Research Article

Variational Homotopy Perturbation Method for Solving Higher Dimensional Initial Boundary Value Problems

Muhammad Aslam Noor and Syed Tauseef Mohyud-Din

Department of Mathematics, COMSATS Institute of Information Technology, Islamabad 44000, Pakistan

Correspondence should be addressed to Muhammad Aslam Noor, n[oormaslam@hotmail.com](mailto:noormaslam@hotmail.com)

Received 14 January 2008; Revised 28 March 2008; Accepted 28 May 2008

Recommended by David Chelidze

We suggest and analyze a technique by combining the variational iteration method and the homotopy perturbation method. This method is called the variational homotopy perturbation method (VHPM). We use this method for solving higher dimensional initial boundary value problems with variable coefficients. The developed algorithm is quite efficient and is practically well suited for use in these problems. The proposed scheme finds the solution without any discritization, transformation, or restrictive assumptions and avoids the round-off errors. Several examples are given to check the reliability and efficiency of the proposed technique.

Copyright q 2008 M. A. Noor and S. T. Mohyud-Din. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

1. Introduction

The numerical and analytical solutions of higher dimensional initial boundary value problems of variable coefficients, linear and nonlinear, are of considerable significance for applied sciences. Examples of linear models are Euler-Darboux equation [1], Lambropoubs' equation [2] and Tricomi equation [3] given by

$$
(x - y)u_{xy} + (\alpha u_x - \beta u_y) = 0,
$$

\n
$$
u_{xy} + \alpha x u_x + b y u_y + c x y u + u_t = 0,
$$

\n
$$
u_{yy} = y u_{xx},
$$
\n(1.1)

respectively. Examples of nonlinear models are introduced in Kdv equation [4–7] of variable coefficients and Clairaut's equation [5] given by

$$
u_t + \alpha t^n u u_x + \beta t^m u_{xxx} = 0, \quad u = x u_x + y u_y + f(u_x, u_y), \tag{1.2}
$$

respectively; see [1–7]. Several [n](#page-9-1)[um](#page-9-2)erical and analytical techniques including the spectral methods, characteristics method, and Adomian's decomposition method have been developed for solving th[e](#page-9-3)se problems; see $[1–7]$ and the references therein. For implementation of the Adomian decomposition method, one has to find the so-called the Adomian polynomial, which is itself a difficult problem. To overcome these difficulties and drawbacks, He $[8-18]$ developed variational iteration method for solving linear and nonlinear problems, which arise in various branches of pure and applied sciences. It is worth me[ntion](#page-10-0)ing that the origin of variational iteration method can be traced back to Inokuti et al. [19]. [It](#page-9-3) [has](#page-10-1) been shown that the variational iteration method is user friendly. Furthermore, He [8-14] also introduced the homotopy perturbation method, which is developed by combining the standard homotopy and perturbation met[ho](#page-9-3)d. In these metho[ds](#page-10-2) the solution is given in an infinite series us[uall](#page-10-3)y converging to an accurate solution, see $[8-31]$. We would like to mention that Noor $[32]$ used the homotopy perturbation method for suggesting a number of iterative methods solving nonlinear equations of the type $f(x) = 0$. This is another application of the homotopy perturbation method.

Motivated and inspired by the on-going research in these areas, we consider a new method, which is called the variational homotopy perturbation method (VHPM). This method is suggested by combining the variational iteration technique and the homotopy perturbation method. The suggested VHPM provides the solution in a rapid convergent series which may lead the solution in a closed form and is in full agreement with $[7]$ [, w](#page-9-2)here similar problems were solved by using the decomposition method. The fact that the proposed technique solves nonlinear problems without using the so-called Adomian's polynomials is a clear advantage of this algorithm over the decomposition method. In this algorithm, the correct functional is developed $[8, 15-19, 21-25]$ and the Lagrange multipliers are calculated optimally via variational [th](#page-9-3)[eory](#page-10-4)[. Fin](#page-10-0)[ally](#page-10-5), [the](#page-10-6) homotopy perturbation is implemented on the correct functional and the comparison of like powers of *p* gives solutions of various orders. The developed algorithm takes full advantage of variational iteration and the homotopy perturbation methods. It is worth mentioning that the VHPM is applied without any discretization, restrictive assumption, or transformation and is free from round-off errors. Unlike the method of separation of variables that require initial and boundary conditions, the VHPM provides an analytical solution by using the initial conditions only. The boundary conditions can be used only to justify the obtained result. The proposed method work efficiently and the results so far are very encouraging and reliable. We would like to emphasize that the VHPM may be considered as an important and significant refinement of the previously developed techniques and can be viewed as an alternative to the recently developed methods such as Adomian's decomposition, variational iterations, and homotopy perturbation methods. Several examples are given to verify the reliability and efficiency of the variational homotopy perturbation method (VHPM).

