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## SOME NEW INEQUALITIES FOR THE GAMMA, BETA AND ZETA FUNCTIONS

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## Abstract

An inequality involving a positive linear operator acting on the composition of two continuous functions is presented. This inequality leads to new inequalities involving the Beta, Gamma and Zeta functions and a large family of functions which are Mellin transforms.

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[^0]
## 1. Introduction

Let $I$ be the interval $(0,1)$ or $(0,+\infty)$ and let $f$ and $g$ be functions which are strictly increasing, strictly positive and continuous on $I$. To fix ideas, we shall suppose that $f(x) \rightarrow 0$ and $g(x) \rightarrow 0$ as $x \rightarrow 0+$. Suppose also that $f / g$ is strictly increasing.

Let $L$ be a positive linear functional defined on a subspace $C^{*}(I) \subset C(I)$; see Note below. Supposing that $f, g \in C^{*}(I)$, define the function $\phi$ by

$$
\begin{equation*}
\phi=g \frac{L(f)}{L(g)} \tag{1.1}
\end{equation*}
$$

Next, let $F$ be defined on the ranges of $f$ and $g$ so that the compositions $F(f)$ and $F(g)$ each belong to $C^{*}(I)$.

Note. In our applications the functional $L$ will involve an integral over the interval $I$, and so that $L$ will be well-defined, it is necessary to require extra end conditions to be satisfied by the members of $C(I)$. The subspace arrived at in this way will be denoted by $C^{*}(I)$ and this will be the domain of $L$.

The subspace $C^{*}(I)$ may vary from case to case but, for technical reasons, it will always be supposed that the functions $e_{k}$, where $e_{k}(x)=x^{k}(k=0,1,2)$, are in $C^{*}(I)$.

Our object is to prove the results:

## Theorem 1.1.

(a) If $F$ is convex then

$$
\begin{equation*}
L[F(f)] \geq L[F(\phi)] \tag{1.2a}
\end{equation*}
$$



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(b) If $F$ is concave then

$$
\begin{equation*}
L[F(f)] \leq L[F(\phi)] \tag{1.2b}
\end{equation*}
$$

Clearly it is sufficient to consider only (1.2a) and, prior to Section 3 where we present our applications, we shall proceed with this understanding.

In the note [1] this result was proved for the case in which $I$ was $[0,1], g(x)$ was $x$, and $F$ was differentiable but it has since been realised that the more general results of the present theorem are a source of interesting inequalities involving the Gamma, Beta and Zeta functions.

The method of proof in [1] could possibly be adapted to the present case but, instead, we shall give a proof which is entirely different. As well as using the more general $g(x)$ it allows the less stringent hypothesis that $F$ is merely convex and deals with intervals other than $[0,1]$. We also believe that this proof is of some interest in its own right.


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## 2. Proofs

First, we need the following lemma:

## Lemma 2.1.

$$
\begin{equation*}
L\left(f^{2}\right)-L\left(\phi^{2}\right) \geq 0 \tag{2.1}
\end{equation*}
$$

Proof. It is seen from (1.1) that

$$
L(f)-L(\phi)=0
$$

Since $L$ is positive, this negates the possibility that

$$
f(x)-\phi(x)>0 \quad \text { or } \quad f(x)-\phi(x)<0 \quad \text { for all } x \in I
$$

Hence $f-\phi$ changes sign in $I$ and since

$$
f-\phi=f-g \frac{L(f)}{L(g)}
$$

and

$$
\frac{f}{g} \text { is strictly increasing in } I,
$$

this change of sign is from - to + .
We suppose that the change of sign occurs at $x=\gamma$ and that $f(\gamma)=\phi(\gamma)=$ $K$ (say).

