G(\mu, s) f(x(s)) ds \\ &= \left(\frac{1}{\mu}\right) Tx(\mu) = \left(\frac{1}{\mu}\right) \psi(Tx) \leq \left(\frac{1}{\mu}\right) c = d.\end{aligned}$$

Therefore, the hypotheses of Theorem 4 have been satisfied; thus the operator T has at least one positive solution $x^* \in A(\alpha, \beta, a, d)$. \square

We note that because of the concavity of solutions, the proof of Theorem 5 remains valid for certain singular nonlinearities as presented in this example.

Example: Let

$$d = \frac{5}{4}, \quad \tau = \frac{1}{16}, \quad \mu = \frac{3}{4}, \quad \text{and} \quad \nu = \frac{15}{16}.$$

Then the boundary value problem

$$x'' + \frac{1}{\sqrt{x}} + \sqrt{x} = 0,$$

with right-focal boundary conditions

$$x(0) = 0 = x'(1),$$

has at least one positive solution x^* which can be verified by the above theorem, with

$$5/64 \leq x^*(1/16) \quad \text{and} \quad x^*(1) \leq 5/4.$$

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