2. Variational iteration method

To illustrate the basic concept of the technique, we consider the following general differential equation:

$$
Lu + Nu = g(x), \tag{2.1}
$$

where L is a linear operator, N a nonlinear operator, and $g(x)$ the forcing term. According to variational iteration method $[8, 15-19, 21-25]$, we can construct a correct functional as follows:

$$
u_{n+1}(x) = u_n(x) + \int_0^x \lambda \big(Lu_n(s) + N\tilde{u}_n(s) - g(s)\big)ds,
$$
\n(2.2)

where λ is a Lagrange multiplier [8, 15–19], which can be identified optimally via a variational iteration method. The subscripts *n* [deno](#page-2-0)te the *n*th approximation, \tilde{u}_n is considered as a restricted variation. That is, $\delta \tilde{u}_n = 0$; (2.2) is called a correct functional. The solution of the linear problems can be solved in a single iteration can due to the exact identification of the linear problems can be solved in a single iteration step due to the exact identification of the Lagrange multiplier. The principles of the variation[al](#page-9-3) i[tera](#page-10-4)[tion](#page-10-0) method and its applicability for various kinds of differential equations are given in 8, 15–19. In this method, it is required first to determine the Lagrange multiplier λ optimally. The successive approximation u_{n+1} , $n \geq 0$ of the solution *u* will be readily obtained upon using the determined Lagrange multiplier and any selective function u_0 , consequently, the solution is given by $u = \lim u_n$.

3. Homotopy perturbation method

To explain the homotopy perturbation method, we consider a general equation of the type,

$$
L(u) = 0,\t\t(3.1)
$$

where L is any integral or differential operator. We define a convex homotopy $H(u, p)$ by

$$
H(u,p) = (1-p)F(u) + pL(u),
$$
\n(3.2)

where $F(u)$ is a functional operator with known solutions v_0 , which can be obtained easily. It is clear that, for

$$
H(u,p) = 0,\t(3.3)
$$

we have

$$
H(u,0) = F(u), \qquad H(u,1) = L(u). \tag{3.4}
$$

This shows that $H(u, p)$ continuously traces an implicitly defined curve from a starting point $H(v_0, 0)$ to a solution function $H(f, 1)$. The embedding parameter monotonically increases from zero to unit as the trivial problem $F(u) = 0$ is continuously deforms the original problem $L(u) = 0$. The embedding parameter $p \in (0,1]$ can be considered as an expanding parameter $[8-14, 26-31]$. The homotopy perturbation method uses the homotopy parameter p as an expanding parameter $[8-14]$ to obtain

$$
u = \sum_{i=0}^{\infty} p^i u_i = u_0 + p u_1 + p^2 u_2 + p^3 u_3 + \cdots
$$
 (3.5)

If $p\rightarrow 1$, then (3.5) corresponds to (3.2) and becomes the approximate solution of the form

$$
f = \lim_{p \to 1} u = \sum_{i=0}^{\infty} u_i.
$$
 (3.6)

It is well known that series (3.5) is convergent for most of the cases and also the rate of convergence is dependent on $L(u)$; see $[8-14]$. We assume that (3.6) has a unique solution. The comparisons of like powers of *p* give solutions of various orders.

4. Variational homotopy perturbation method (VHPM)

To convey the basic idea of the variational homotopy perturbation method, we consider the following general differential equation:

$$
Lu + Nu = g(x), \tag{4.1}
$$

where *L* is a linear operato[r,](#page-9-3) *[N](#page-10-4)* a [non](#page-10-0)linear operator, and $g(x)$ the forcing term. According to variational iteration method $[8, 15-19]$, we can construct a correct functional as follows:

$$
u_{n+1}(x) = u_n(x) + \int_0^x \lambda(\xi) (Lu_n(\xi) + N\tilde{u}_n(\xi) - g(\xi)) d\xi,
$$
 (4.2)

where λ is a Lagrange multiplier [8, [15](#page-10-4)[–19](#page-10-0)], which can be identified optimally via variational iteration method. The subscripts *n* denote the *n*th approximation, \tilde{u}_n is considered as a restricted variation. That is, $\delta \tilde{u}_n = 0$; ([4.2](#page-3-0)) is called as a correct functional. Now, we apply the homotony perturbation method the homotopy perturbation method,

$$
\sum_{n=0}^{\infty} p^{(n)} u_n = u_0(x) + p \int_0^x \lambda(\xi) \left(\sum_{n=0}^{\infty} p^{(n)} L(u_n) + \sum_{n=0}^{\infty} p^{(n)} N(\tilde{u}_n) \right) d\xi - \int_0^x \lambda(\xi) g(\xi) d\xi, \tag{4.3}
$$

which is the variational homotopy perturbation method and is formulated by the coupling of variational iteration method and Adomian's polynomials. A comparison of like powers of *p* gives solutions of various orders.