Since $f-\phi$ is non-negative on $x \geq \gamma$ and $f+\phi \geq 2 K$ there, then

$$
(f-\phi)(f+\phi) \geq 2 K(f-\phi) \text { on } x \geq \gamma
$$

Since $f-\phi$ is negative on $x<\gamma$ and $f+\phi<2 K$ there then

$$
(f-\phi)(f+\phi)>2 K(f-\phi) \text { on } x<\gamma .
$$

Hence

$$
f^{2}-\phi^{2}=(f-\phi)(f+\phi) \geq 2 K(f-\phi) \quad \text { on } I .
$$

Applying $L$ we get the result of the lemma.
Proof of the theorem (part (a)). Let us introduce the functional $\Lambda$ defined on $C^{*}(I)$ by

$$
\Lambda(G)=L[G(f)]-L[G(\phi)],
$$

in which $f$ and $\phi$ are fixed. It is easily seen that $\Lambda$ is a continuous linear functional.

According to the theorem, we will be interested in those $F$ for which $F \in S$ where $S$ is the subset of $C^{*}(I)$ consisting of continuous convex functions.

Now the set $S$ is itself convex and closed so that the maximum and/or minimum values of $\Lambda$, when acting on $S$, will be taken in its set of extreme points, say $\operatorname{Ext}(S)$.

But

$$
\operatorname{Ext}(S)=\left\{A e_{0}+B e_{1}\right\},
$$

where $e_{k}(x)=x^{k}(k=0,1,2)$.
Now

$$
\begin{gathered}
\Lambda\left(e_{0}\right)=L\left[e_{0}(f)\right]-L\left[e_{0}(\phi)\right]=L(1)-L(1)=0 \\
\Lambda\left(e_{1}\right)=L\left[e_{1}(f)\right]-L\left[e_{1}(\phi)\right]=L(f)-L(\phi)=0 \quad \text { by }(1.1)
\end{gathered}
$$

so that zero is the (unique) extreme value of $\Lambda$.

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Next

$$
\Lambda\left(e_{2}\right)=L\left[e_{2}(f)\right]-L\left[e_{2}(\phi)\right]=L\left(f^{2}\right)-L\left(\phi^{2}\right) \geq 0 \text { by }
$$

so this extreme value is a minimum. That is to say that

$$
\Lambda(F)=L[F(f)]-L[F(\phi)] \geq 0 \text { for all } F \in S
$$

and this concludes the proof of the theorem.


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## 3. Preparation for the Applications

In (1.2a) and (1.2b) take

$$
F(u)=u^{\alpha}
$$

which is convex if ( $\alpha<0$ or $\alpha>1$ ) and concave if $0<\alpha<1$. So now we have

$$
L\left(f^{\alpha}\right) \gtrless L\left(\phi^{\alpha}\right)
$$

with $\gtrless$ (upper and lower) respectively, in the cases 'convex', 'concave'. There is equality in case $\alpha=0$ or $\alpha=1$.

Substituting for $\phi$ this reads:

$$
\begin{equation*}
\frac{[L(g)]^{\alpha}}{L\left(g^{\alpha}\right)} \gtrless \frac{[L(f)]^{\alpha}}{L\left(f^{\alpha}\right)} . \tag{3.1}
\end{equation*}
$$

Finally, take

$$
f(x)=x^{\beta} \quad \text { and } \quad g(x)=x^{\delta} \quad \text { with } \beta>\delta>0
$$

Then (3.1) becomes (using incorrect, but simpler, notation):

$$
\begin{equation*}
\frac{\left[L\left(x^{\delta}\right)\right]^{\alpha}}{L\left(x^{\alpha \delta}\right)} \gtrless \frac{\left[L\left(x^{\beta}\right)\right]^{\alpha}}{L\left(x^{\alpha \beta}\right)} . \tag{3.2}
\end{equation*}
$$

The inequality (3.2) is the source of our various examples.


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## 4. Applications

Note. To avoid repetition in the examples below (except at (4.8)) it is to be understood that $\gtrless$ correspond to the cases $(\alpha<0$ or $\alpha>1)$ and $(0<\alpha<1)$ respectively. There will be equality if $\alpha=0$ or 1 . Furthermore, it will always be the case that $\beta>\delta>0$.