5. Numerical applications

In this section, we apply the VHPM developed in Section 4 for solving higher dimensional initial boundary value problems with variable coeffi[cient. We](#page-3-1) develop the correct functional and calculate the Lagrange multipliers optimally via variational theory. The homotopy perturbation method is implemented on the correct functional and finally, the comparison of like powers of *p* gives solutions of various orders. Numerical results reveal that the VHPM is easy to implement and reduces the computational work to a tangible level while still maintaining a very higher level of accuracy. For the sake of comparison, we take the same examples as used in [7, 20].

Example 5.1. Cons[id](#page-9-2)[er th](#page-10-7)e two-dimensional initial boundary value problem:

$$
u_{tt} = \frac{1}{2}y^2 u_{xx} + \frac{1}{2}x^2 u_{yy}, \quad 0 < x, \, y < 1, \, t > 0,\tag{5.1}
$$

with boundary conditions

$$
u(0, y, t) = y2e-t, \t u(1, y, t) = (1 + y2)e-t,u(x, 0, t) = y2e-t, \t u(x, 1, t) = (1 + x2)e-t, \t (5.2)
$$

and the initial conditions

$$
u(x, y, 0) = x2 + y2, \qquad ut(x, y, 0) = -(x2 + y2).
$$
 (5.3)

The correct functional is given as

$$
u_{n+1}(x, y, z, t) = (x^2 + y^2) - (x^2 + y^2)t + \int_0^t \lambda(\xi) \left(\frac{\partial^2 u_n}{\partial t^2} - \frac{1}{2} \left(y^2 (\tilde{u}_n)_{xx} + x^2 (\tilde{u}_n)_{yy} \right) \right) d\xi, \quad (5.4)
$$

where \tilde{u}_n is considered as a restricted variation. Making the above functional stationary, the Lagrange multiplier can be determined as $\lambda = \xi - t$, which yields the following iteration formula:

$$
u_{n+1}(x,y,z,t) = (x^2 + y^2) - (x^2 + y^2)t + \int_0^t (\xi - t) \left(\frac{\partial^2 u_n}{\partial t^2} - \frac{1}{2} \left(y^2 (u_n)_{xx} + x^2 (u_n)_{yy} \right) \right) d\xi. \tag{5.5}
$$

Applying the variational homotopy perturbation method, we have

$$
u_0 + pu_1 + p^2 u_2 + \dots = (x^2 + y^2) - (x^2 + y^2)t + p \int_0^t (\xi - t) \left(\frac{\partial^2 u_0}{\partial t^2} + p \frac{\partial^2 u_1}{\partial t^2} + p^2 \frac{\partial^2 u_2}{\partial t^2} + \dots \right) d\xi
$$

$$
- \frac{1}{2} p \int_0^t (\xi - t) \left(\left(y^2 \left(\frac{\partial^2 \tilde{u}_0}{\partial x^2} + p \frac{\partial^2 \tilde{u}_1}{\partial x^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial x^2} + \dots \right) \right) + \left(x^2 \left(\frac{\partial^2 \tilde{u}_0}{\partial y^2} + p \frac{\partial^2 \tilde{u}_1}{\partial y^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial y^2} + \dots \right) \right) \right) d\xi.
$$

(5.6)

Comparing the coefficient of like powers of *p,* we have

$$
p^{(0)}: u_0(x, y, t) = (x^2 + y^2) - (x^2 + y^2)t,
$$

\n
$$
p^{(1)}: u_1(x, y, t) = (x^2 + y^2)\frac{t^2}{2!} - (x^2 + y^2)\frac{t^3}{3!},
$$

\n
$$
p^{(2)}: u_2(x, y, t) = (x^2 + y^2)\frac{t^4}{4!} - (x^2 + y^2)\frac{t^5}{5!},
$$

\n
$$
p^{(3)}: u_3(x, y, t) = (x^2 + y^2)\frac{t^5}{5!} - (x^2 + y^2)\frac{t^7}{7!},
$$

\n
$$
p^{(4)}: u_4(x, y, t) = (x^2 + y^2)\frac{t^8}{8!} - (x^2 + y^2)\frac{t^9}{9!},
$$

\n
$$
p^{(5)}: u_5(x, y, t) = (x^2 + y^2)\frac{t^{10}}{10!} - (x^2 + y^2)\frac{t^{11}}{11!},
$$

\n
$$
\vdots
$$

The series solution is given by

$$
u(x,y,t) = (x^2 + y^2) \left(1 - t + \frac{t^2}{2!} - \frac{t^3}{3!} + \frac{t^4}{4!} - \frac{t^5}{5!} + \frac{t^6}{6!} - \frac{t^7}{7!} + \frac{t^8}{8!} - \cdots \right),
$$
(5.8)

and in a closed form by $u(x, y, t) = (x^2 + y^2)e^{-t}$, which is in full agreement with [7].

Example 5.2. Consider the three-dimensional initial boundary value problem

$$
u_{tt} = \frac{1}{45}x^2u_{xx} + \frac{1}{45}y^2u_{yy} + \frac{1}{45}z^2u_{zz} - u, \quad 0 < x, \, y < 1, \, t < 0 \tag{5.9}
$$

subject to the Neumann boundary conditions

$$
u_x(0, y, z, t) = 0, \t u_x(1, y, z, t) = 6y^6 z^6 \sinh t, \t u_y(x, 0, z, t) = 0,
$$

$$
u_y(x, 1, z, t) = 6x^6 z^6 \sinh t, \t u_z(x, y, 0, t) = 0, \t u_z(x, y, 1, t) = 6x^6 y^6 \sinh t,
$$
 (5.10)

and the initial conditions

$$
u(x, y, z, 0) = 0, \qquad u_t(x, y, z, 0) = x^6 y^6 z^6. \tag{5.11}
$$

The correct functional is given by

$$
u_{n+1}(x,y,z,t) = (x^6 y^6 z^6) t + \int_0^t \lambda(\xi) \left(\frac{\partial^2 u_n}{\partial t^2} - \frac{1}{45} \left(x^2 (\tilde{u}_n)_{xx} + y^2 (\tilde{u}_n)_{yy} + z^2 (\tilde{u}_n)_{zz} \right) + \tilde{u}_n \right) d\xi,
$$
\n(5.12)

where \tilde{u}_n is considered as a restricted variation. Making the above functional stationary, the Lagrange multiplier can be determined as $\lambda = \xi - t$, which yields the following iteration formula:

$$
u_{n+1}(x,y,z,t) = (x^6 y^6 z^6) t + \int_0^t (\xi - t) \left(\frac{\partial^2 u_n}{\partial t^2} - \frac{1}{45} \left(x^2 (u_n)_{xx} + y^2 (u_n)_{yy} + z^2 (u_n)_{zz} \right) + u_n \right) d\xi.
$$
\n(5.13)

Applying the variational homotopy perturbation method,

$$
u_0 + pu_1 + p^2 u_2 + \dots = (x^2 + y^2) - (x^2 + y^2)t + p \int_0^t (\xi - t) \left(\frac{\partial^2 u_0}{\partial t^2} + p \frac{\partial^2 u_1}{\partial t^2} + p^2 \frac{\partial^2 u_2}{\partial t^2} + \dots \right) d\xi
$$

$$
- \frac{1}{45} p \int_0^t (\xi - t) \left(\left(x^2 \left(\frac{\partial^2 \tilde{u}_0}{\partial x^2} + p \frac{\partial^2 \tilde{u}_1}{\partial x^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial x^2} + \dots \right) \right) + \left(y^2 \left(\frac{\partial^2 \tilde{u}_0}{\partial y^2} + p \frac{\partial^2 \tilde{u}_1}{\partial y^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial y^2} + \dots \right) \right) \right) d\xi
$$

$$
- \frac{1}{45} p \int_0^t (\xi - t) z^2 \left(\frac{\partial^2 \tilde{u}_0}{\partial z^2} + p \frac{\partial^2 \tilde{u}_1}{\partial z^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial z^2} + \dots \right) d\xi
$$

$$
+ p \int_0^t (\xi - t) (u_0 + pu_1 + p^2 u_2 + \dots) d\xi.
$$
 (5.14)

Comparing the coefficient of like powers of *p*, we have

$$
p^{(0)}: u_0(x, y, z, t) = x^6 y^6 z^6 t,
$$

\n
$$
p^{(1)}: u_1(x, y, z, t) = x^6 y^6 z^6 \frac{t^3}{3!},
$$

\n
$$
p^{(2)}: u_2(x, y, z, t) = x^6 y^6 z^6 \frac{t^5}{5!},
$$

\n
$$
p^{(3)}: u_3(x, y, z, t) = x^6 y^6 z^6 \frac{t^7}{7!},
$$

\n
$$
p^{(4)}: u_4(x, y, z, t) = x^6 y^6 z^6 \frac{t^9}{9!},
$$

\n
$$
\vdots
$$

The series solution is given by

$$
u(x, y, z, t) = x^{6} y^{6} z^{6} \left(t + \frac{t^{3}}{3!} + \frac{t^{5}}{5!} + \frac{t^{7}}{7!} + \frac{t^{9}}{9!} + \cdots \right) = x^{6} y^{6} z^{6} \sinh t,
$$
 (5.16)

w[h](#page-9-2)ich is in full agreement with [7].