### 4.1. The Gamma function

Referring back to the Note in the Introduction, the subspace $C^{*}(I)$ for this application is obtained from $C(I)$ by requiring its members to satisfy:
(i) $w(x)=O\left(x^{\theta}\right) \quad($ for any $\theta>-1)$ as $x \rightarrow 0$
(ii) $w(x)=O\left(x^{\varphi}\right) \quad$ (for any finite $\varphi$ ) as $x \rightarrow+\infty$.

Then we define

$$
L(w)=\int_{0}^{\infty} w(x) e^{-x} d x
$$

In this case (3.2) gives:

$$
\begin{equation*}
\frac{[\Gamma(1+\delta)]^{\alpha}}{\Gamma(1+\alpha \delta)} \gtrless \frac{[\Gamma(1+\beta)]^{\alpha}}{\Gamma(1+\alpha \beta)} \tag{4.1}
\end{equation*}
$$

in which, $\alpha \beta>-1$ and $\alpha \delta>-1$.
In [2] this result was obtained partially in the form

$$
\frac{[\Gamma(1+y)]^{n}}{\Gamma(1+n y)}>\frac{[\Gamma(1+x)]^{n}}{\Gamma(1+n x)}
$$

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where $1 \geq x>y>0$ and $n=2,3, \ldots$
Then, in [3] this was improved to

$$
\frac{[\Gamma(1+y)]^{\alpha}}{\Gamma(1+\alpha y)}>\frac{[\Gamma(1+x)]^{\alpha}}{\Gamma(1+\alpha x)}
$$

where $1 \geq x>y>0$ and $\alpha>1$.
The methods used in [2] and [3] to obtain these results are quite different from that used here.

### 4.2. The Beta function

The subspace $C^{*}(I)$ for this application is obtained from $C(I)$ by requiring its members to satisfy:

$$
\begin{gathered}
\left.w(x)=O\left(x^{\theta}\right) \text { (for any } \theta>-1\right) \text { as } x \rightarrow 0 \\
w(x)=O(1) \text { as } x \rightarrow 1
\end{gathered}
$$

Then we define

$$
L(w)=\int_{0}^{1} w(x)(1-x)^{\zeta-1} d x:(\zeta>0)
$$

From (3.2) we have

$$
\begin{equation*}
\frac{[B(1+\delta, \zeta)]^{\alpha}}{B(1+\alpha \delta, \zeta)} \gtrless \frac{[B(1+\beta, \zeta)]^{\alpha}}{B(1+\alpha \beta, \zeta)} \tag{4.2}
\end{equation*}
$$

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in which $\alpha \delta>-1, \alpha \beta>-1$ and $\zeta>0$.

### 4.3. The Zeta function (i)

For this example the subspace $C^{*}(I)$ is the same as for the Gamma function case above. $L$ is defined by

$$
L(w)=\int_{0}^{\infty} w(x) \frac{x e^{-x}}{1-e^{-x}} d x
$$

We recall here (see [4]) that when $s$ is real and $s>1$ then

$$
\Gamma(s) \zeta(s)=\int_{0}^{\infty} x^{s-1} \frac{e^{-x}}{1-e^{-x}} d x
$$

Using (3.2) this leads to

$$
\begin{equation*}
\frac{[\Gamma(2+\delta) \zeta(2+\delta)]^{\alpha}}{\Gamma(2+\alpha \delta) \zeta(2+\alpha \delta)} \gtrless \frac{[\Gamma(2+\beta) \zeta(2+\beta)]^{\alpha}}{\Gamma(2+\alpha \beta) \zeta(2+\alpha \beta)} \tag{4.3}
\end{equation*}
$$

in which $\alpha \beta>-1$ and $\alpha \delta>-1$.
The number of examples of this nature could be enlarged considerably. For example, the formula

$$
\Gamma(s) \eta(s)=\int_{0}^{\infty} x^{s-1} \frac{e^{-x}}{1+e^{-x}} d x, \quad s>0
$$

where

$$
\eta(s)=\sum_{k=1}^{\infty} \frac{(-1)^{k-1}}{k^{s}}
$$

leads, via (3.2), to similar inequalities.