Example 5.3. Consider the two-dimensional nonlinear inhomogeneous initial boundary value problem

$$
u_{tt} = 2x^2 + 2y^2 + \frac{15}{2}(xu_{xx}^2 + yu_{yy}^2), \quad 0 < x, \ y < 1, \ t > 0 \tag{5.17}
$$

with boundary conditions

$$
u(0, y, t) = y^{2}t^{2} + yt^{6}, \qquad u(1, y, t) = (1 + y^{2})t^{2} + (1 + y)t^{6},
$$

$$
u(x, 0, t) = x^{2}t^{2} + xt^{6}, \qquad u(x, 1, t) = (1 + x^{2})t^{2} + (1 + x)t^{6},
$$
 (5.18)

and the initial conditions

$$
u(x, y, 0) = 0, \qquad u_t(x, y, 0) = 0, \tag{5.19}
$$

The correct functional is given as

$$
u_{n+1}(x, y, z, t) = \int_0^t \lambda(\xi) \left(\frac{\partial^2 u_n}{\partial t^2} - \frac{15}{2} \left(x (\tilde{u}_n^2)_{xx} + y^2 (\tilde{u}_n^2)_{yy} \right) - 2(x^2 + y^2) \right) d\xi,
$$
(5.20)

where \tilde{u}_n is considered as a restricted variation. Making the above functional stationary, the Lagrange multiplier can be determined as $\lambda = \xi - t$, which yields the following iteration formula

$$
u_{n+1}(x,y,z,t) = \int_0^t (\xi - t) \left(\frac{\partial^2 u_n}{\partial t^2} - \frac{15}{2} \left(x (\tilde{u}_n^2)_{xx} + y^2 (\tilde{u}_n^2)_{yy} \right) - 2(x^2 + y^2) \right) d\xi. \tag{5.21}
$$

Applying the variational homotopy perturbation method, we have

$$
u_0 + pu_1 + p^2 u_2 + \dots = p \int_0^t (\xi - t) \left(\frac{\partial^2 u_0}{\partial t^2} + p \frac{\partial^2 u_1}{\partial t^2} + p^2 \frac{\partial^2 u_2}{\partial t^2} + \dots \right) d\xi
$$

$$
- \frac{15}{2} p(\xi - t) \left(x \left(\frac{\partial^2 \tilde{u}_0}{\partial x^2} + p \frac{\partial^2 \tilde{u}_1}{\partial x^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial x^2} + \dots \right)_{xx}^2 + \int_0^t y \left(\frac{\partial^2 \tilde{u}_0}{\partial y^2} + p \frac{\partial^2 \tilde{u}_1}{\partial y^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial y^2} + \dots \right)_{yy}^2 - 2(x^2 + y^2) \right) d\xi.
$$

(5.22)

Comparing the coefficient of like powers of *p*, we have

$$
p^{(0)}: u_0(x, y, t) = 0,
$$

\n
$$
p^{(1)}: u_1(x, y, t) = (x^2 + y^2)t^2,
$$

\n
$$
p^{(2)}: u_2(x, y, t) = (x + y)t^6,
$$

\n
$$
p^{(3)}: u_3(x, y, t) = 0,
$$

\n
$$
\vdots
$$
 (5.23)

The solution is obtained as $u(x, y, t) = (x^2 + y^2)t^2 + (x + y)t^6$, which is in full agreement with $[7]$.

Example 5.4. Consider the three-dimensional nonlinear initial boundary value problem

$$
u_{tt} = (2 - t^2) + u - (e^{-x} u_{xx}^2 + e^{-y} u_{yy}^2 + e^{-z} u_{zz}^2), \quad 0 < x, \, y < 1, \, t < 0 \tag{5.24}
$$

subject to the Neumann boundary conditions

$$
u_x(0, y, z, t) = 1, \t u_x(1, y, z, t) = e,u_y(x, 0, z, t) = 0, \t u_y(x, 1, z, t) = e,u_z(x, y, 0, t) = 1, \t u_z(x, y, 1, t) = e,
$$
\t(5.25)

and the initial conditions

$$
u(x, y, z, 0) = e^x + e^y + e^z, \qquad u_t(x, y, z, 0) = 0.
$$
 (5.26)