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Indeed, recalling that the Mellin transform [5] of a function $q$ is defined by

$$
Q(s)=\int_{0}^{\infty} q(x) x^{s-1} d x
$$

we see that the Mellin transform of any non-negative function satisfies an inequality of the type (3.2). In fact, (4.1) and (4.3) are examples of this.

### 4.4. The Zeta function (ii)

We conclude by presenting a family of inequalities in which the Zeta function appears alone, in contrast with (4.3).

With $a>1$ define the non-decreasing function $w_{N} \in[0,1]$ as follows:

$$
\begin{aligned}
w_{N}(x) & =0 \quad\left(0 \leq x<\frac{1}{N}\right) \\
& =\sum_{k=m}^{\infty} \frac{1}{k^{a}} \quad\left(\frac{1}{m} \leq x<\frac{1}{m-1}\right), \quad m=N, N-1, \ldots, 2 \\
& =\sum_{k=1}^{\infty} \frac{1}{k^{a}} \quad(x=1)
\end{aligned}
$$

Then we have

$$
\begin{equation*}
\int_{0}^{1} x^{s} d w_{N}(x)=\sum_{k=1}^{N-1} \frac{1}{k^{s+a}}+\frac{1}{N^{s}} \sum_{k=N}^{\infty} \frac{1}{k^{a}} \tag{4.4}
\end{equation*}
$$



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and we note that

$$
\begin{equation*}
\sum_{k=N}^{\infty} \frac{1}{k^{a}}<\frac{1}{a-1} \cdot \frac{1}{N^{a-1}} \tag{4.5}
\end{equation*}
$$

## Writing

$$
V_{N}(s)=\int_{0}^{1} x^{s} d w_{N}(x) \quad\left(\equiv \int_{\frac{1}{N}}^{1} x^{s} d w_{N}(x)\right)
$$

and defining $L$ on $C[0,1]^{1}$ by

$$
L(v)=\int_{0}^{1} v(x) d w_{N}(x)
$$

then (3.2) gives the inequalities

$$
\begin{equation*}
\frac{\left[V_{N}(\delta)\right]^{\alpha}}{V_{N}(\alpha \delta)} \gtrless \frac{\left[V_{N}(\beta)\right]^{\alpha}}{V_{N}(\alpha \beta)} . \tag{4.6}
\end{equation*}
$$

But, from (4.4) and (4.5), letting $N \rightarrow \infty$ shows that $V_{N}(s) \rightarrow \zeta(s+a)$ provided that $a>1$ and $s>0$ and so (4.6) gives the Zeta function inequality:

$$
\begin{equation*}
\frac{[\zeta(a+\delta)]^{\alpha}}{\zeta(a+\alpha \delta)} \gtrless \frac{[\zeta(a+\beta)]^{\alpha}}{\zeta(a+\alpha \beta)} \tag{4.7}
\end{equation*}
$$

provided $a>1, \alpha \beta>0$ and $\alpha \delta>0$.
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[^1]Finally, since the $\zeta(s)$ is known to be continuous for $s>1$ we can now let $a \rightarrow 1$ in (4.7) provided that we keep $\alpha>0$ when we get

$$
\begin{equation*}
\frac{[\zeta(1+\delta)]^{\alpha}}{\zeta(1+\alpha \delta)} \gtrless \frac{[\zeta(1+\beta)]^{\alpha}}{\zeta(1+\alpha \beta)} \tag{4.8}
\end{equation*}
$$

in which $\beta>\delta>0$ and $\alpha>0$. Regarding the directions of the inequalities here, we note that the option $\alpha \leq 0$ does not arise.


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[^1]:    ${ }^{1}$ Not a subspace of $C(0,1)$ but the theorem is true in this context also.