The correct functional is given as

$$
u_{n+1}(x,y,z,t)
$$

= $(e^x + e^y + e^z) + \int_0^t \lambda(\xi) \left(\frac{\partial^2 u_n}{\partial t^2} + \left(e^{-x} (\tilde{u}_n)_{xx}^2 + e^{-y} (\tilde{u}_n)_{yy}^2 + e^{-z} (\tilde{u}_n)_{zz}^2 \right) - \tilde{u}_n \right) d\xi - \int_0^t \lambda(\xi) (2 - t^2) d\xi,$ (5.27)

where \tilde{u}_n is considered as a restricted variation. Making the above functional stationary, the Lagrange multiplier can be determined as $\lambda = \xi - t$, which yields the following iteration formula:

$$
u_{n+1}(x, y, z, t)
$$

= $(e^x + e^y + e^z) + \int_0^t (\xi - t) \left(\frac{\partial^2 u_n}{\partial t^2} + \left(e^{-x} (\tilde{u}_n)_{xx}^2 + e^{-y} (\tilde{u}_n)_{yy}^2 + e^{-z} (\tilde{u}_n)_{zz}^2 \right) - \tilde{u}_n \right) d\xi - \int_0^t \lambda(\xi) (2 - t^2) d\xi,$ (5.28)

Applying the variational homotopy perturbation method, we have

$$
u_0 + pu_1 + \dots = (e^x + e^y + e^z) + p \int_0^t (\xi - t) \left(\left(\frac{\partial^2 u_0}{\partial t^2} + p \frac{\partial^2 u_1}{\partial t^2} + p^2 \frac{\partial^2 u_2}{\partial t^2} + \dots \right) \right. \\
\left. + e^{-x} \left(\frac{\partial^2 \tilde{u}_0}{\partial x^2} + p \frac{\partial^2 \tilde{u}_1}{\partial x^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial x^2} + \dots \right)_{xx}^2 \right) d\xi
$$
\n
$$
+ p \int_0^t (\xi - t) \left(e^{-y} \left(\frac{\partial^2 \tilde{u}_0}{\partial y^2} + p \frac{\partial^2 \tilde{u}_1}{\partial y^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial y^2} + \dots \right)_{xx}^2 \right. \\
\left. + \int_0^t e^{-z} \left(\frac{\partial^2 \tilde{u}_0}{\partial z^2} + p \frac{\partial^2 \tilde{u}_1}{\partial z^2} + p^2 \frac{\partial^2 \tilde{u}_2}{\partial z^2} + \dots \right)_{yy}^2 \right) d\xi
$$
\n
$$
- p \int_0^t (\xi - t) \left((u_0 + pu_1 + p^2 u_2 + \dots) + (2 - t^2) \right) d\xi.
$$
\n(5.29)

Comparing the coefficient of like powers of *p*, we have

$$
p^{(0)}: u_0(x, y, z, t) = (e^x + e^y + e^z) + t^2 - \frac{t^4}{12},
$$

\n
$$
p^{(1)}: u_1(x, y, z, t) = \frac{t^4}{12} - \frac{t^6}{360},
$$

\n
$$
p^{(2)}: u_2(x, y, z, t) = \frac{t^6}{360} - \frac{t^8}{20160},
$$

\n
$$
\vdots
$$
\n(5.30)

The solution is obtained as $u(x, y, z, t) = (e^x + e^y + e^z) + t^2$, which is in full agreement with [7].

Remark 5.5. We would like to point out that Noor [[32](#page-10-3)] used the homotopy perturbation method for suggesting some iterative-type methods for solving nonlinear equations $f(x) = 0$ coupled with system of equations. Also it has been shown [32] that the homotopy perturbation method and Adomian decomposition method are equivalent. This application of the homotopy method is quite different in nature. It is an interesting problem to consider such type of applications of the variational homotopy method in solving nonlinear equations.

6. Conclusions

In this paper, we develop the variational homotopy perturbation method (VHPM) for solving nonlinear problems. We used the variational homotopy perturbation method for solving the higher dimensional initial boundary value problems with variable coefficient. The proposed method is successfully implemented by using the initial conditions only. There are two important points to make here. First, unlike the implicit and explicit finite difference methods, the solution here is given in a closed form and by using the initial conditions only. Second, the VHPM avoids the cumbersome of the computational methods while still maintaining the higher level of accuracy. The fact that the variational homotopy perturbation method solves nonlinear problems without using the Adomian's polynomials can be considered as a clear advantage of this technique over the decomposition method. It is observed that the proposed scheme exploits full advantage of variational iteration method and the homotopy perturbation method. Finally, we conclude that the VHPM may be considered as a nice refinement in existing numerical techniques.

Acknowledgments

The authors are highly grateful to a referee for his/her constructive comments. They would like to thank Dr. S. M. Junaid Zaidi, Rector CIIT for providing excellent research environment and facilities.

References

- 1 W. Miller Jr., "Symmetries of differential equations. The hypergeometric and Euler-Darboux equations," *SIAM Journal on Mathematical Analysis*, vol. 4, no. 2, pp. 314–328, 1973.
- [2] R. Wilcox, "Closed-form solution of the differential equation $((\partial^2/\partial x \partial y) + ax(\partial/\partial x) + by(\partial/\partial y) + a$ *cxy* + (∂/∂*t*))P = 0 by normal-ordering exponential operators," *Journal of Mathematical Physics*, vol. 11, pp. 1235–1237, 1970.
- 3 A. R. Manwell, *The Tricomi Equation with Applications to the Theory of Plane Transonic Flow*, vol. 35 of *Research Notes in Mathematics*, Pitman, London, UK, 1979.
- [4] N. Nirmala, M. J. Vedan, and B. V. Baby, "A variable coefficient Korteweg-de Vries equation: similarity analysis and exact solution—II," *Journal of Mathematical Physics*, vol. 27, no. 11, pp. 2644–2646, 1986.
- 5 S. Iyanaga and Y. Kawada, *Encyclopedic Dictionary of Mathematics*, MIT Press, Cambridge, Mass, USA, 1962.
- 6 A. A. Soliman, "A numerical simulation and explicit solutions of KdV-Burgers' and Lax's seventhorder KdV equations," *Chaos, Solitons & Fractals*, vol. 29, no. 2, pp. 294–302, 2006.
- 7 A.-M. Wazwaz, "The decomposition method for solving higher dimensional initial boundary value problems of variable coefficients," *International Journal of Computer Mathematics*, vol. 76, no. 2, pp. 159– 172, 2000.
- 8 J.-H. He, "Some asymptotic methods for strongly nonlinear equations," *International Journal of Modern Physics B*, vol. 20, no. 10, pp. 1141–1199, 2006.

- 9 J.-H. He, "Homotopy perturbation technique," *Computer Methods in Applied Mechanics and Engineering*, vol. 178, no. 3-4, pp. 257–262, 1999.
- 10 J.-H. He, "Homotopy perturbation method for solving boundary value problems," *Physics Letters A*, vol. 350, no. 1-2, pp. 87–88, 2006.
- 11 J.-H. He, "Comparison of homotopy perturbation method and homotopy analysis method," *Applied Mathematics and Computation*, vol. 156, no. 2, pp. 527–539, 2004.
- 12 J.-H. He, "Homotopy perturbation method for bifurcation of nonlinear problems," *International Journal of Nonlinear Sciences and Numerical Simulation*, vol. 6, no. 2, pp. 207–208, 2005.
- 13 J.-H. He, "The homotopy perturbation method nonlinear oscillators with discontinuities," *Applied Mathematics and Computation*, vol. 151, no. 1, pp. 287–292, 2004.
- 14 J.-H. He, "A coupling method of a homotopy technique and a perturbation technique for non-linear problems," *International Journal of Non-Linear Mechanics*, vol. 35, no. 1, pp. 37–43, 2000.
- [15] J.-H. He, "Variational iteration method—a kind of non-linear analytical technique: some examples," *International Journal of Non-Linear Mechanics*, vol. 34, no. 4, pp. 699–708, 1999.
- 16 J.-H. He, "Variational iteration method for autonomous ordinary differential systems," *Applied Mathematics and Computation*, vol. 114, no. 2-3, pp. 115–123, 2000.
- 17 J.-H. He and X.-H. Wu, "Construction of solitary solution and compacton-like solution by variational iteration method," *Chaos, Solitons & Fractals*, vol. 29, no. 1, pp. 108–113, 2006.
- 18 J.-H. He and X.-H. Wu, "Variational iteration method: new development and applications," *Computers & Mathematics with Applications*, vol. 54, no. 7-8, pp. 881–894, 2007.
- 19 M. Inokuti, H. Sekine, and T. Mura, "General use of the Lagrange multiplier in nonlinear mathematical physics," in *Variational Method in the Mechanics of Solids*, S. Nemat-Naseer, Ed., pp. 156–162, Pergamon Press, New York, NY, USA, 1978.
- 20 M. A. Noor and S. T. Mohyud-Din, "Variational iteration decomposition method for solving higher dimensional initial boundary value problems with variable coefficients," preprint, 2007.
- 21 S. T. Mohyud-Din, "A reliable algorithm for Blasius equation," in *Proceedings of the International Conference of Mathematical Sciences (ICMS '07)*, pp. 616–626, Selangor, Malaysia, November 2007.
- 22 M. A. Noor and S. T. Mohyud-Din, "Variational iteration technique for solving higher order boundary value problems," *Applied Mathematics and Computation*, vol. 189, no. 2, pp. 1929–1942, 2007.
- [23] M. A. Noor and S. T. Mohyud-Din, "An efficient method for fourth-order boundary value propblems," *Computers & Mathematics with Applications*, vol. 54, no. 7-8, pp. 1101–1111, 2007.
- [24] M. A. Noor and S. T. Mohyud-Din, "Variational iteration technique for solving higher order boundary value problems," *Applied Mathematics and Computation*, vol. 189, no. 2, pp. 1929–1942, 2007.
- [25] M. A. Noor and S. T. Mohyud-Din, "Variational iteration decomposition method for solving eighthorder boundary value problems," *Differential Equations and Nonlinear Mechanics*, vol. 2007, Article ID 19529, 16 pages, 2007.
- [26] S. T. Mohyud-Din and M. A. Noor, "Homotopy perturbation method for solving fourth order boundary value problems," *Mathematical Problems in Engineering*, vol. 2006, Article ID 98602, 15 pages, 2006.
- 27 M. A. Noor and S. T. Mohyud-Din, "Homotopy method for solving eighth order boundary value problems," *Journal of Mathematical Analysis and Approximation Theory*, vol. 1, no. 2, pp. 161–169, 2006.
- [28] M. A. Noor and S. T. Mohyud-Din, "An efficient algorithm for solving fifth-order boundary value problems," *Mathematical and Computer Modelling*, vol. 45, no. 7-8, pp. 954–964, 2007.
- [29] M. A. Noor and S. T. Mohyud-Din, "Homotopy perturbation method for solving sixth-order boundary value problems," *Computers & Mathematics with Applications*, vol. 55, no. 12, pp. 2953–2972, 2008.
- [30] M. A. Noor and S. T. Mohyud-Din, "A reliable approach for solving linear and nonlinear sixth-order boundary value problems," *International Journal of Computational and Applied Mathematics*, vol. 2, no. 2, pp. 163–172, 2007.
- 31 M. A. Noor and S. T. Mohyud-Din, "Approximate solutions of Flieral-Petviashivili equation and its variants," *International Journal of Mathematics and Computer Science*, vol. 2, no. 4, pp. 345–360, 2007.
- [32] M. A. Noor, "On iterative methods for nonlinear equations using homotopy perturbation technique," preprint, 2008.

Special Issue on Space Dynamics

Call for Papers

Space dynamics is a very general title that can accommodate a long list of activities. This kind of research started with the study of the motion of the stars and the planets back to the origin of astronomy, and nowadays it has a large list of topics. It is possible to make a division in two main categories: astronomy and astrodynamics. By astronomy, we can relate topics that deal with the motion of the planets, natural satellites, comets, and so forth. Many important topics of research nowadays are related to those subjects. By astrodynamics, we mean topics related to spaceflight dynamics.

It means topics where a satellite, a rocket, or any kind of man-made object is travelling in space governed by the gravitational forces of celestial bodies and/or forces generated by propulsion systems that are available in those objects. Many topics are related to orbit determination, propagation, and orbital maneuvers related to those spacecrafts. Several other topics that are related to this subject are numerical methods, nonlinear dynamics, chaos, and control.

The main objective of this Special Issue is to publish topics that are under study in one of those lines. The idea is to get the most recent researches and published them in a very short time, so we can give a step in order to help scientists and engineers that work in this field to be aware of actual research. All the published papers have to be peer reviewed, but in a fast and accurate way so that the topics are not outdated by the large speed that the information flows nowadays.

Before submission authors should carefully read over the journal's Author Guidelines, which are located at [http://www](http://www.hindawi.com/journals/mpe/guidelines.html) [.hindawi.com/journals/mpe/guidelines.html.](http://www.hindawi.com/journals/mpe/guidelines.html) Prospective authors should submit an electronic copy of their complete manuscript through the journal Manuscript Tracking System at <http://mts.hindawi.com/> according to the following timetable:

Lead Guest Editor

Antonio F. Bertachini A. Prado, Instituto Nacional de Pesquisas Espaciais (INPE), São José dos Campos, 12227-010 São Paulo, Brazil; prado@dem.inpe.br

Guest Editors

Maria Cecilia Zanardi, São Paulo State University (UNESP), Guaratinguetá, 12516-410 São Paulo, Brazil; cecilia@feg.unesp.br

Tadashi Yokoyama, Universidade Estadual Paulista (UNESP), Rio Claro, 13506-900 São Paulo, Brazil; tadashi@rc.unesp.br

Silvia Maria Giuliatti Winter, São Paulo State University (UNESP), Guaratinguetá, 12516-410 São Paulo, Brazil; silvia@feg.unesp.br